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MCDONNELL DOUGLAS TECHNICAL SERVICES CO. HOUSTON ASTRONAUTICS DIVISION

SPACE SHUTTLE ENGINEERING AND OPERATIONS SUPPORT

DESIGN NOTE NO. 1.4-4-8

ORBITER ENTRY TRAJECTORY CORRIDORS -32,000 POUND PAYLOAD, 67.5% CENTER OF GRAVITY

MISSION PLANNING, MISSION ANALYSIS AND SOFTWARE FORMULATION

9 JULY 1975

This Design Note is Submitted to NASA Under Task Order No. D0303, Task Assignment 1.4-4-A in Fulfillment of Contract NAS 9-13970.

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1.0 SUMMARY

This design note presents plots of Orbiter thermal and equilibrium glide boundaries in the drag/mass-relative velocity (D/M-V), dynamic pressure-relative velocity $(\overline{q}$ -V), and altitude-relative velocity (h-V) planes for an Orbiter having a 32,000 pound payload and a 67.5% center of gravity (cg) location. These boundaries were defined for control points 1 through 4 of the Shuttle Orbiter for 40° - 30° and 38° - 28° ramped angle of attack entry profiles and 40° , 38° , 35° , 30° , 28° , and 25° constant angle of attack entry profiles each at 20° , 15° , and 10° constant body flap settings.

2.0 INTRODUCTION

Thermal and equilibrium glide boundaries are used to analyze and/or design Shuttle Orbiter entry trajectories. The boundaries presented in this note were used by the Flight Performance Branch (FPB) of the NASA for trajectory profile shaping of entry trajectories corresponding to a vehicle weight of 193,000 pounds (32,000 pound payload) and a 67.5% cg location. These conditions are consistent with a 28.5° inclination Eastern Test Range (ETR) mission and were used by the FPB to evaluate an ETR mission in support of Thermal Protection System (TPS) design.

3.0 DISCUSSION

Plots of thermal and equilibrium glide boundaries in the D/M-V (Figures 2-49), \overline{q} -V (Figures 50-97), and h-V (Figures 98-145) planes are presented for the 40°-30° and 38°-28° ramped angle of attack profiles and the 40°, 38°, 35°, 30°, 28°, and 25° constant angle of attack profiles each at 20°, 15°, and 10° constant body flap settings. The 40°-30° and 38°-28° ramped angle of attack profiles are presented in Figure 1.

The data presented in the note were generated using the Thermal Boundary Analysis Program (TBAP) (Reference 1) which uses simplified heating models in defining thermal boundaries. Revisions to TBAP for this study include a more sophisticated method in determining the normal shock viscosity coefficient (Reference 2), updates to the transition criteria on control point 2 by representing the normal shock Reynold's number as a function of angle of attack and body flap deflection angle (Reference 3), and updated transition criteria for control point 4 (Reference 4).

The equilibrium glide boundaries were generated using a digital program to solve the equilibrium glide equation:

$$D/M = \frac{g}{\frac{L}{D}\cos\phi} \left(1 - \frac{V_I^2}{V_{sat}^2}\right)$$
 (3-1)

D = drag force (1bs)

M = mass (slugs)

V_I = inertial velocity (ft/sec)

g = gravitational acceleration (ft/sec²)

L/D = lift-to-drag ratio (-)

 ϕ = roll angle

V_{sat} = sattelite velocity (ft/sec)

It should be noted, in equation (3-1), that data for the equilibrium glide boundaries in the D/M-V planes were calculated as a function of inertial velocity (V_I) but were plotted versus relative velocity (V_I) as though $V = V_I$. Therefore, for the data to be meaningful, a transformation from inertial to relative velocity must be applied. In the D/M-V plane this can be done by shifting the data by the difference in the inertial and relative velocities for the trajectory of interest. An approximate transformation is

$$V = V_{T} - \omega R \cos i \qquad (3-2)$$

where

 ω = earth rotation rate (radians/sec)

R = earth radius (ft)

and i = orbit inclination (radians).

Equation (3-2) is least accurate for polar orbits, exhibiting a maximum error of about 45 ft/sec. On the D/M-V boundary figures

presented in this note a 45 ft/sec. error is negligible. Hence, equation (3-2) can be used to adjust the equilibrium glide boundaries to account for orbit inclination.

The equilibrium glide boundaries in the \overline{q} -V and h-V planes can be determined from the drag equation:

$$D/M = \frac{\rho V^2 C_D S}{2M}$$
 (3-3)

where D/M is determined from equation 3-2 and

 C_{D} = aerodynamic drag coefficient (-)

S = reference area (ft²)

 ρ = free stream density (slug/ft³)

that is

$$\overline{q} = \frac{1}{2} \rho V^2 = \left(\frac{D}{M}\right) \frac{M}{C_D S}$$
 (3-4)

and $h = function of \rho$

where
$$\rho = \left(\frac{D}{M}\right) \frac{2M}{v^2 c_n s}$$
 (3-5)

The solution of (3-4) and (3-5) requires an iteration on altitude since C_D is a function of altitude through the Mach number and since h is not easily represented as a direct function of ρ for the 1962 standard atmosphere.

The data for the equilibrium glide boundaries in the \overline{q} -V and h-V planes are accurate only for 90° orbit inclinations (i.e. orbits for which V \approx V $_{\rm I}$). Unlike the equilibrium glide boundaries in the D/M-V plane, a simple "shifting" of the boundaries in the \overline{q} -V and h-V planes is not possible. Determination of the boundaries in these planes requires independent generation of the data for each orbit inclination of interest. Note, however, that the analytic drag control entry guidance software operates in the D/M-V plane and the data presented in that plane can be adjusted for orbit inclination thus providing all the information required for profile shaping for any orbit inclination.

4.0 REFERENCES

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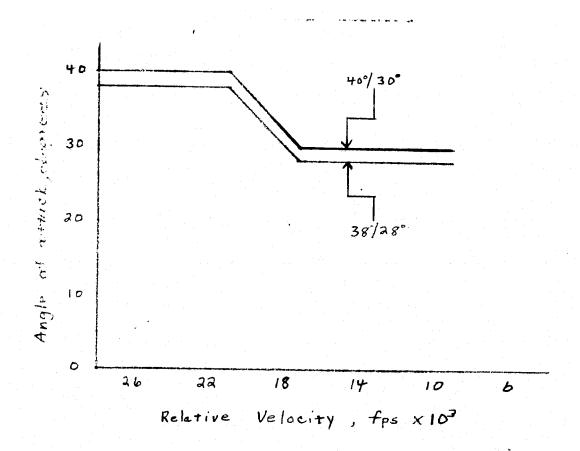
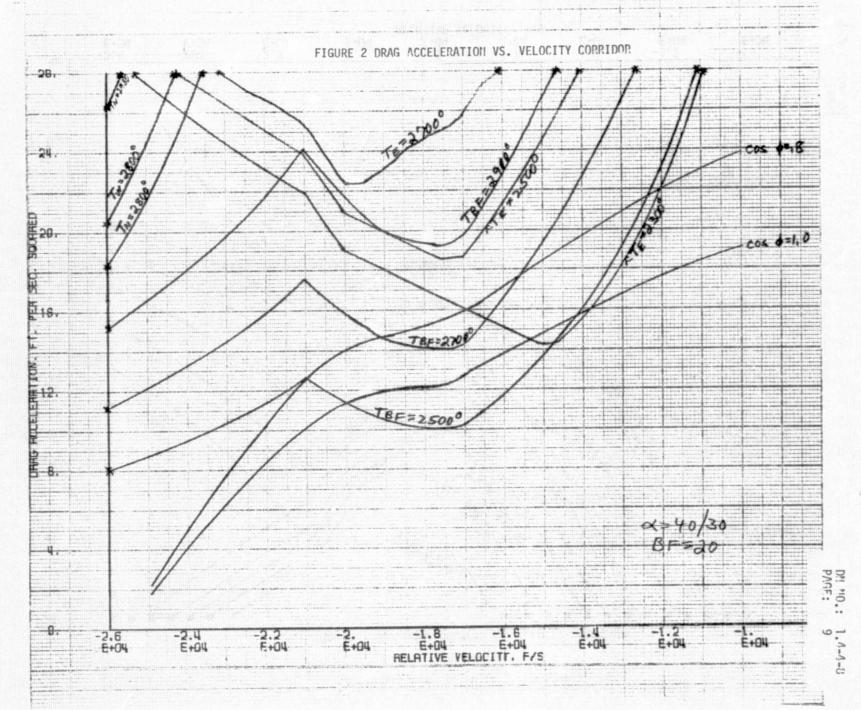
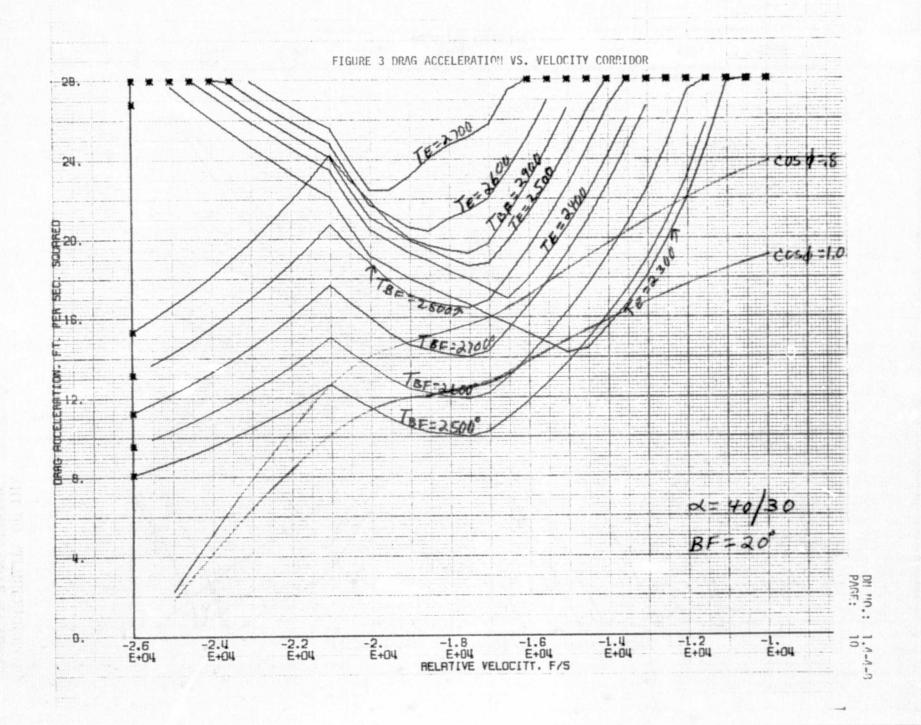
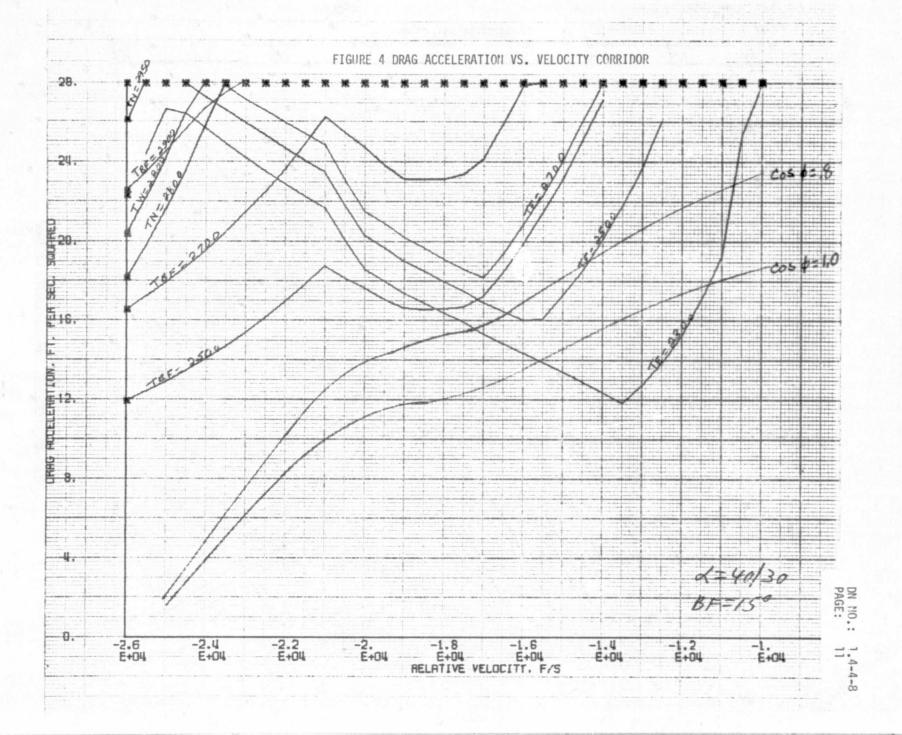
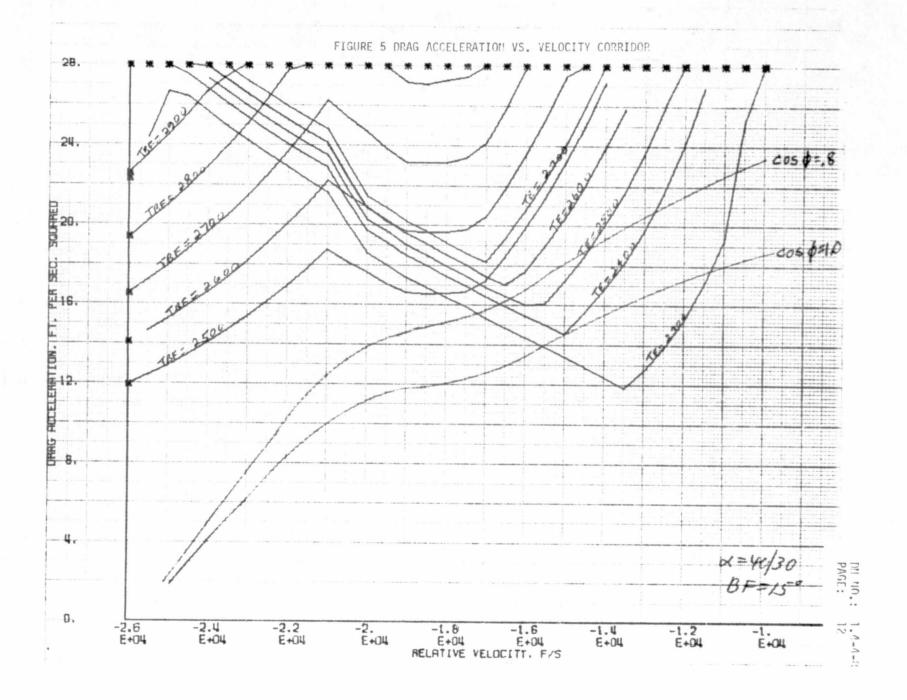


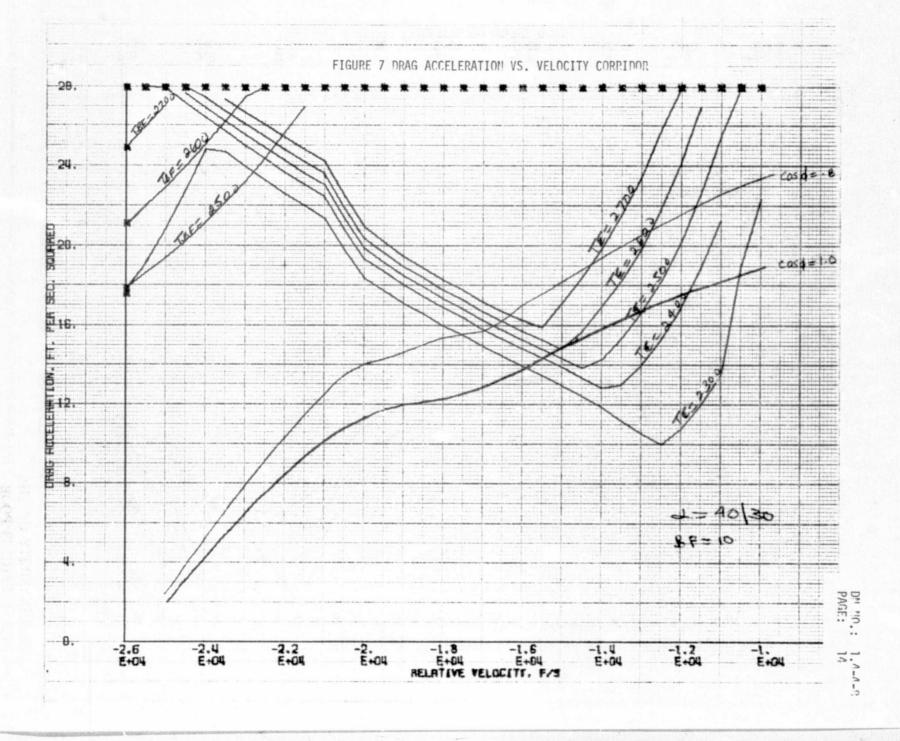
Figure 1 RAMPED ANGLE-OF-ATTACK PROFILES AS A FUNCTION OF RELATIVE VELOCITY

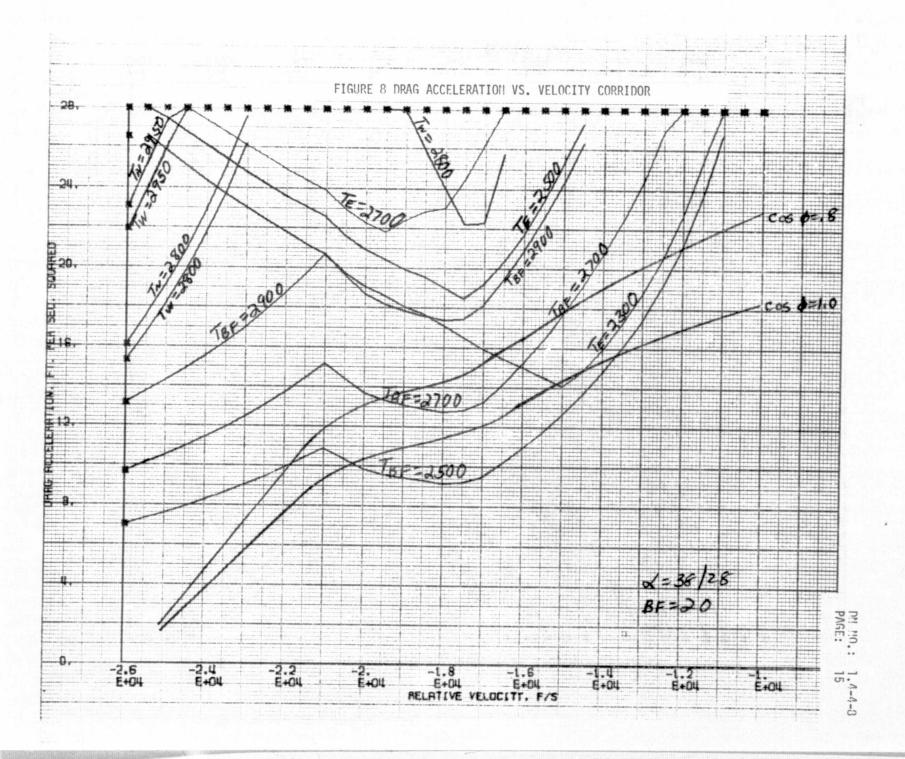


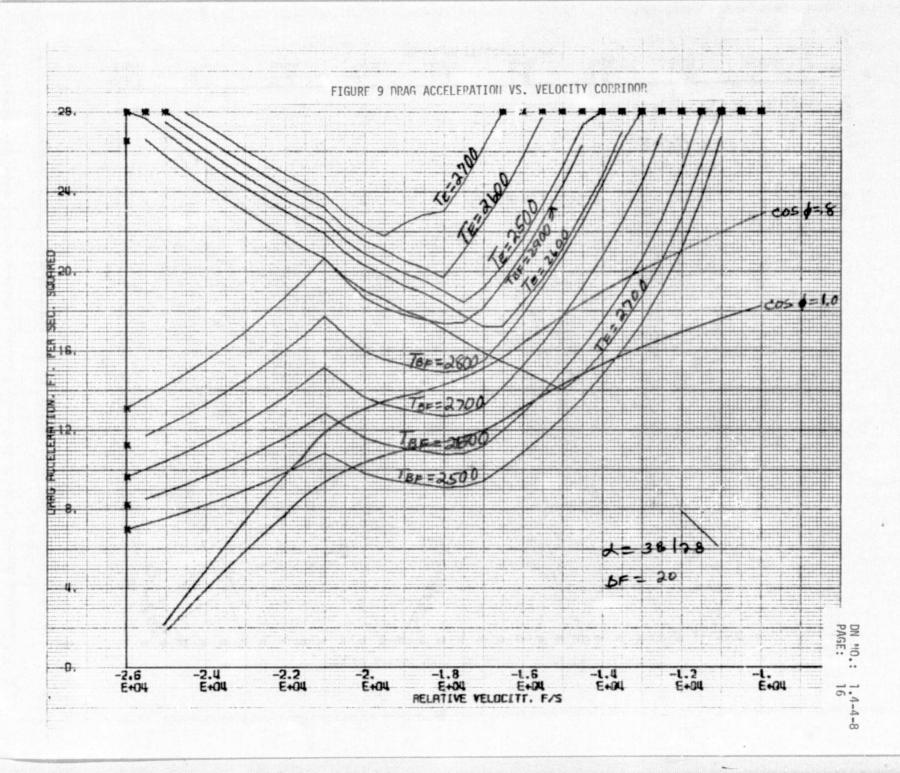


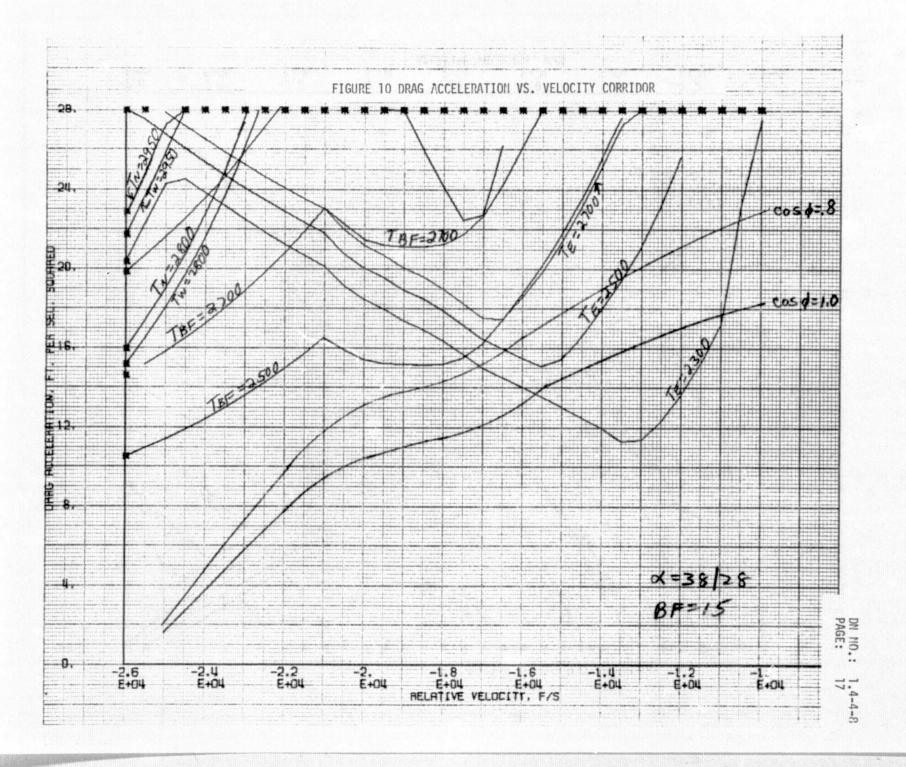


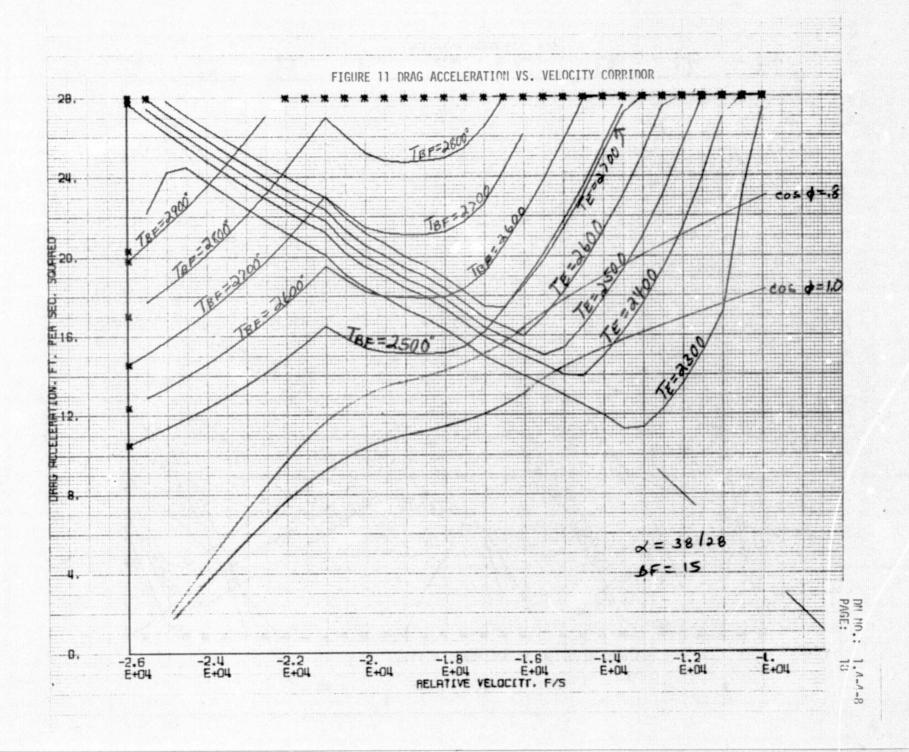


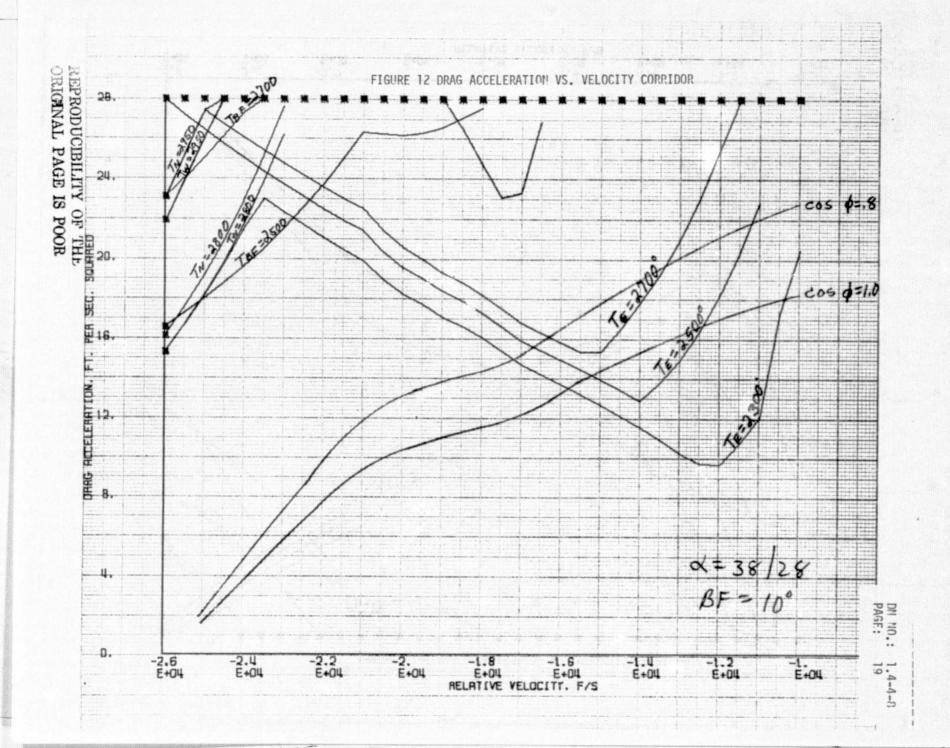


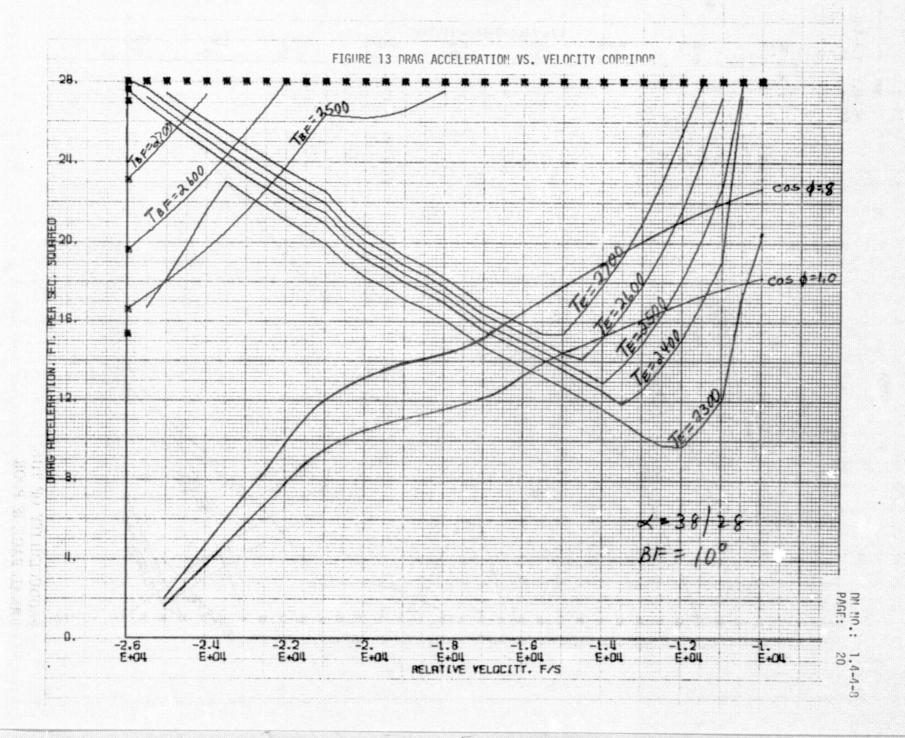


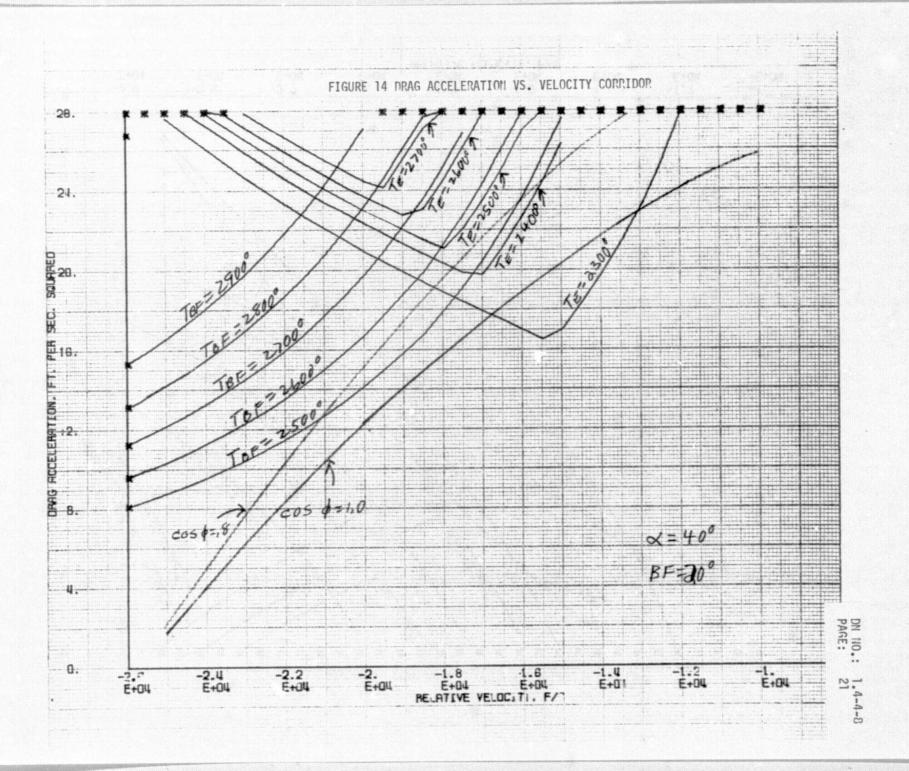


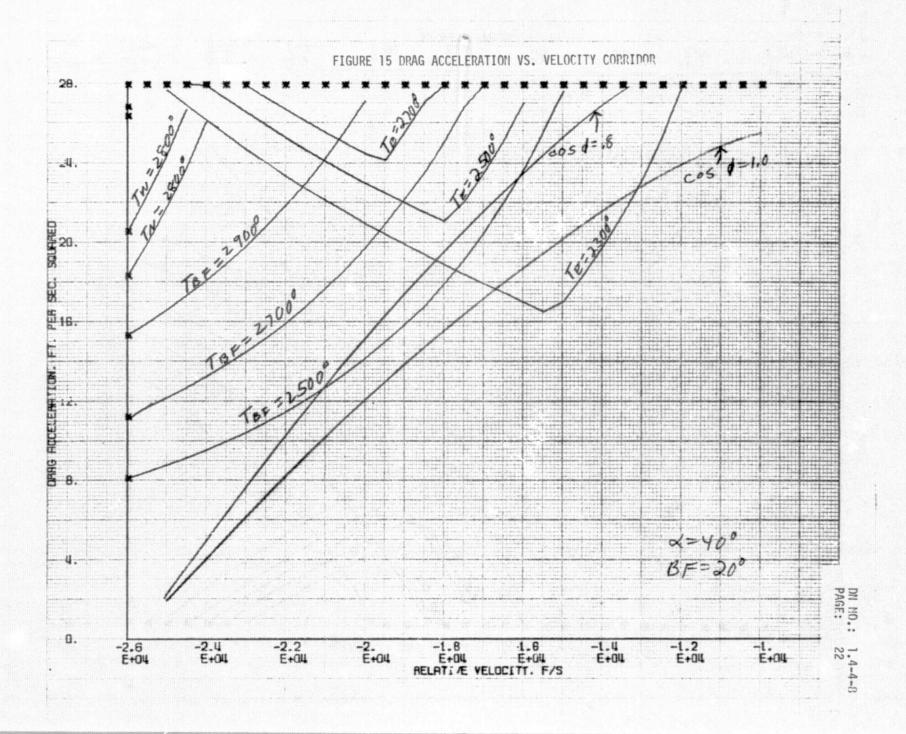


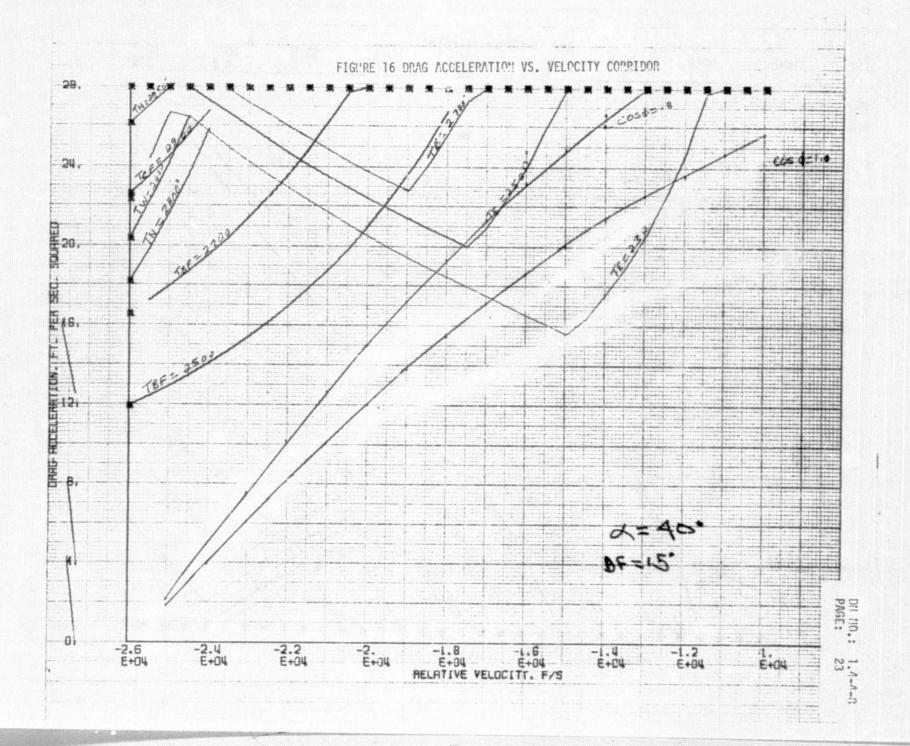


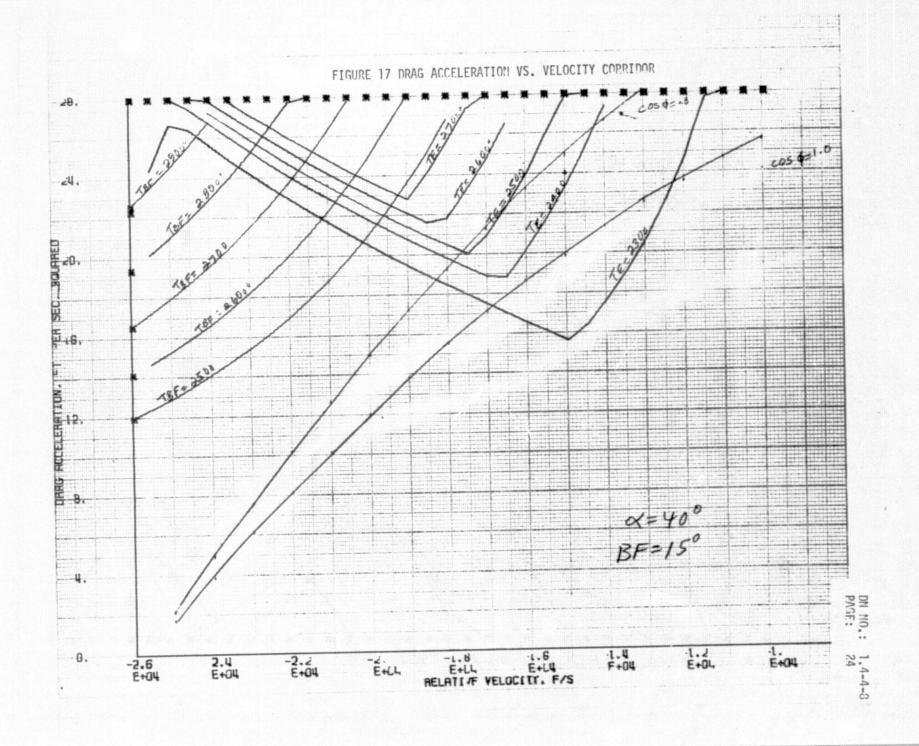


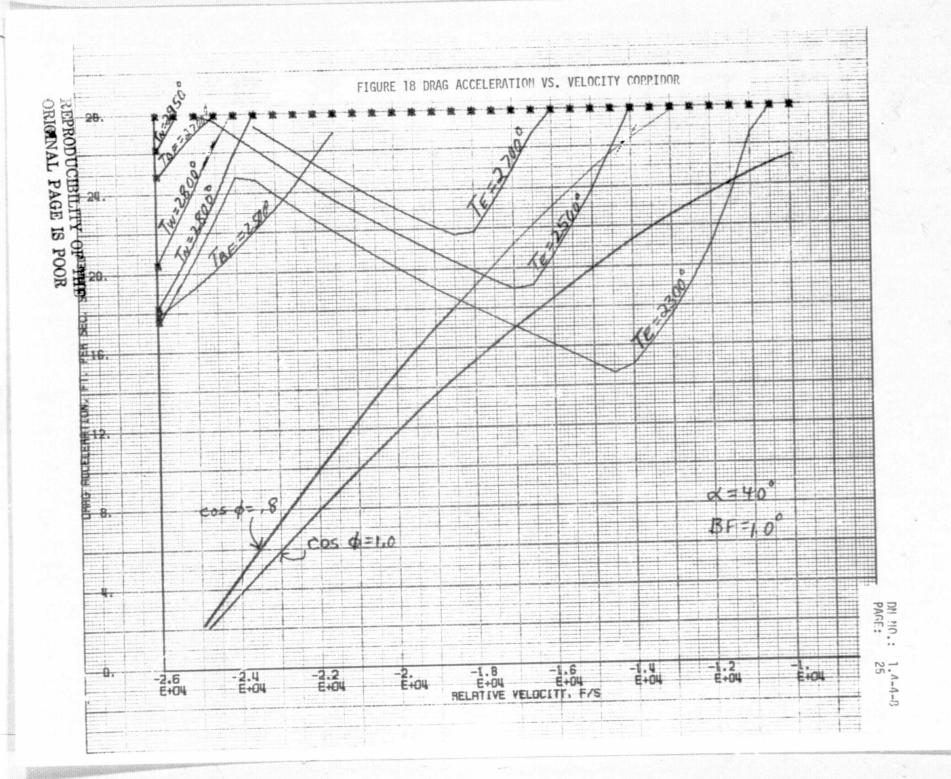


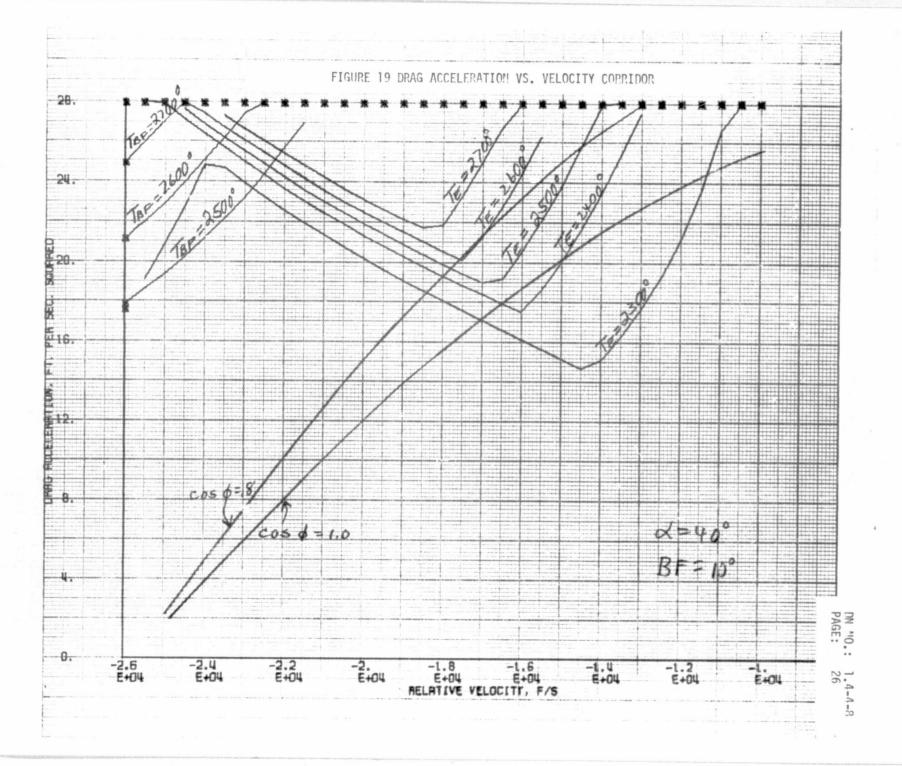


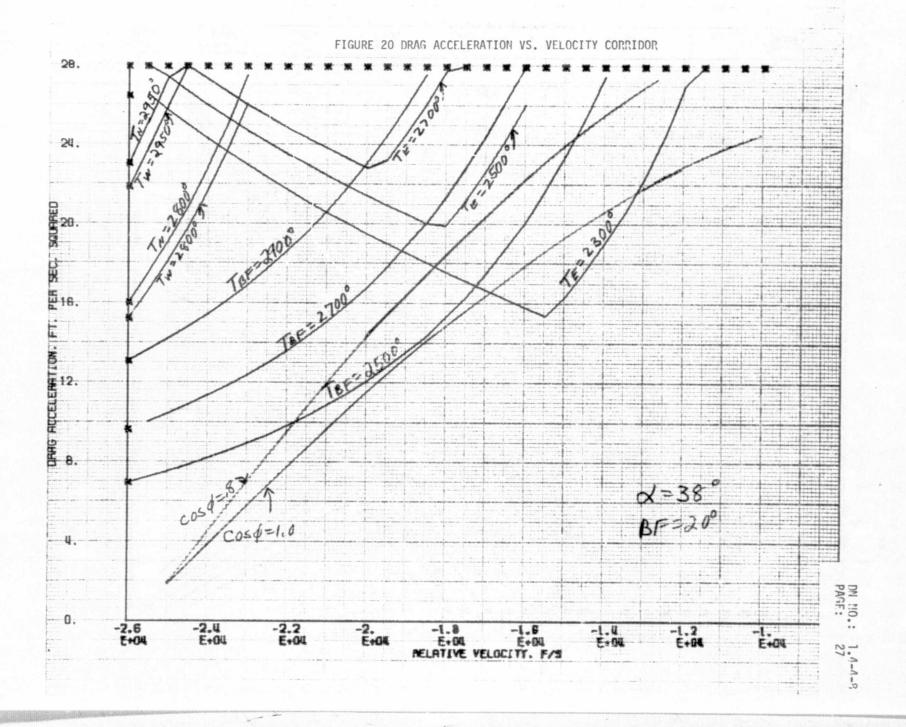


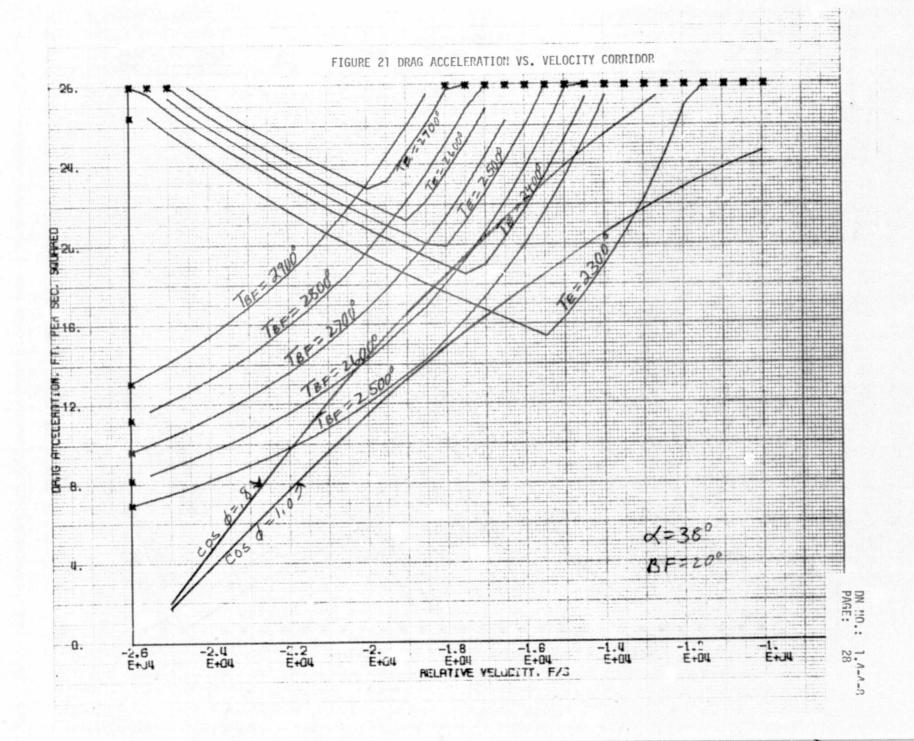


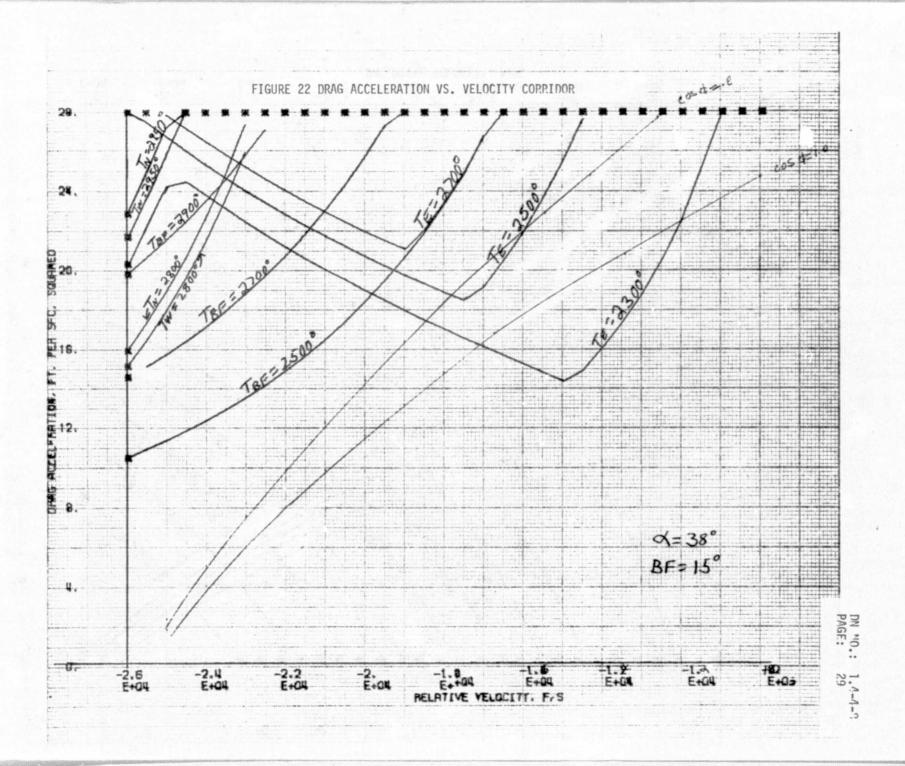


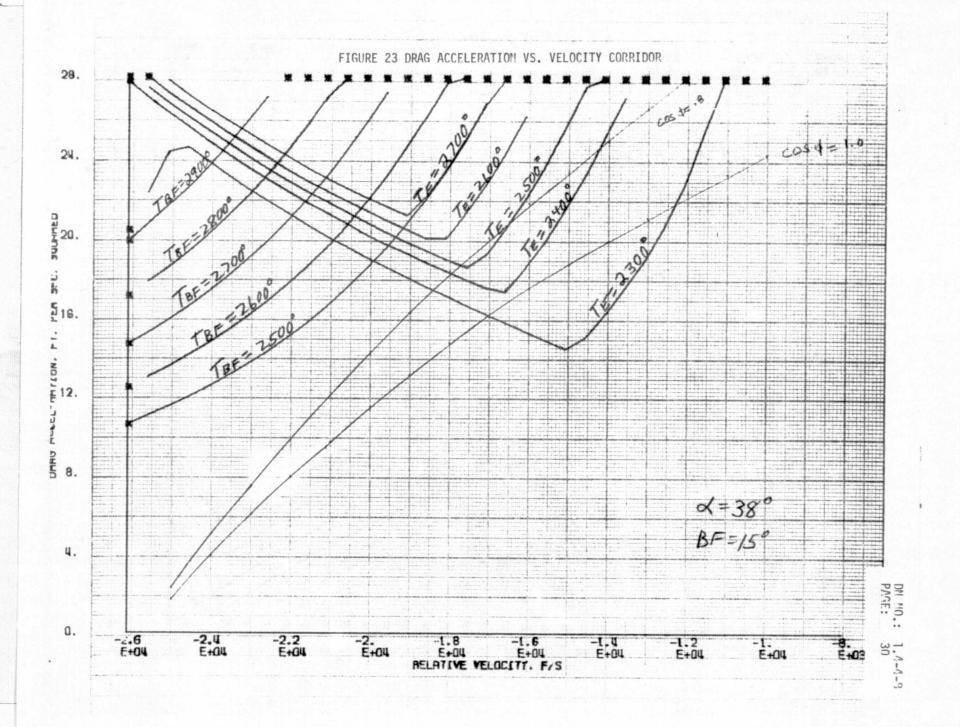


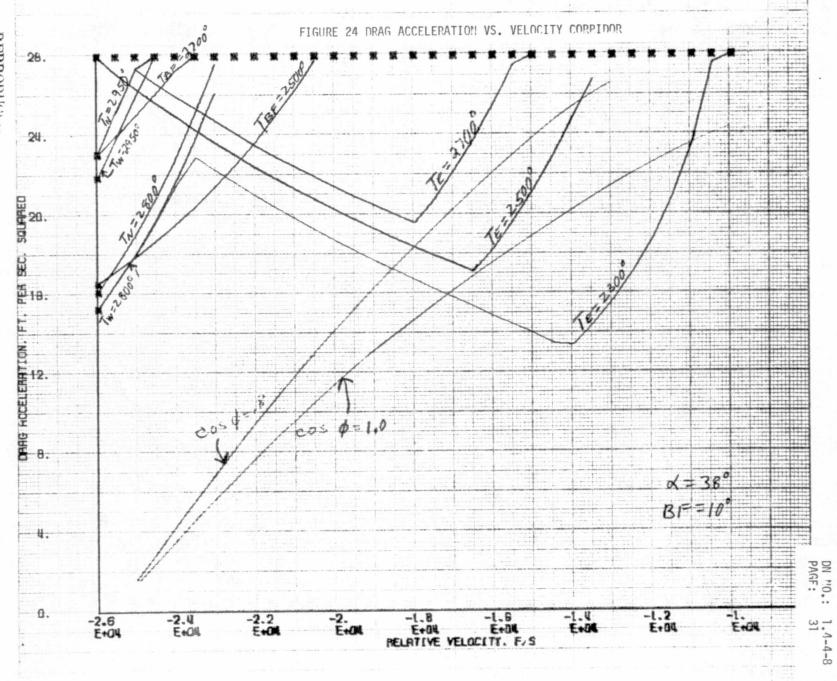


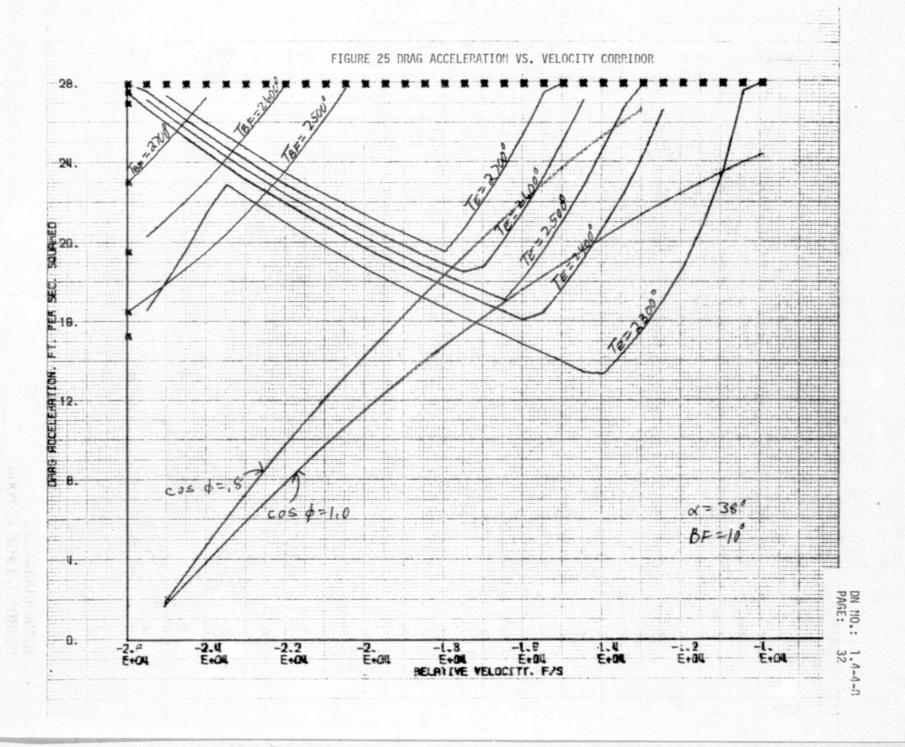


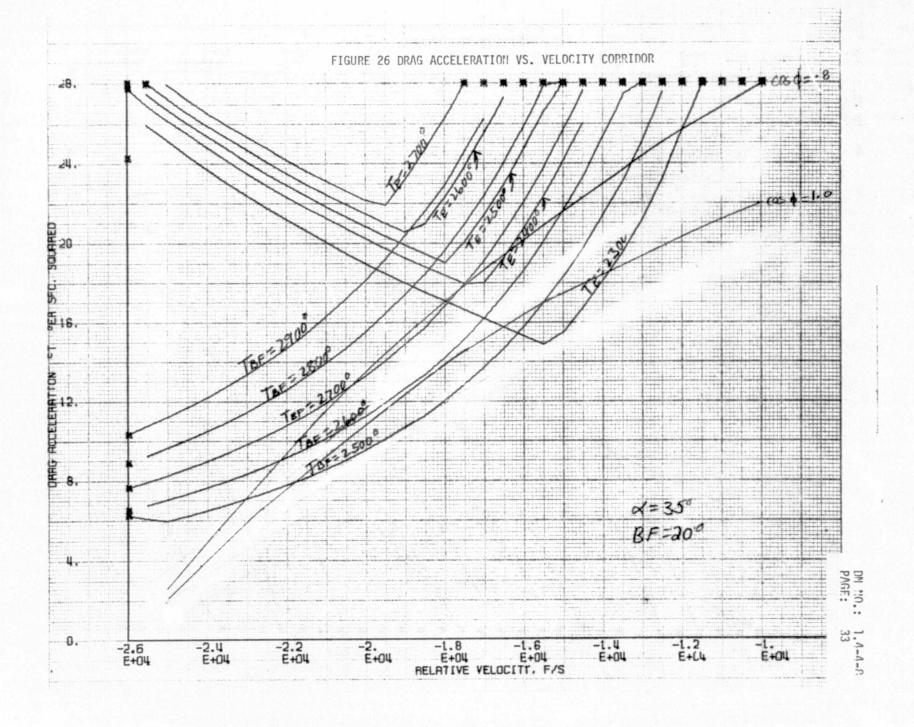


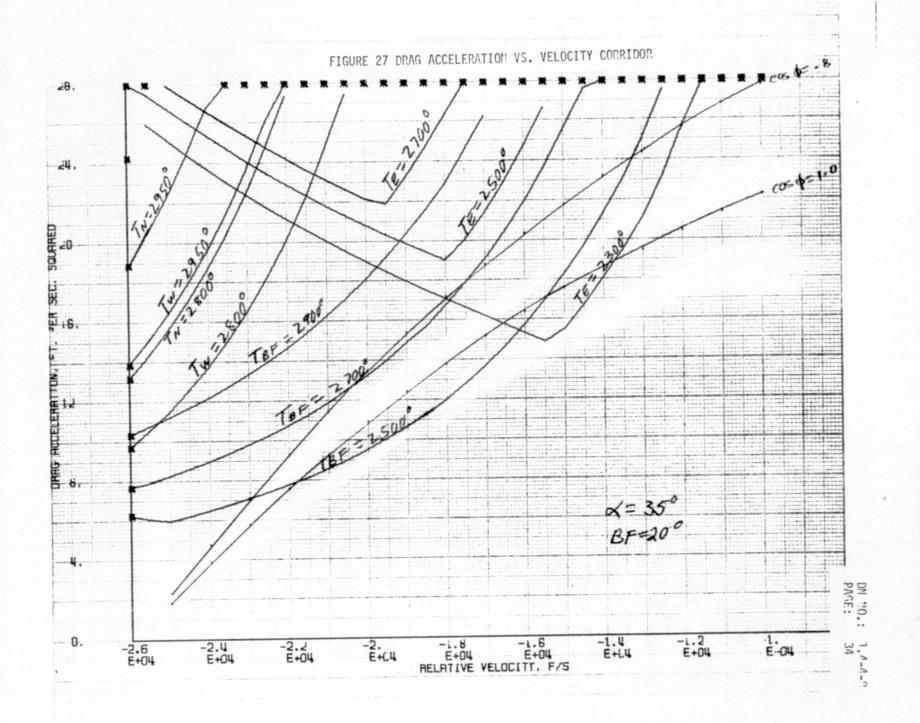


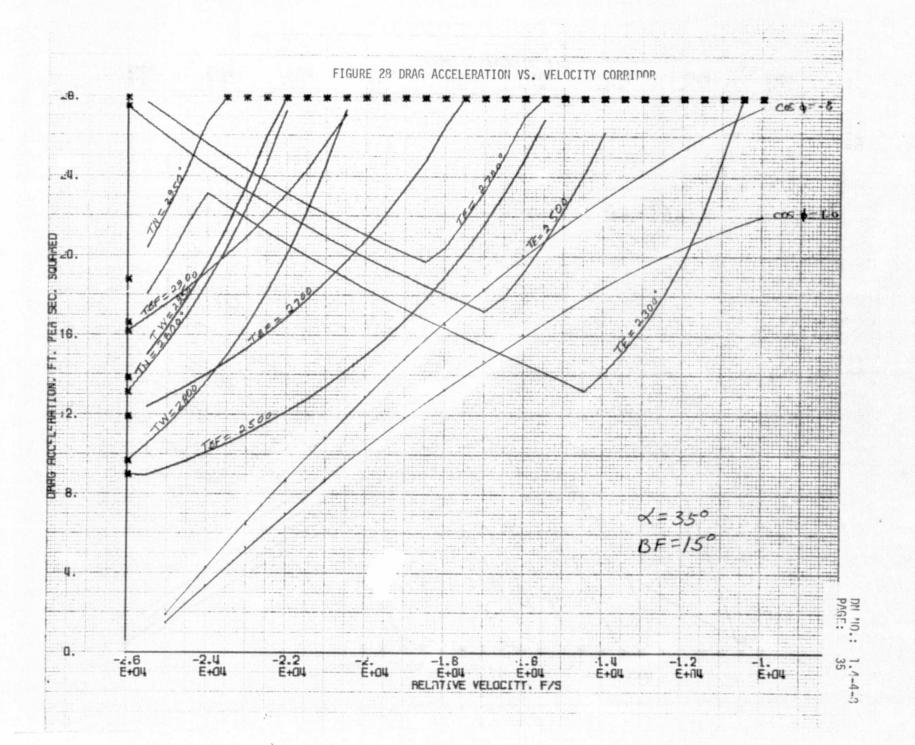


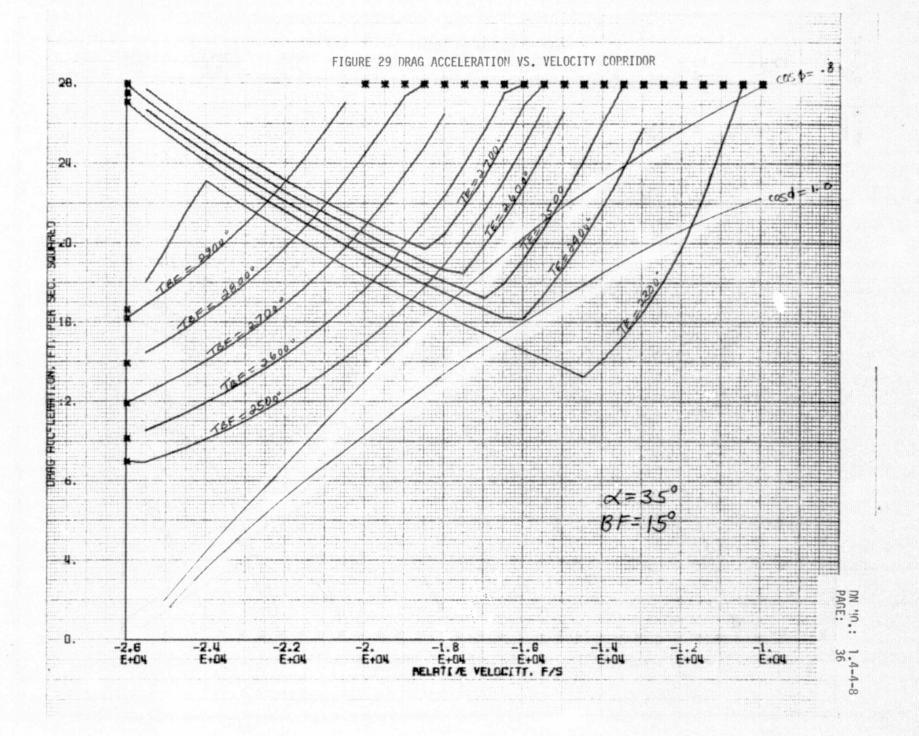


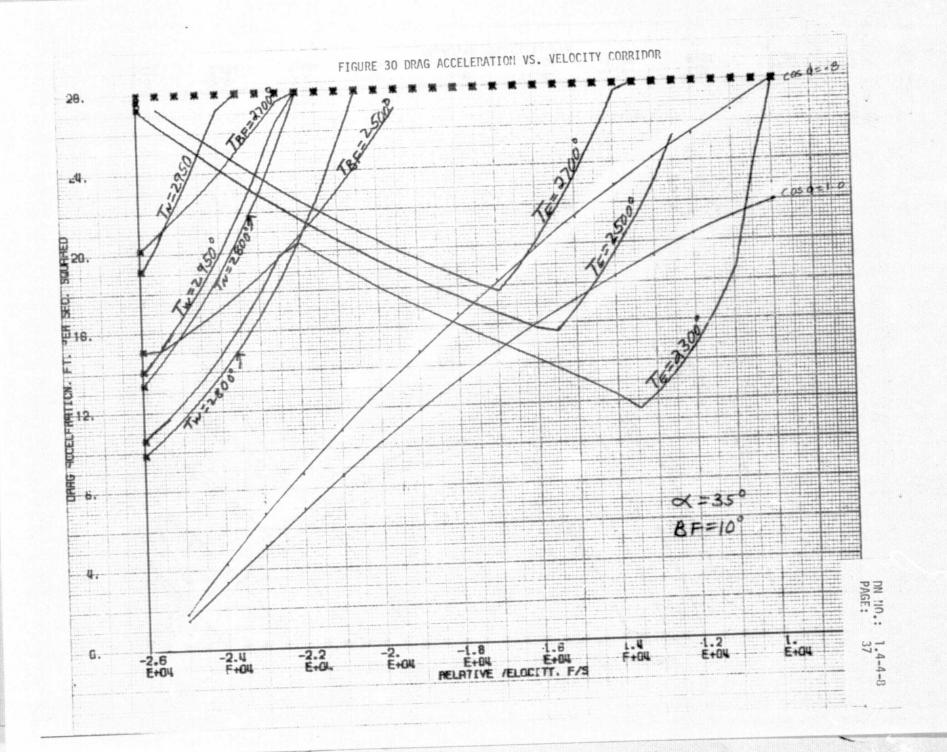


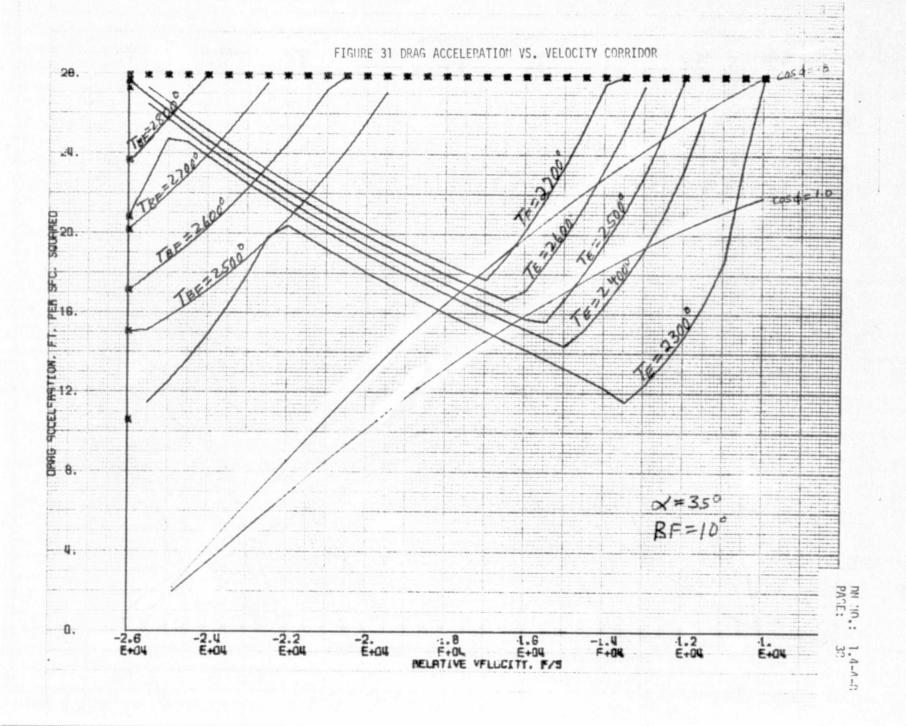


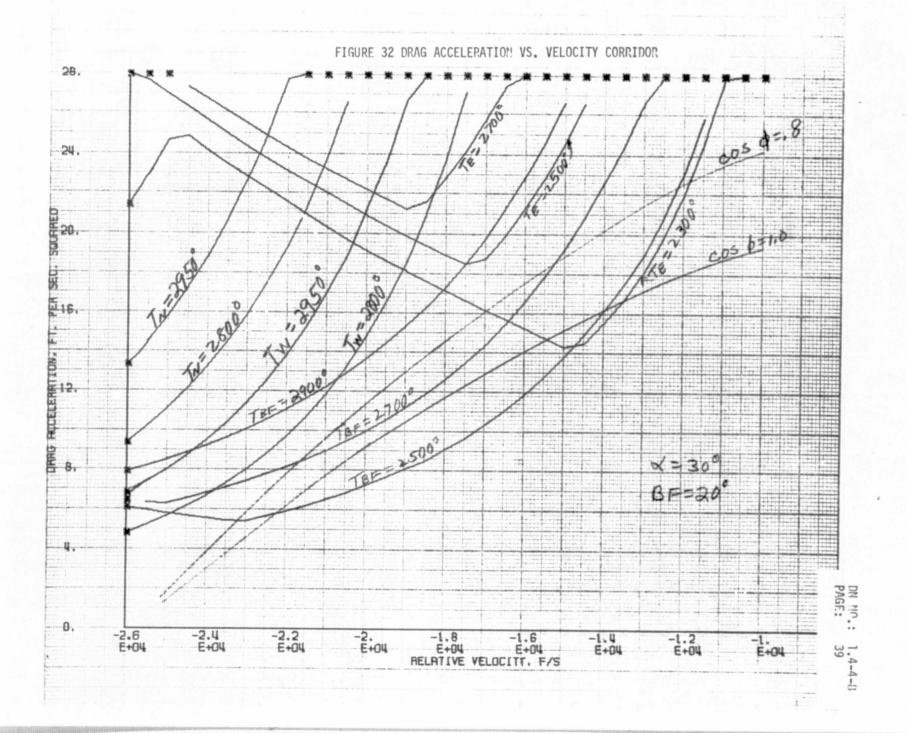


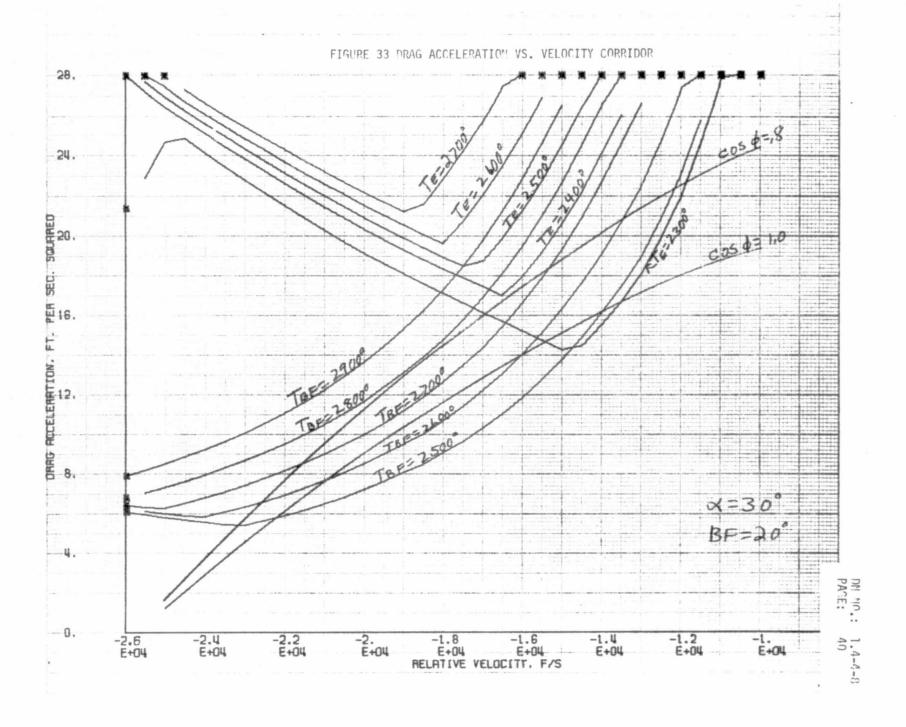


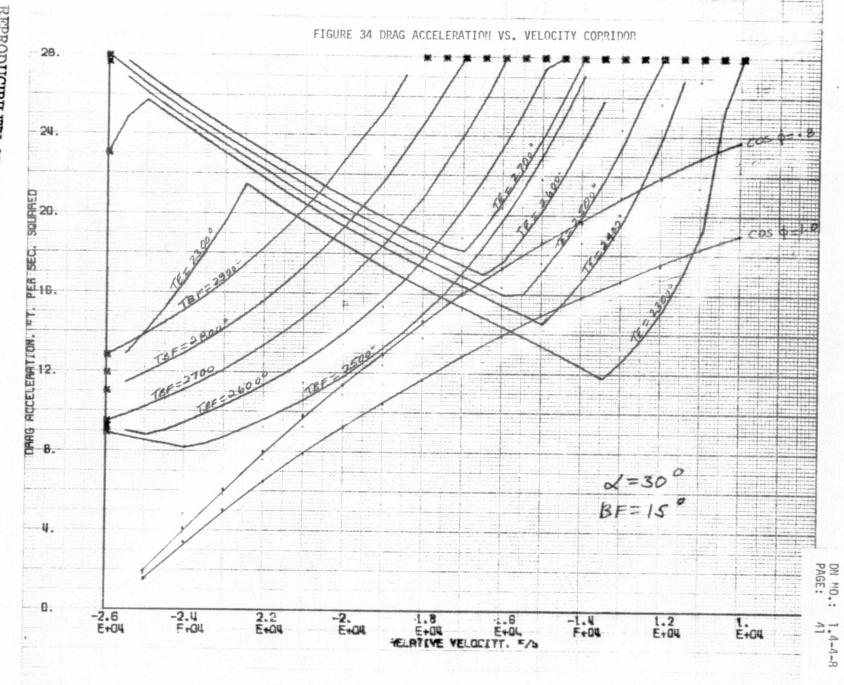


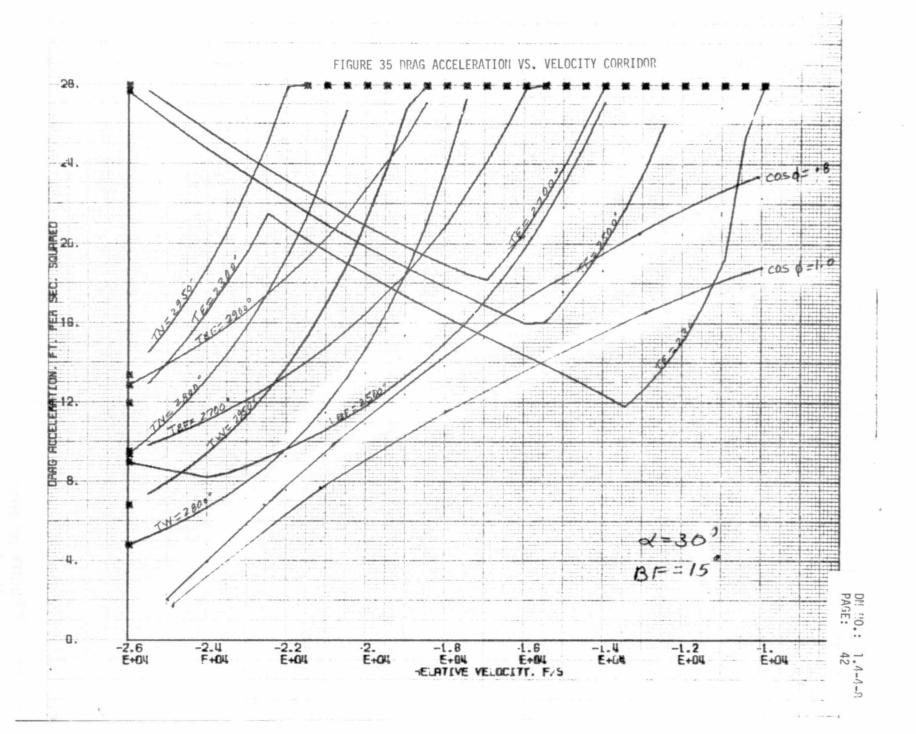


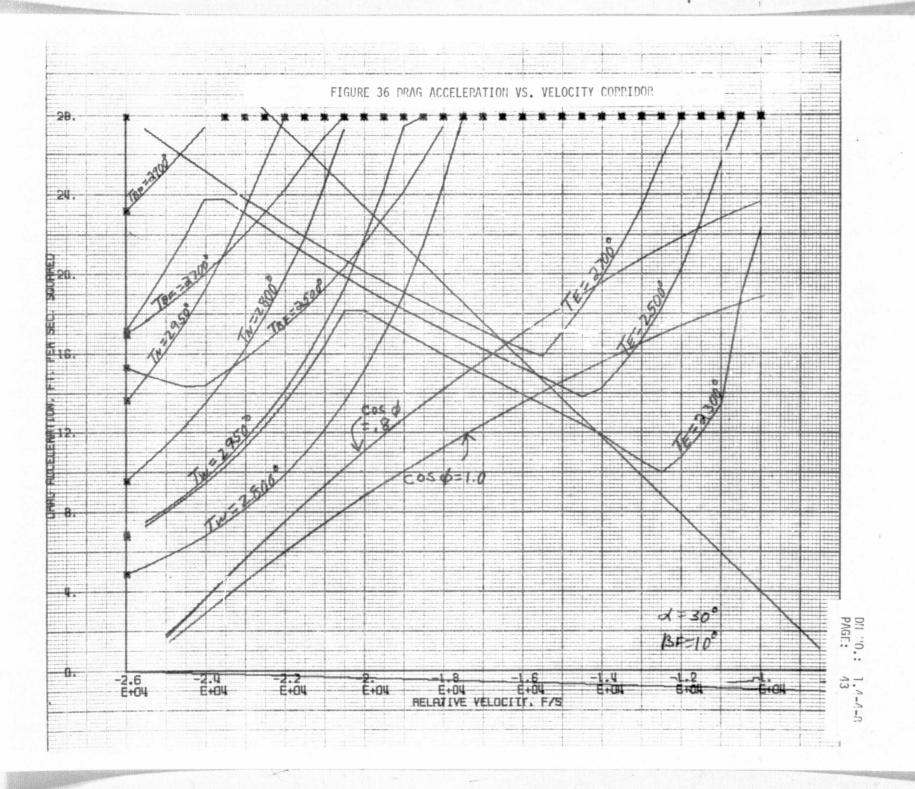


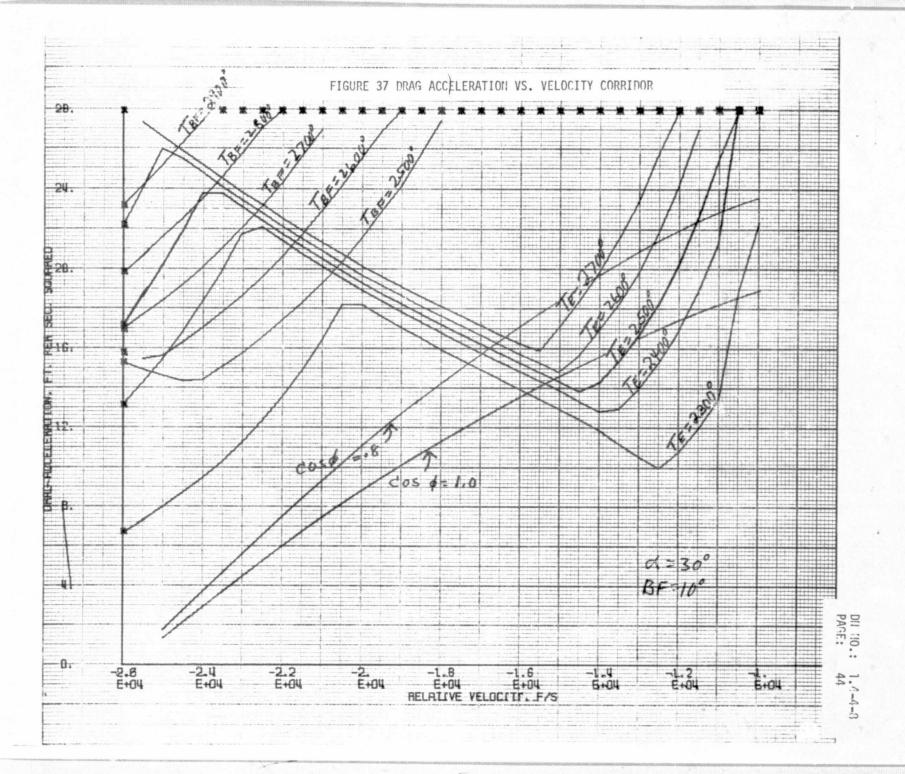


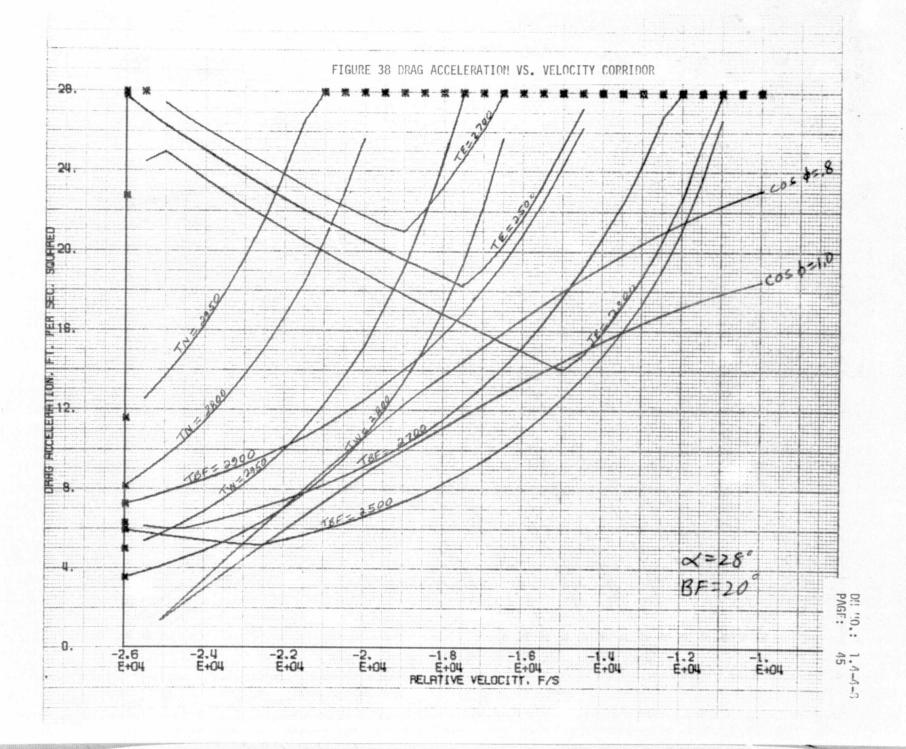


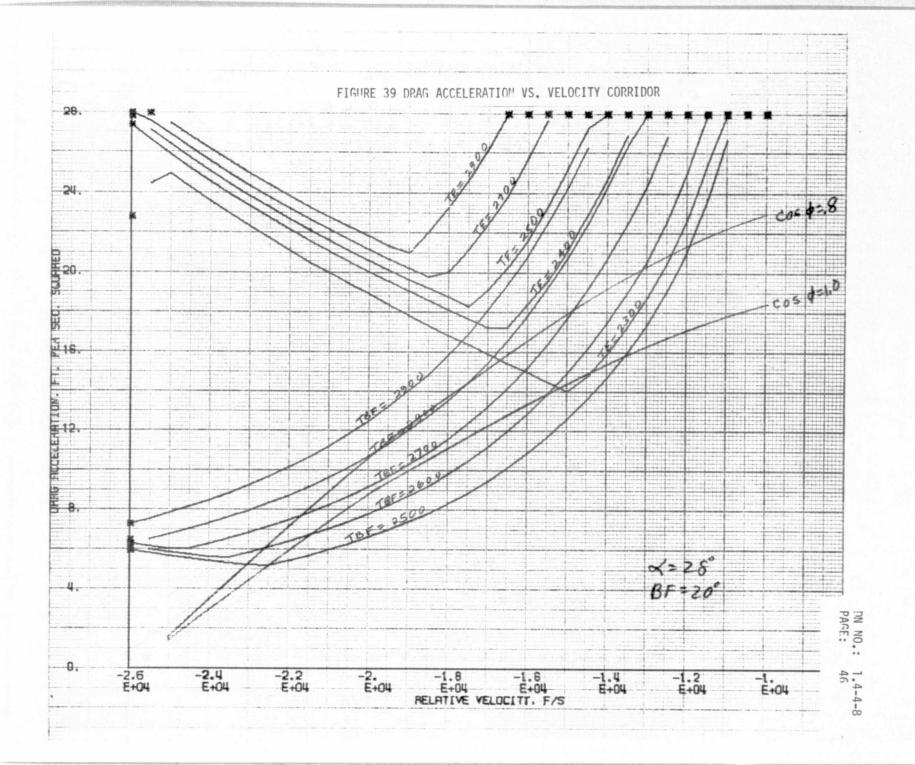


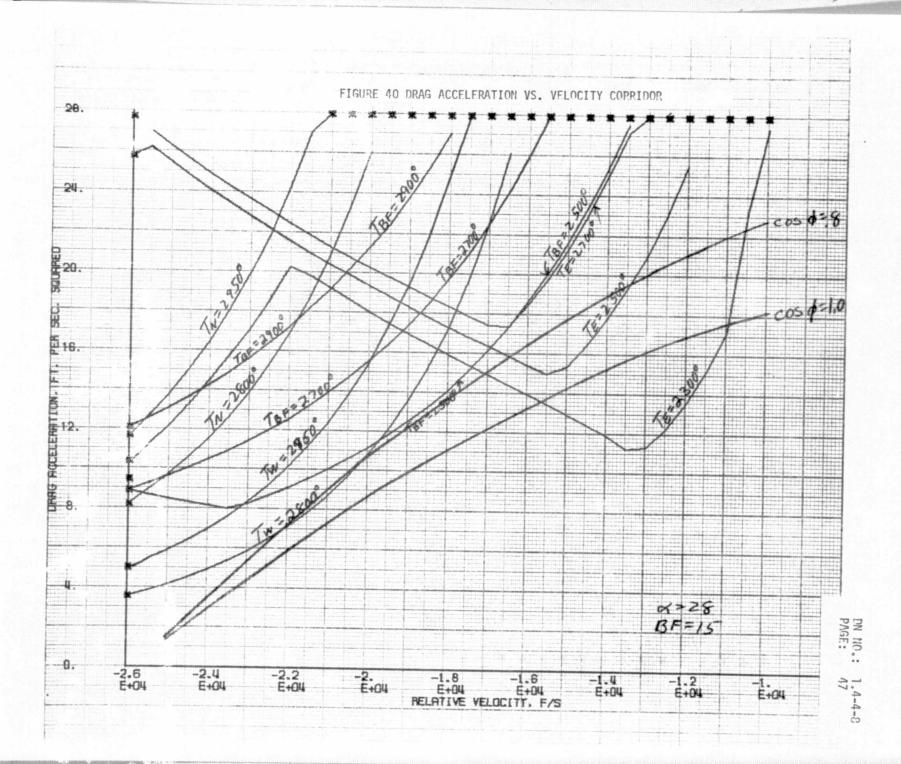


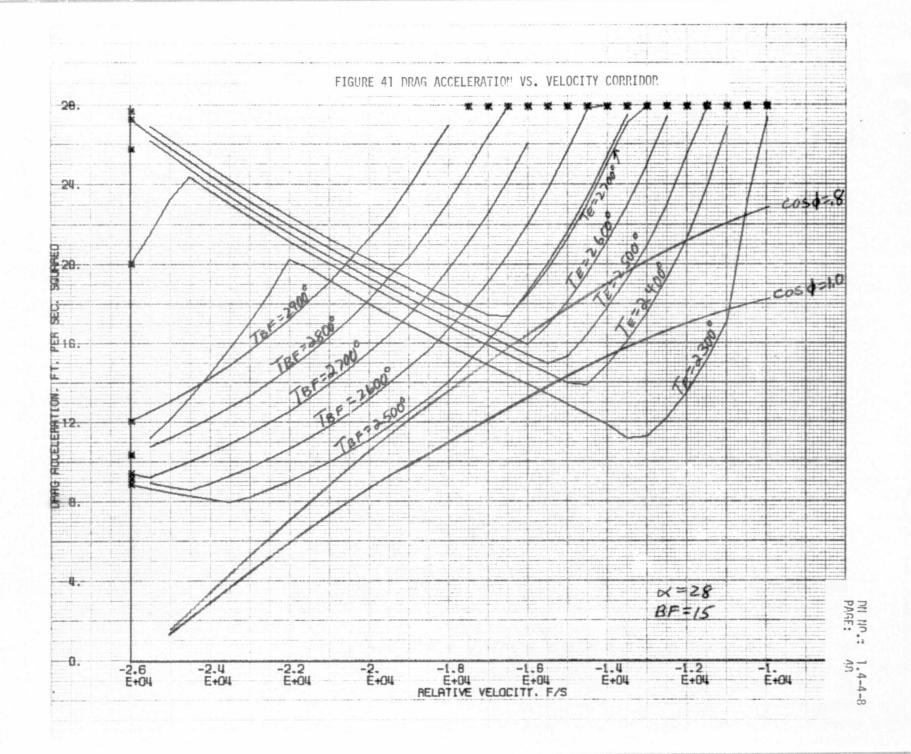


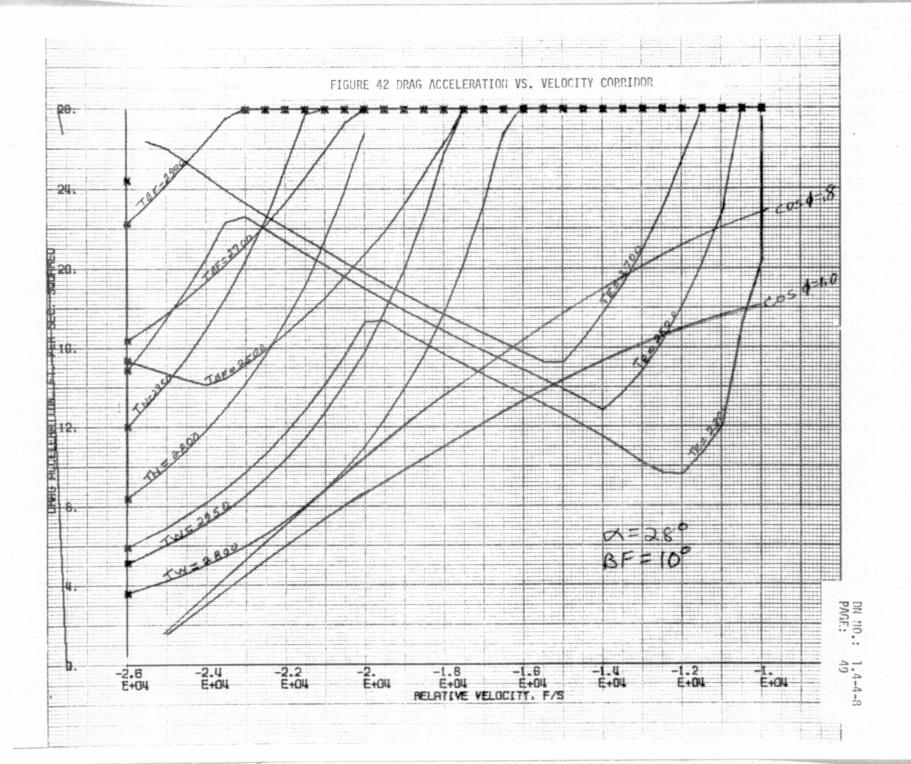


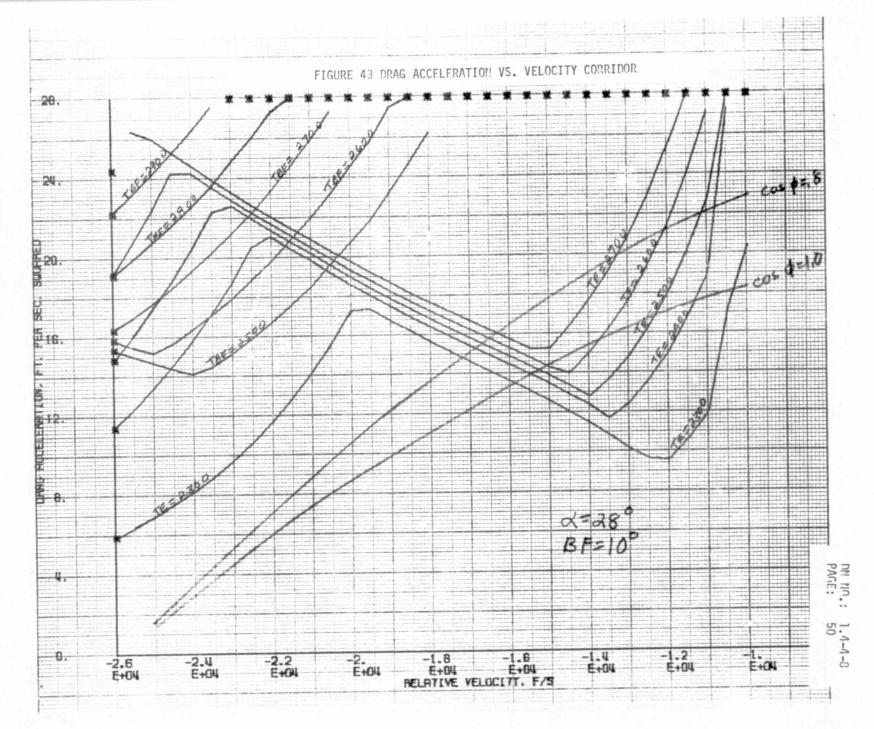


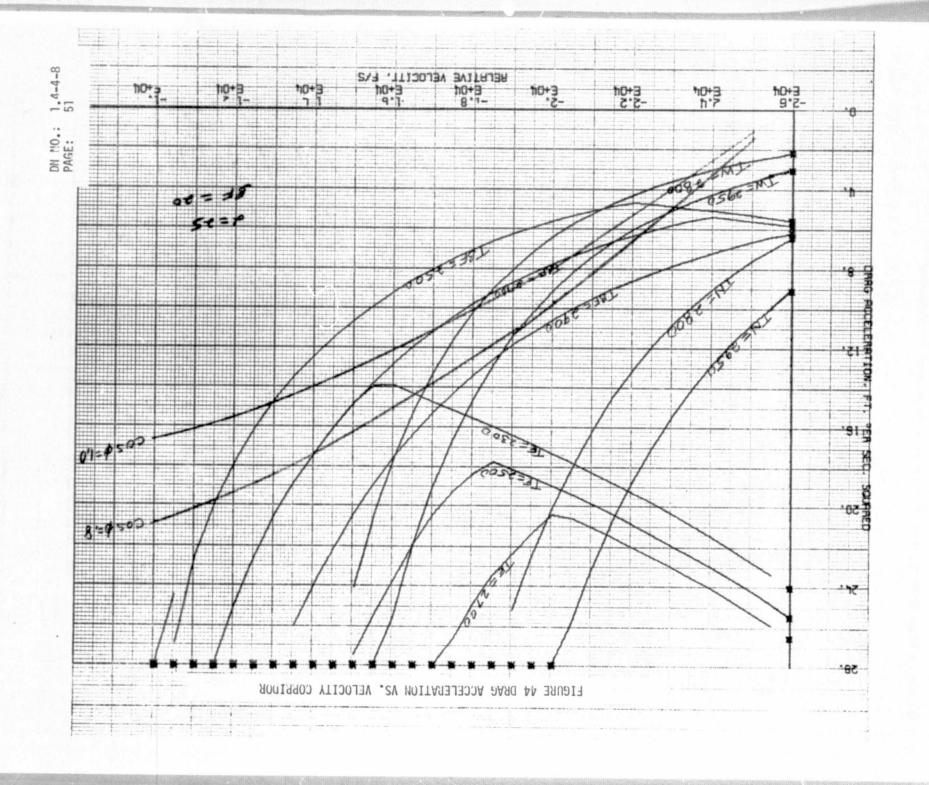


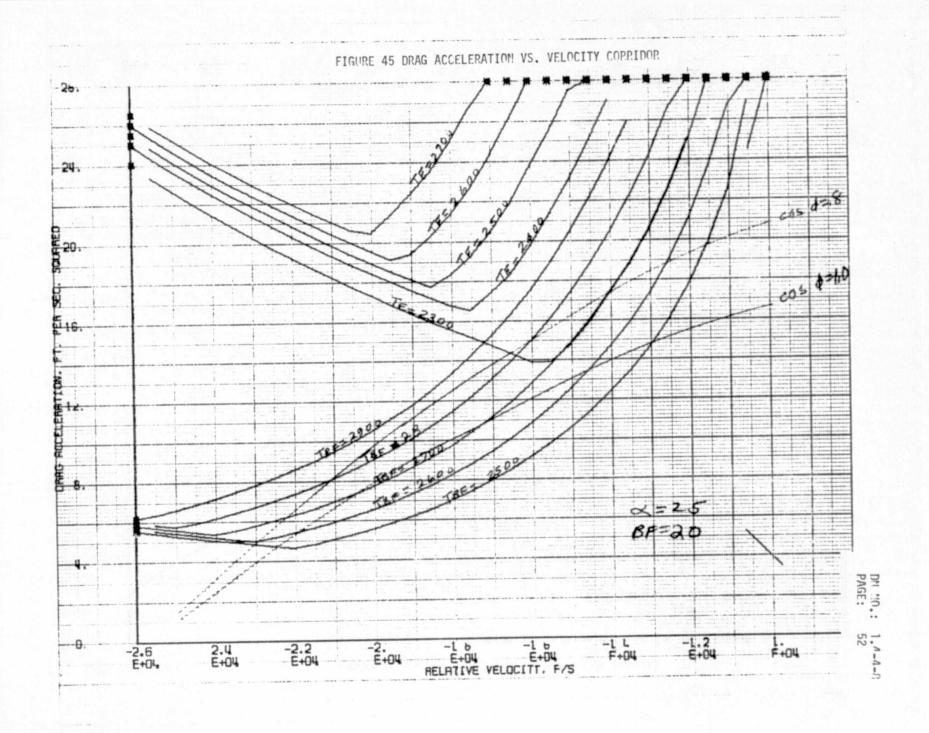


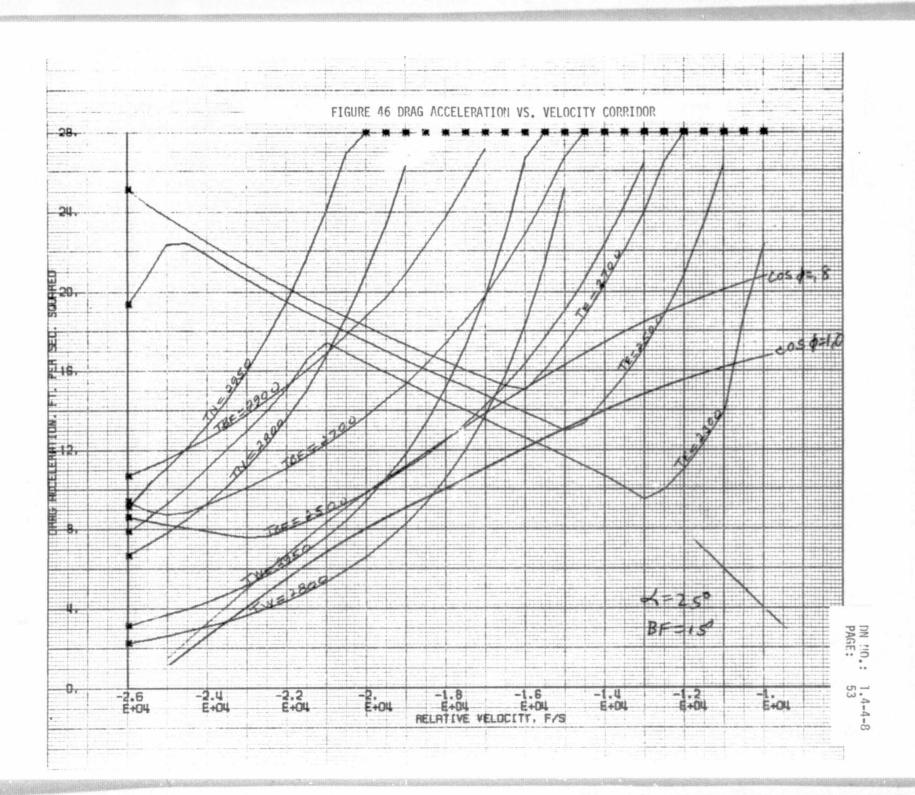


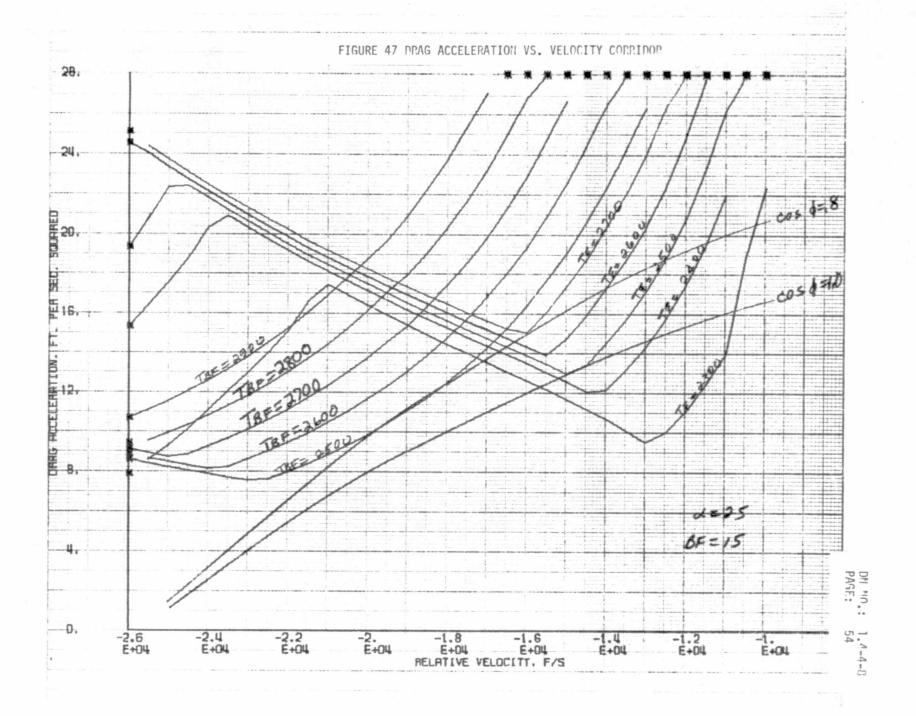


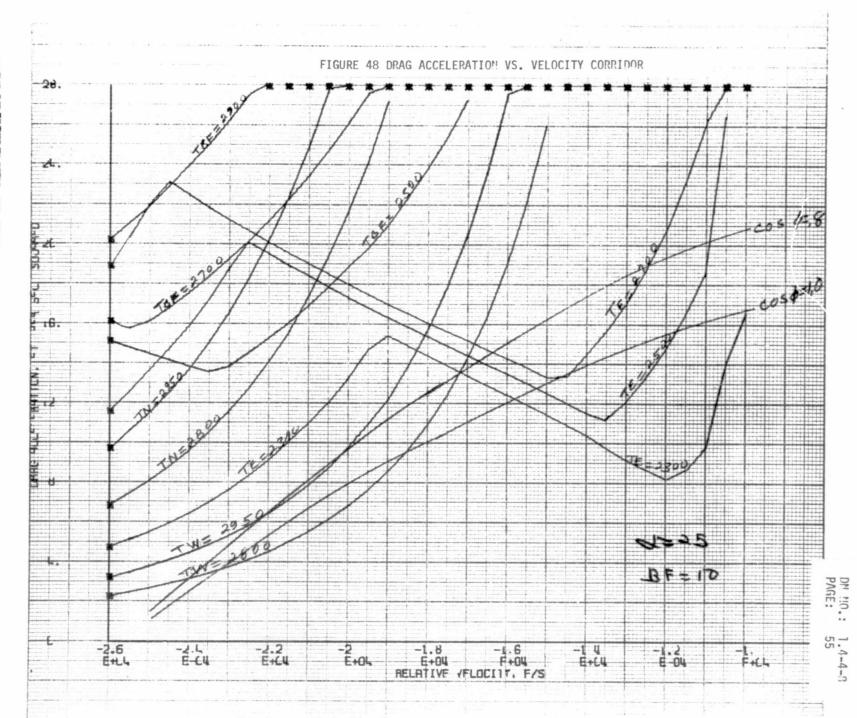


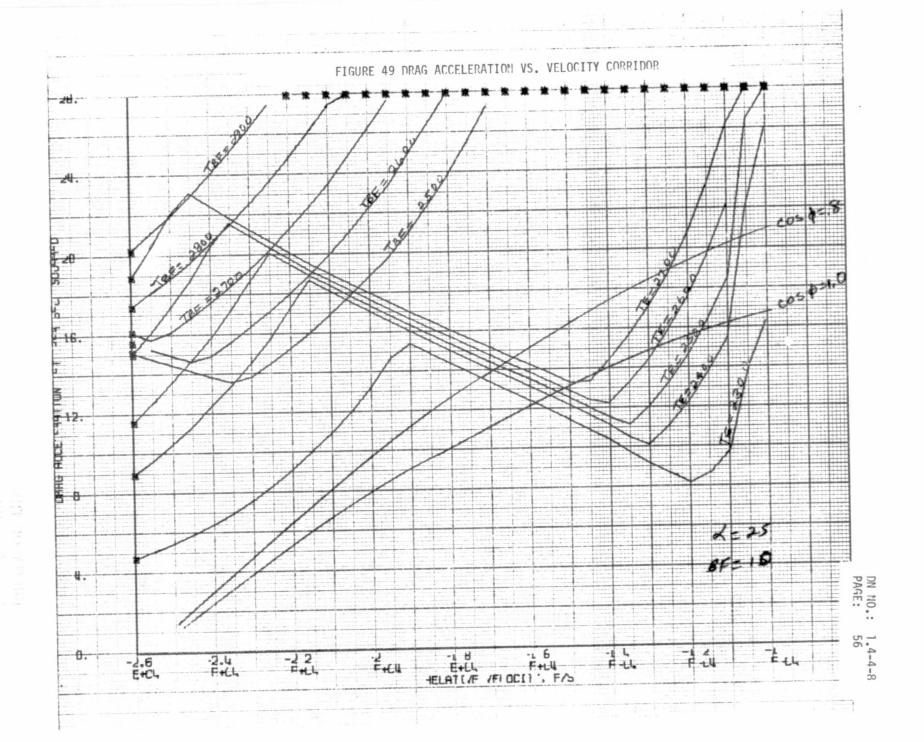


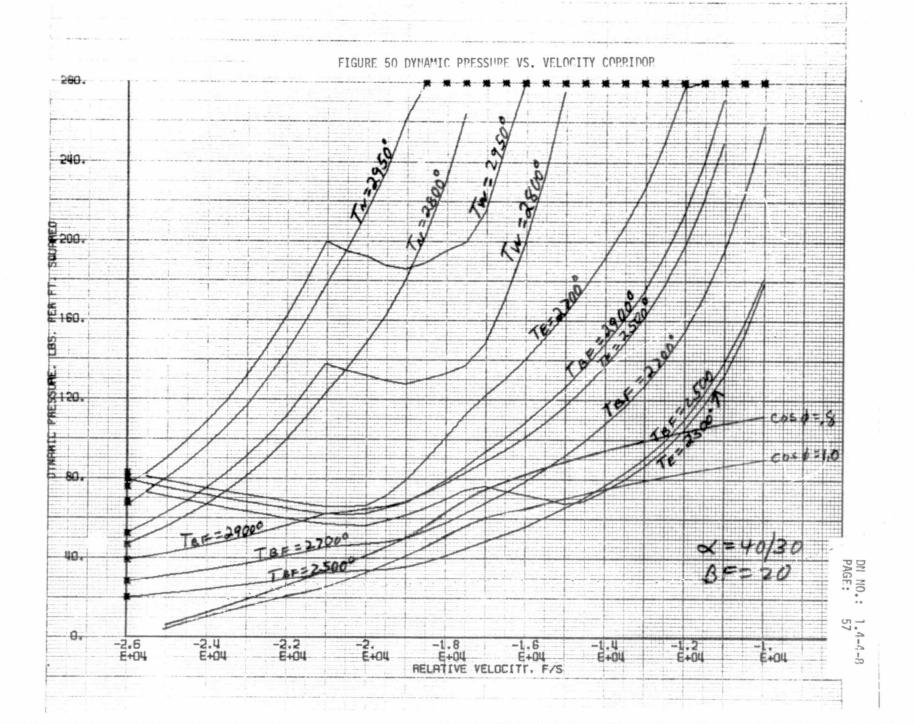


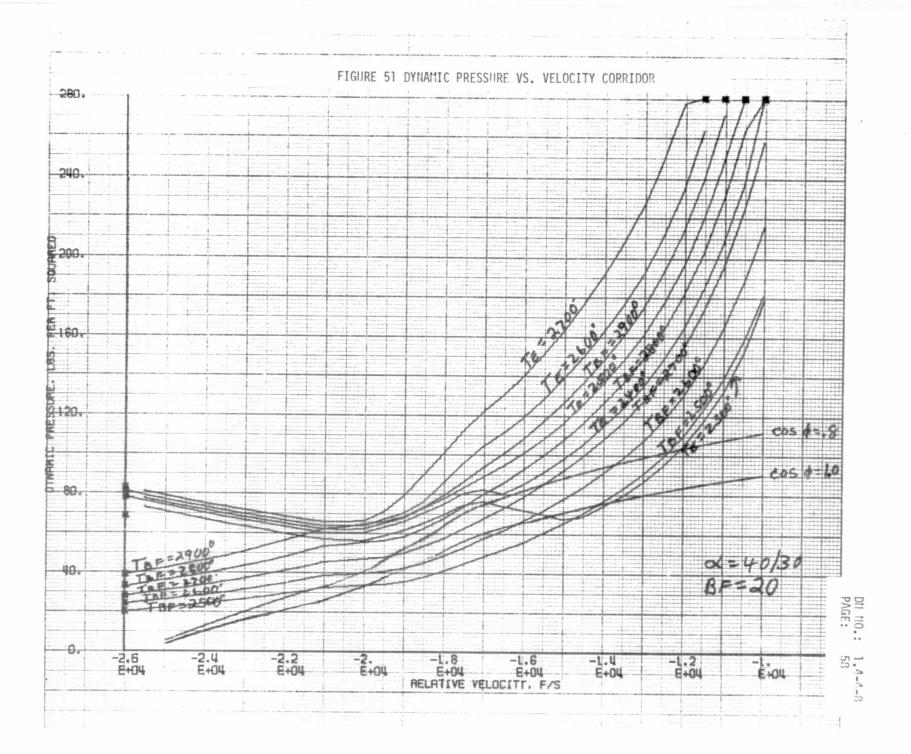


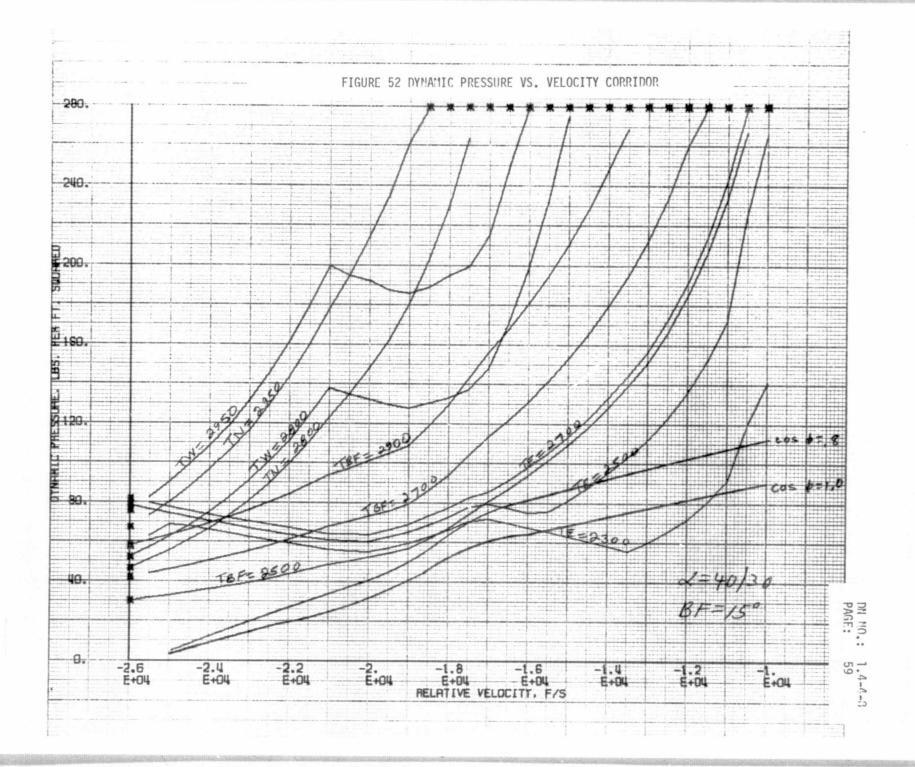


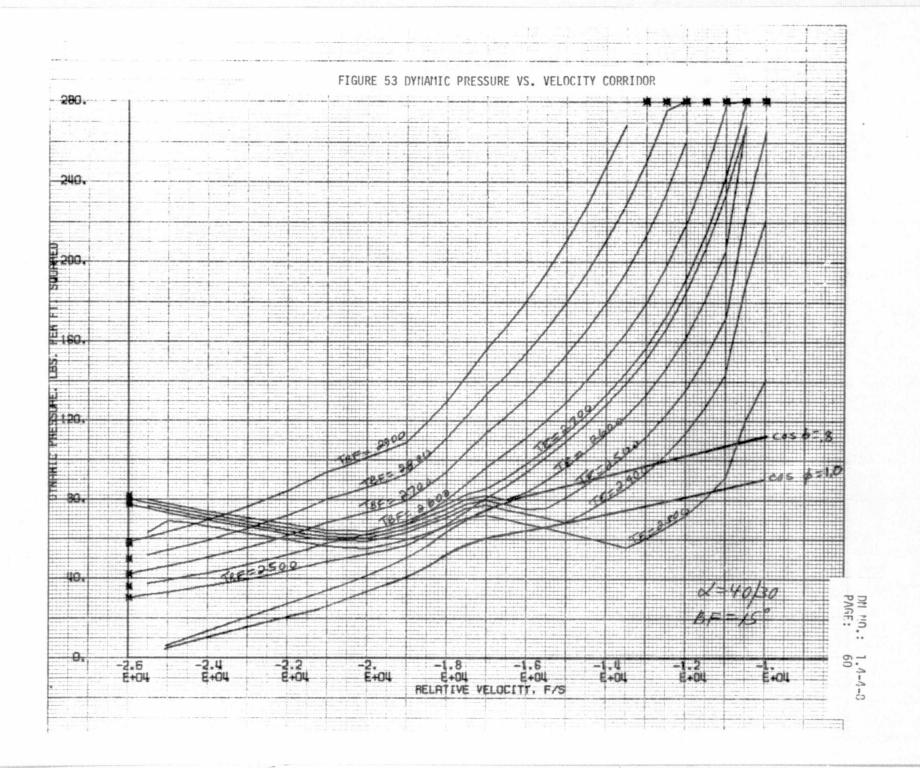


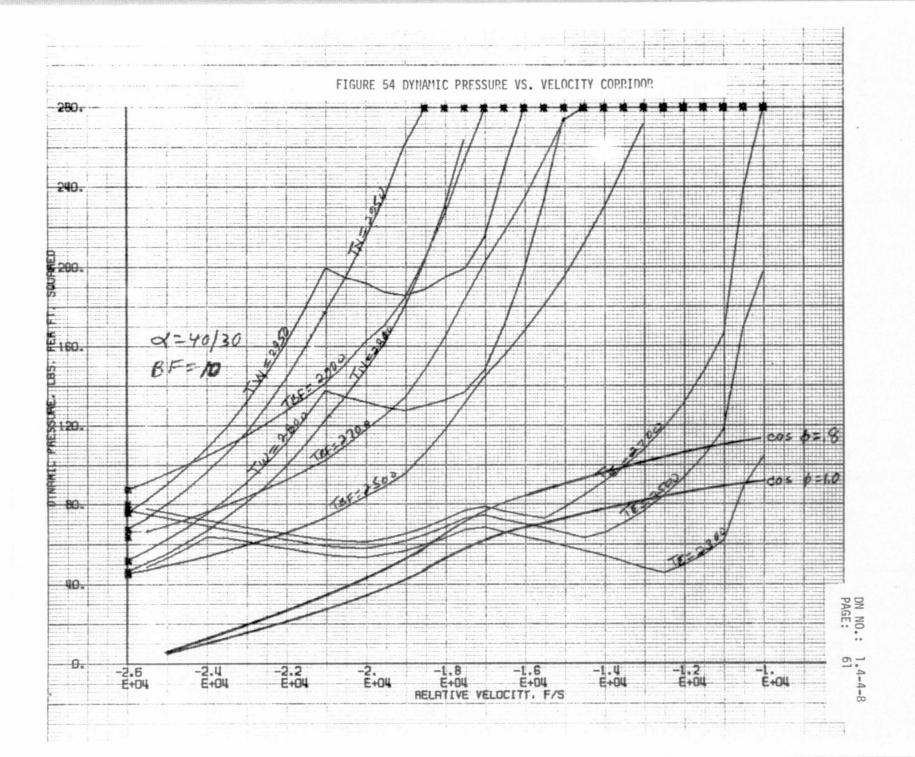


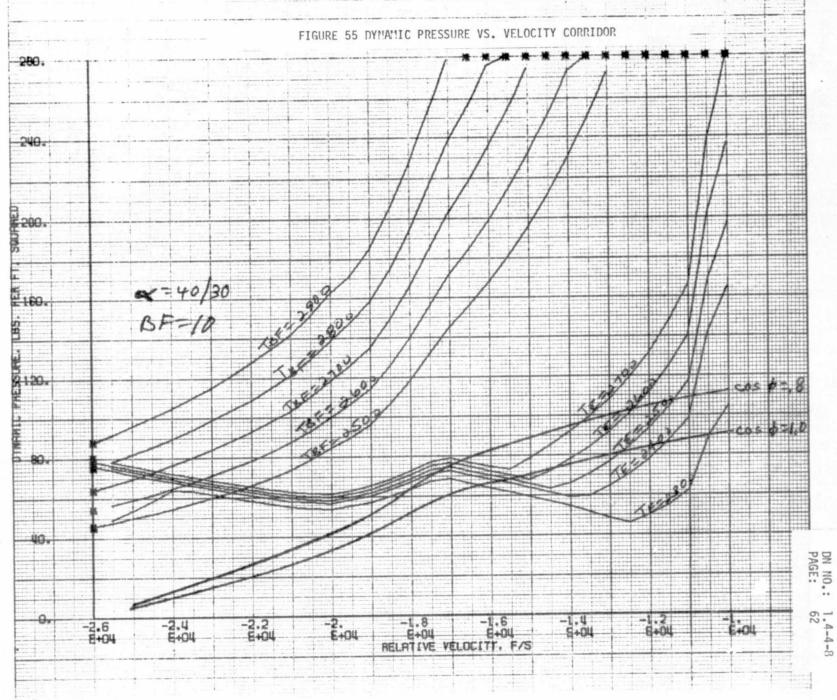


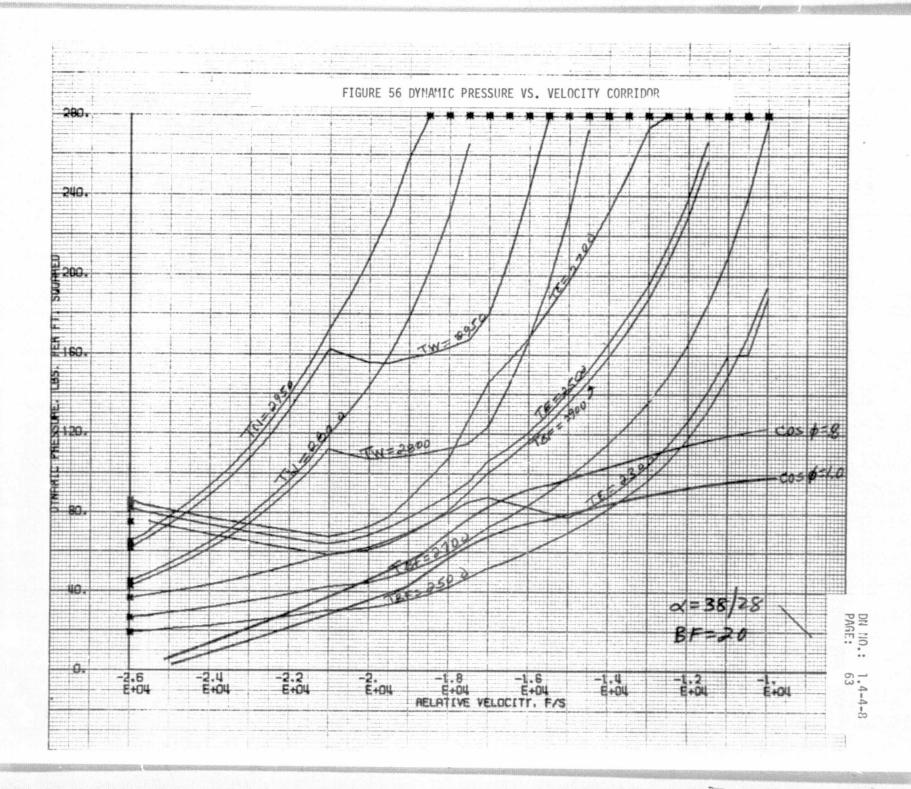


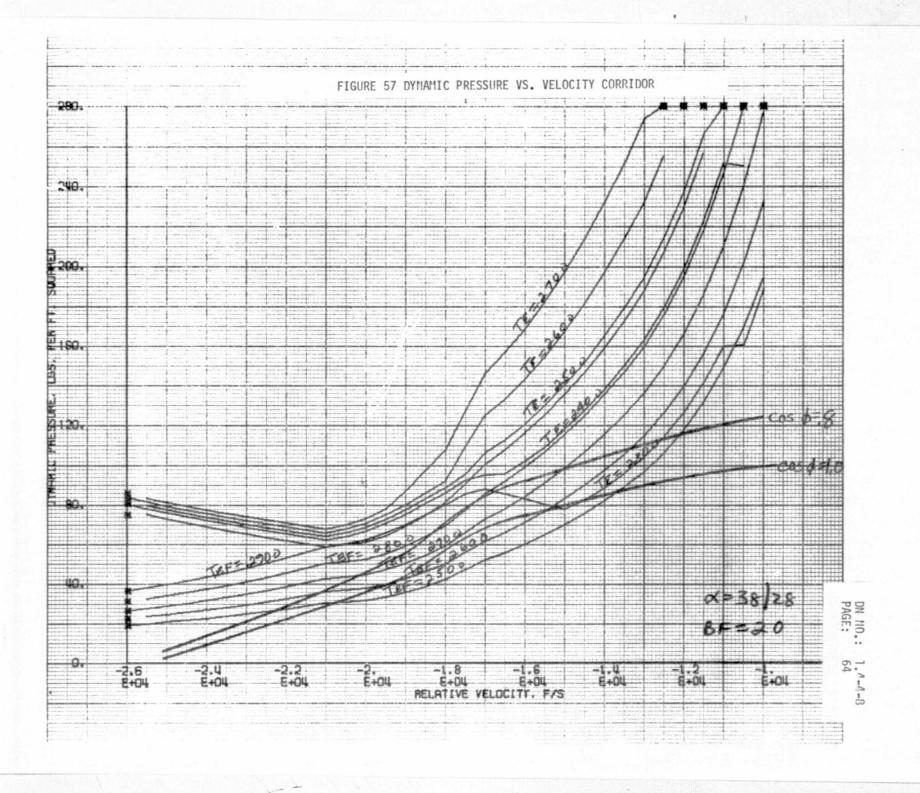


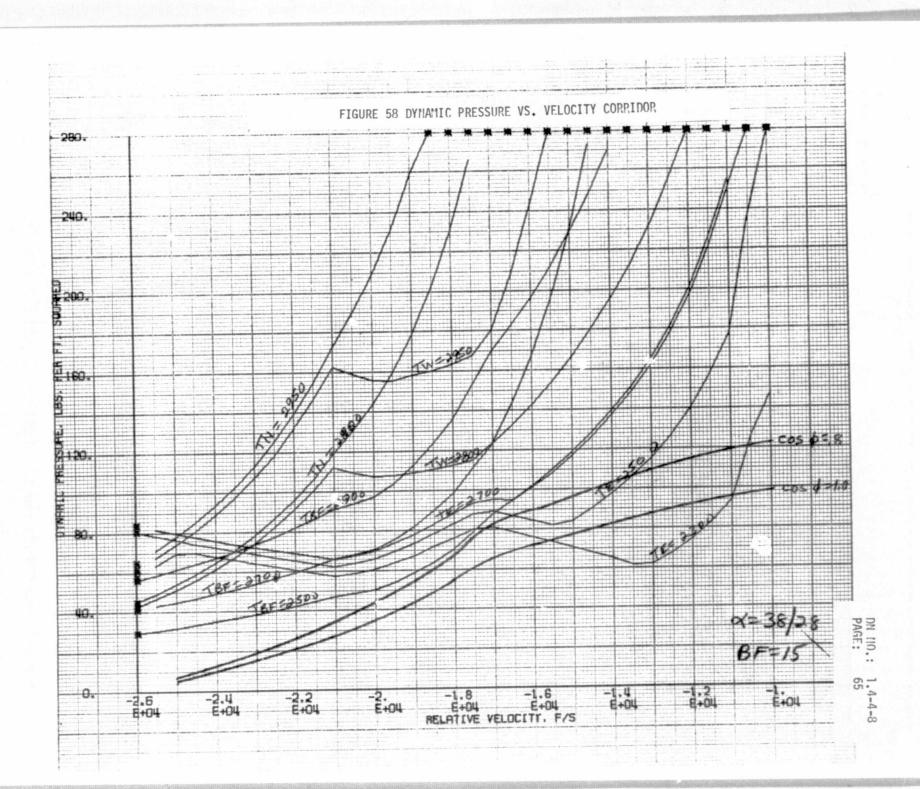


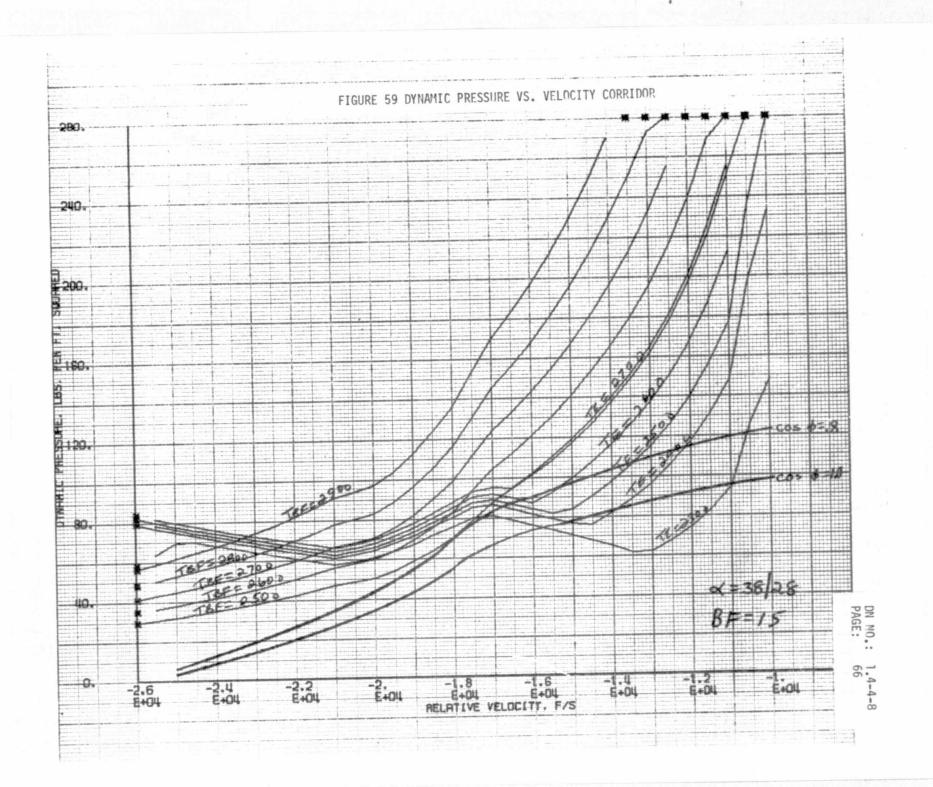


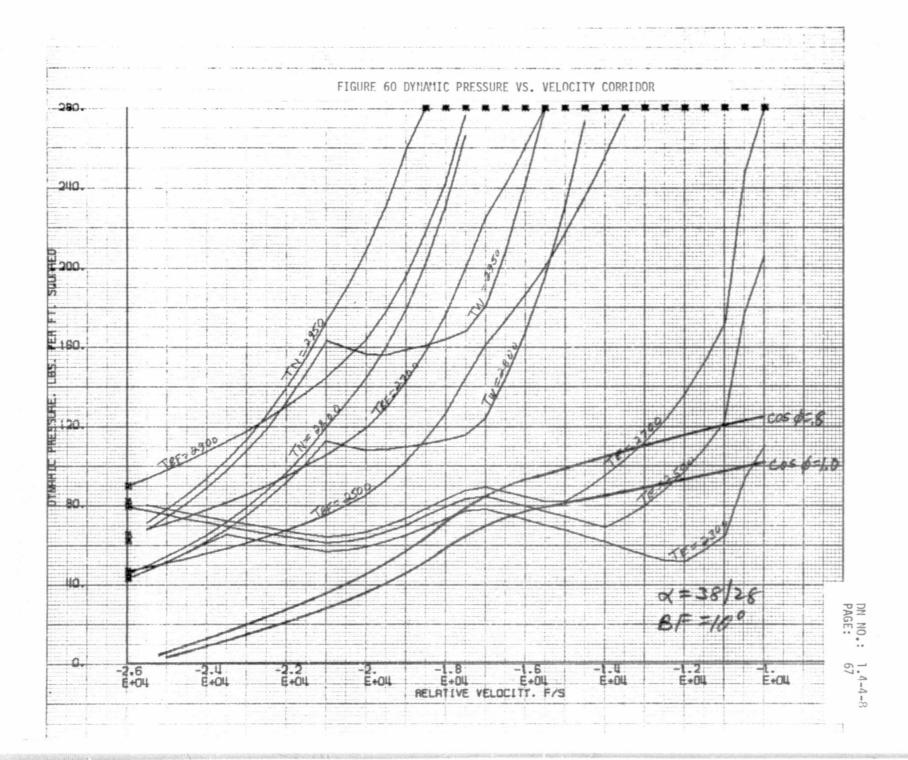


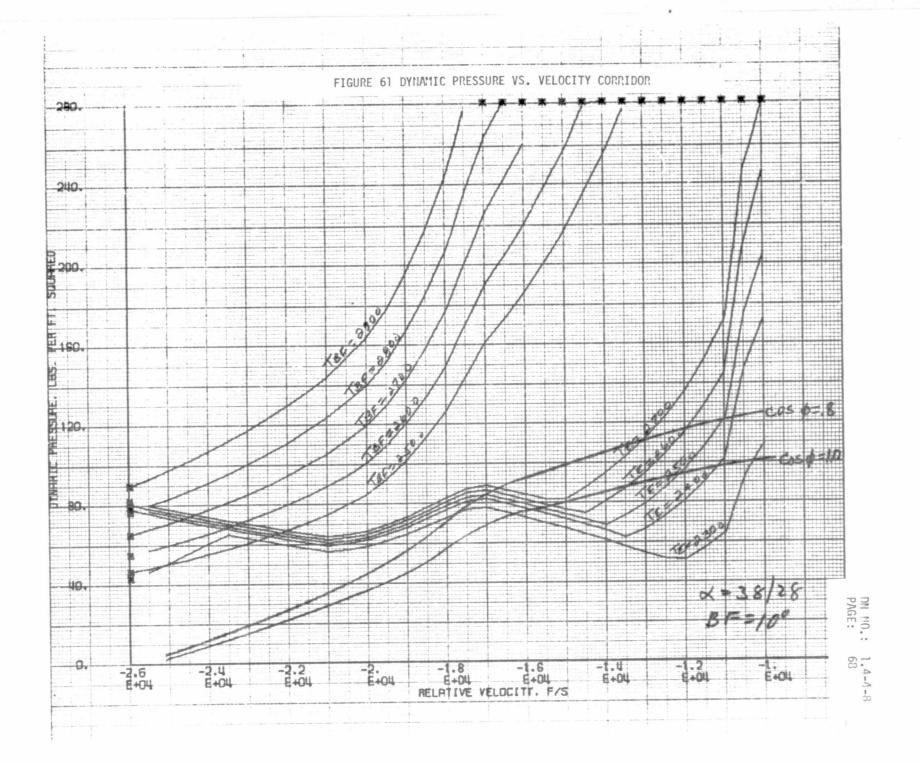


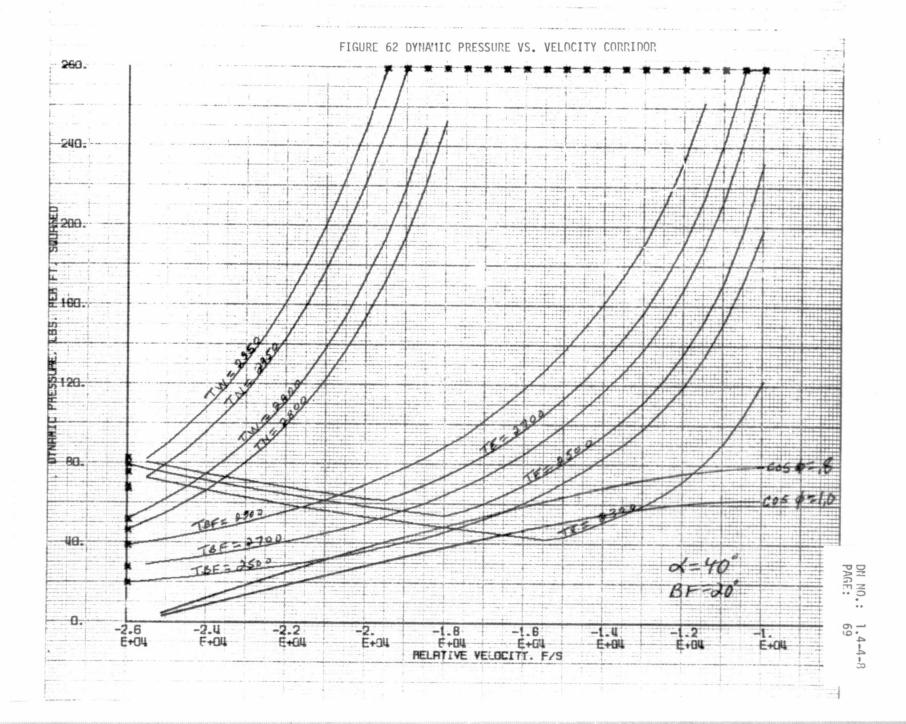


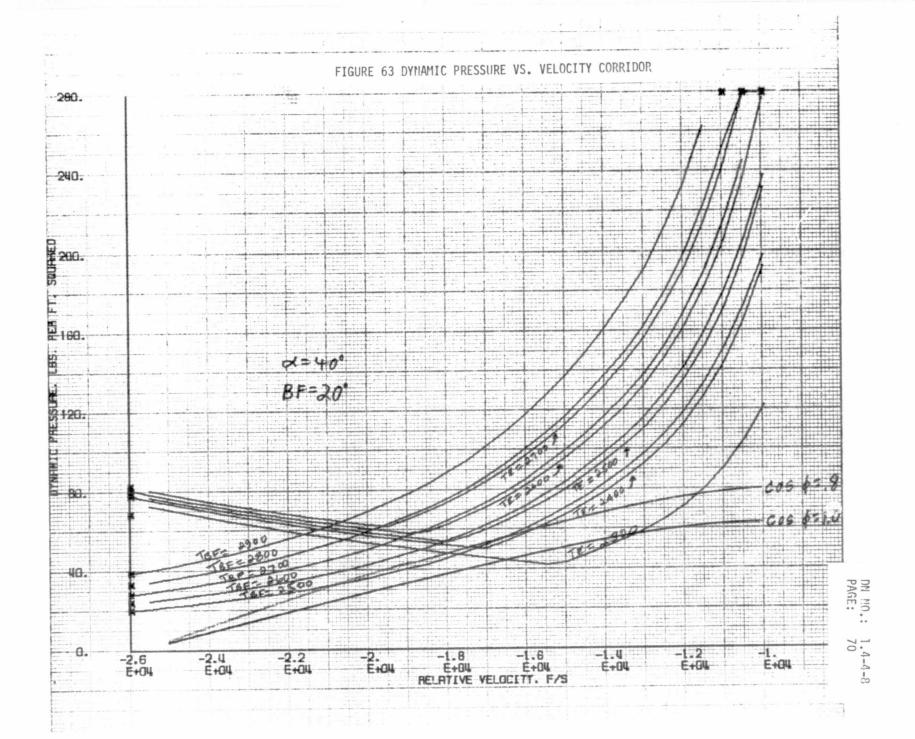


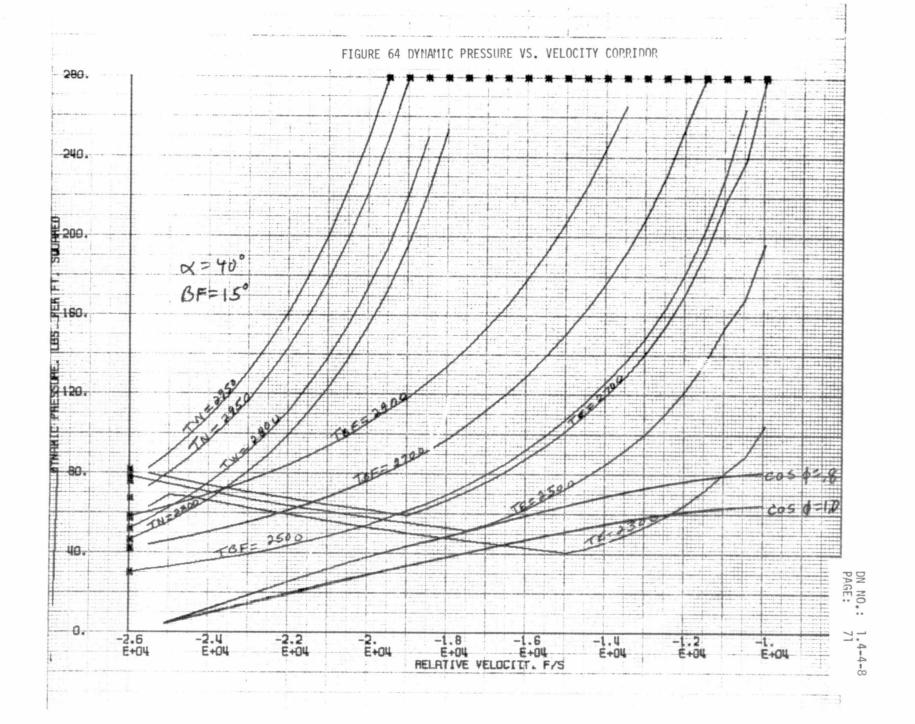


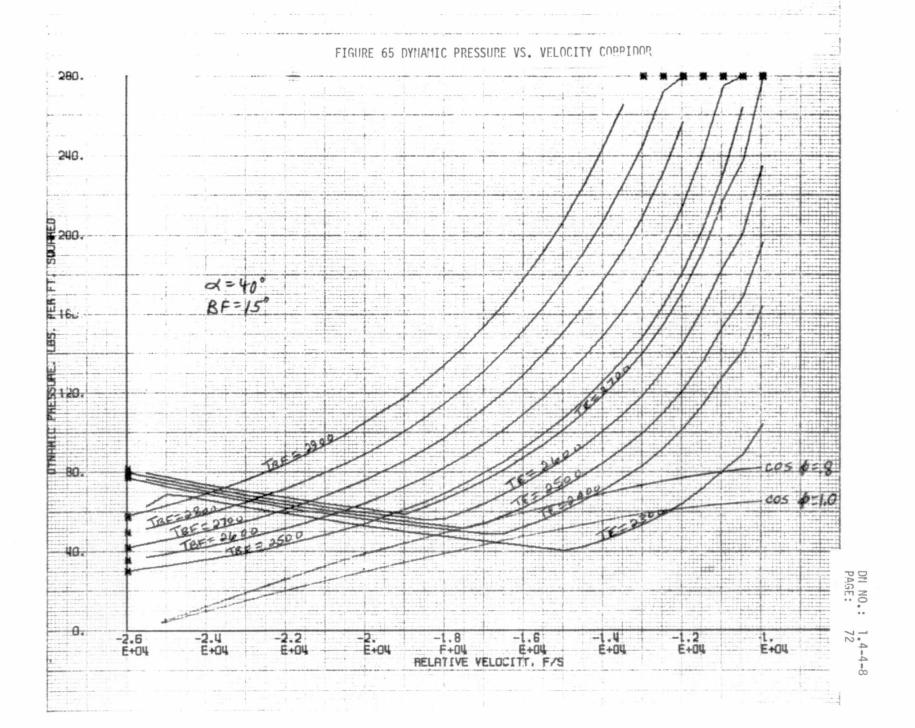


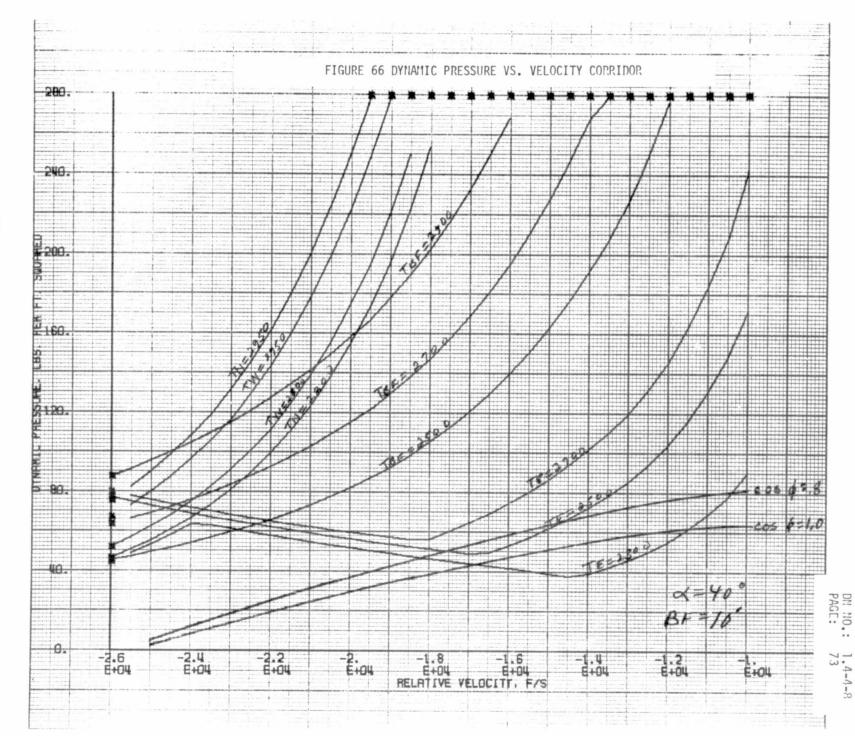


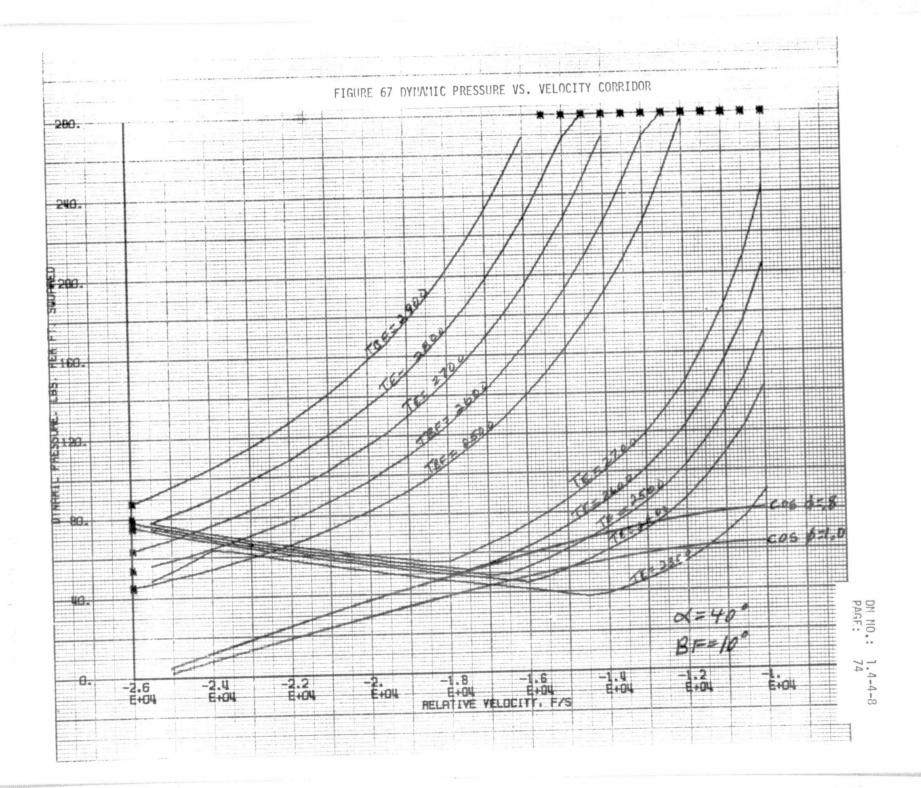


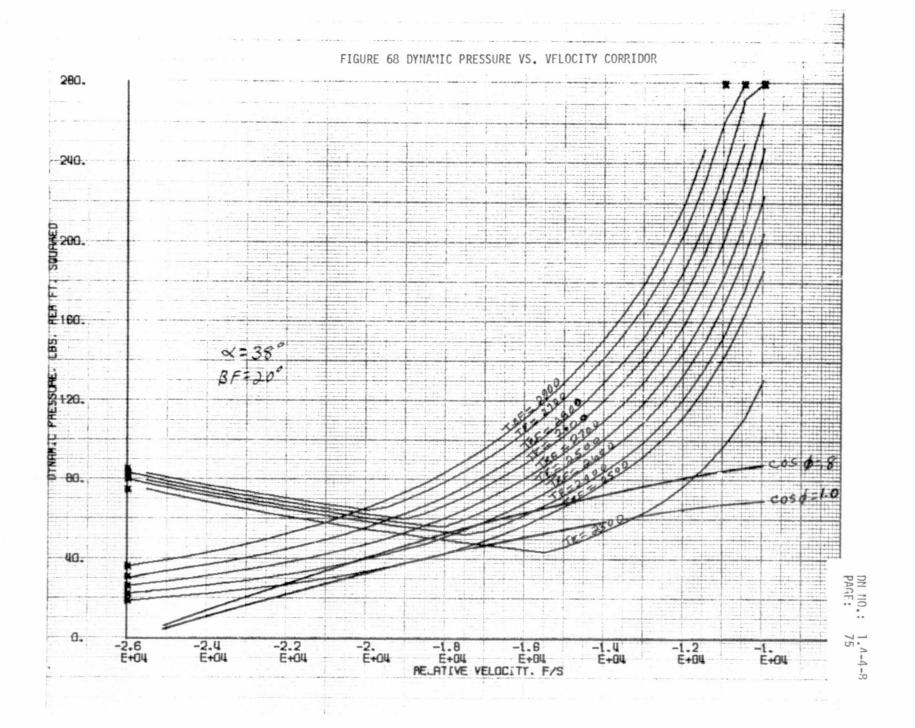


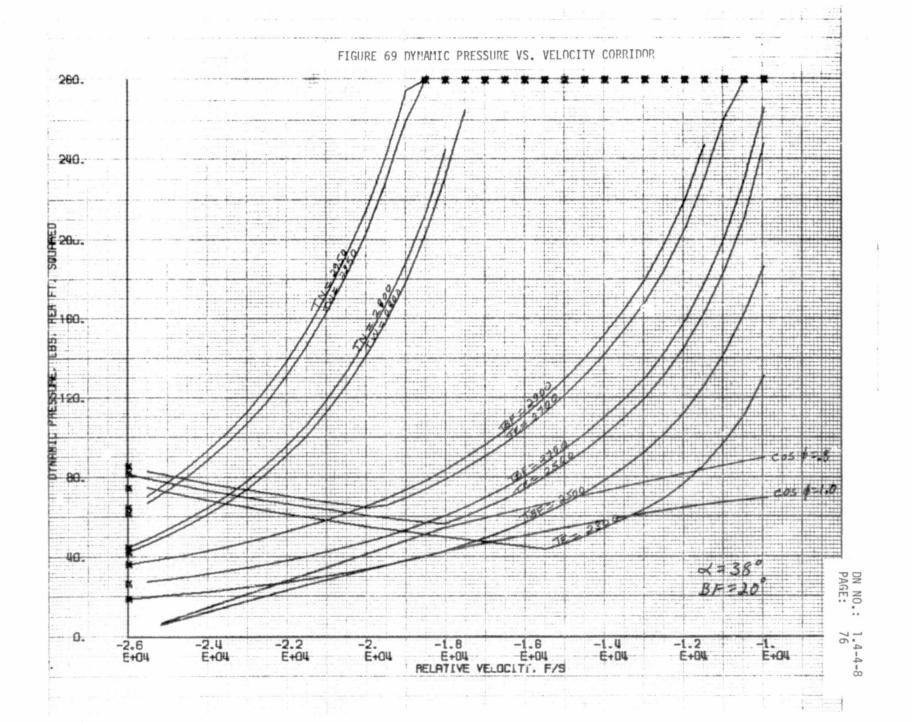


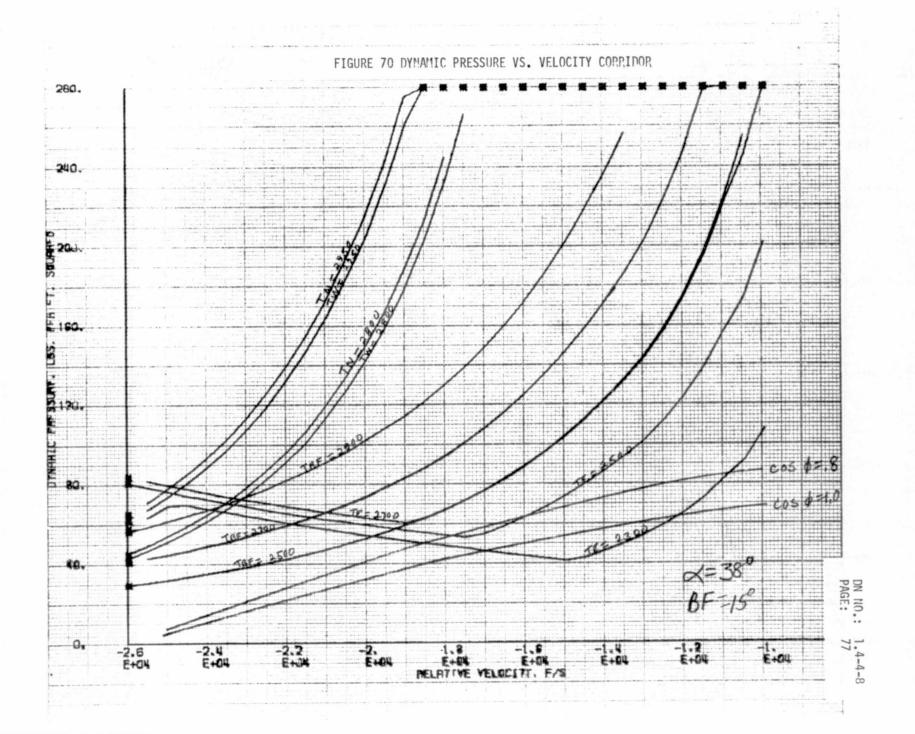


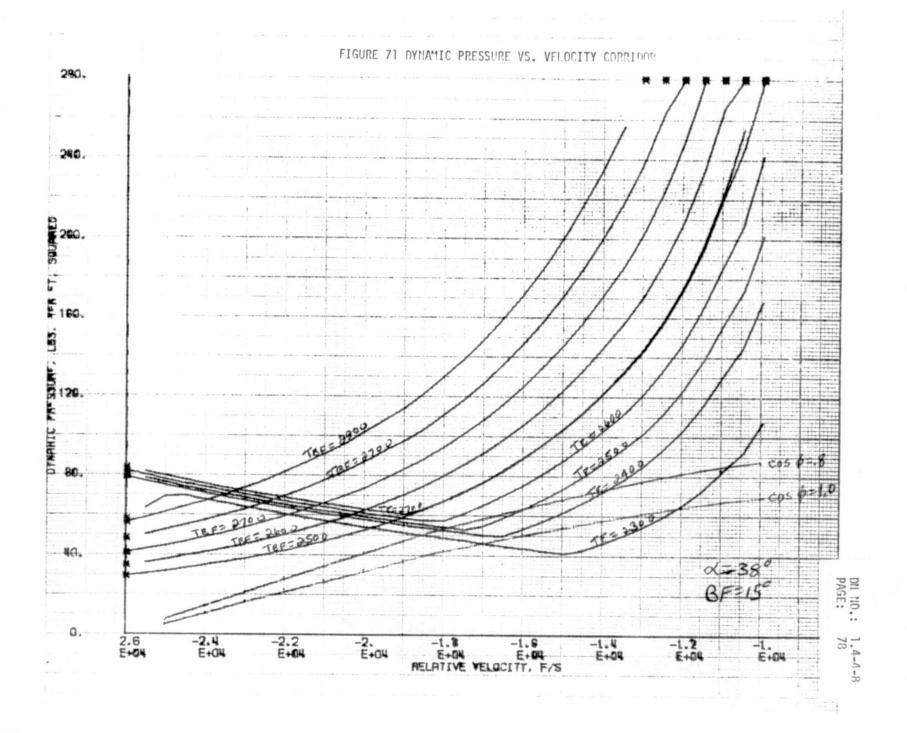


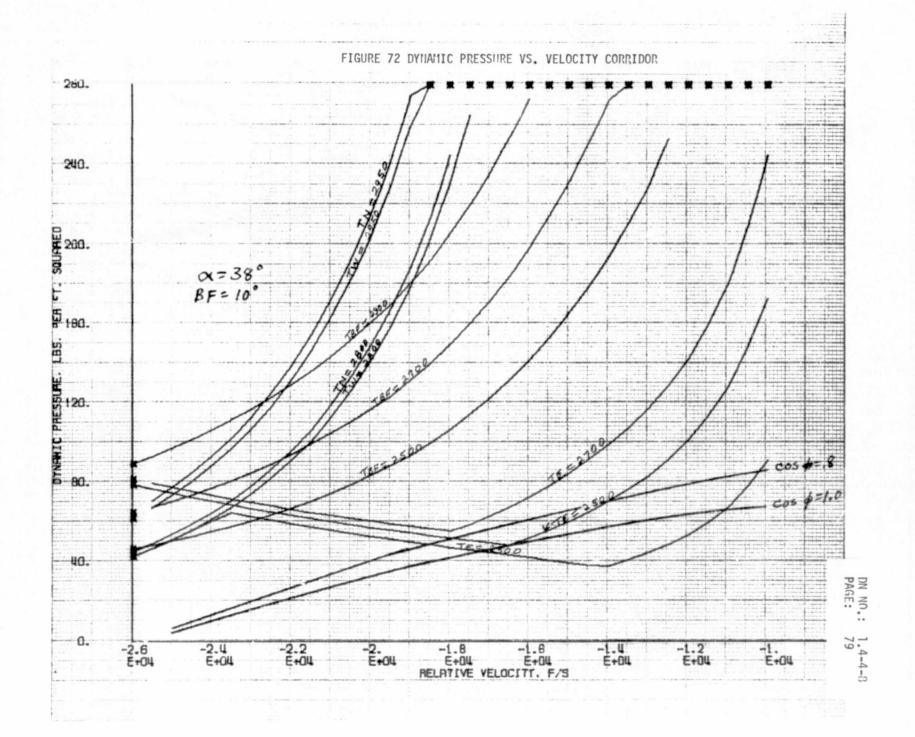


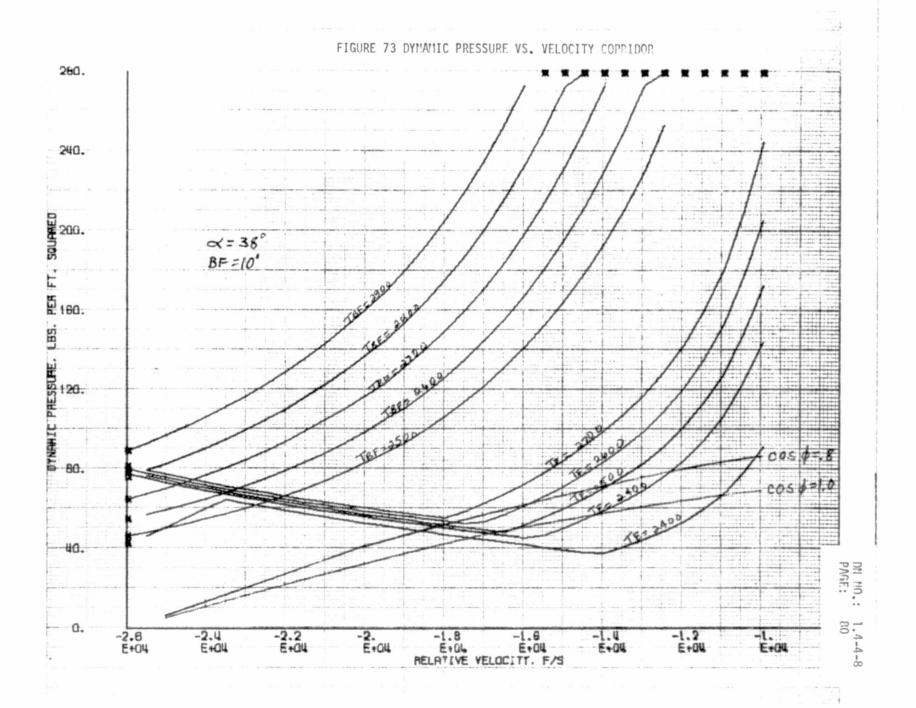


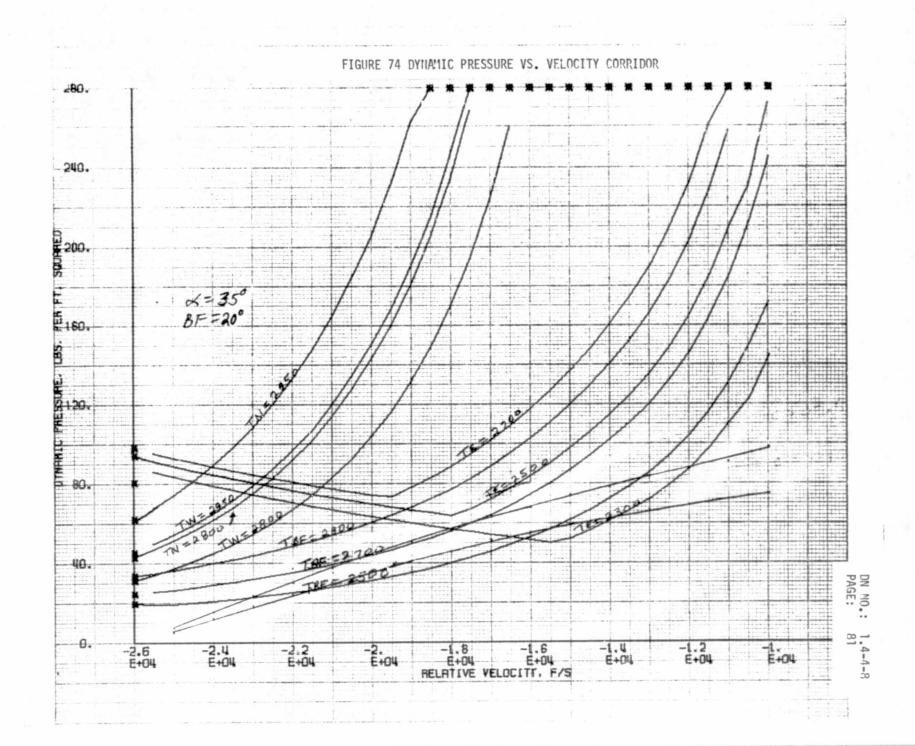


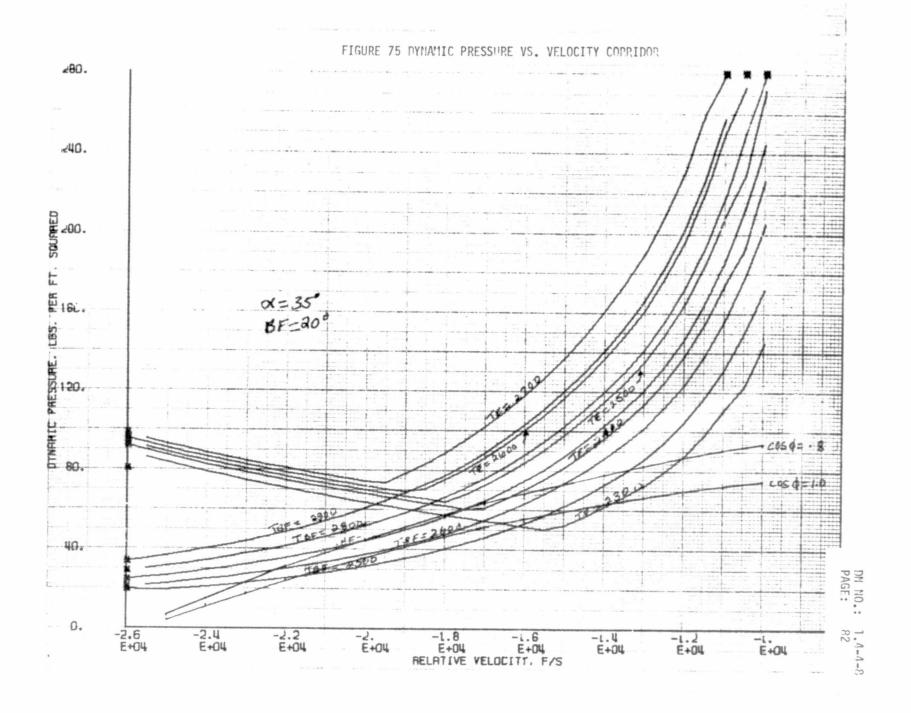


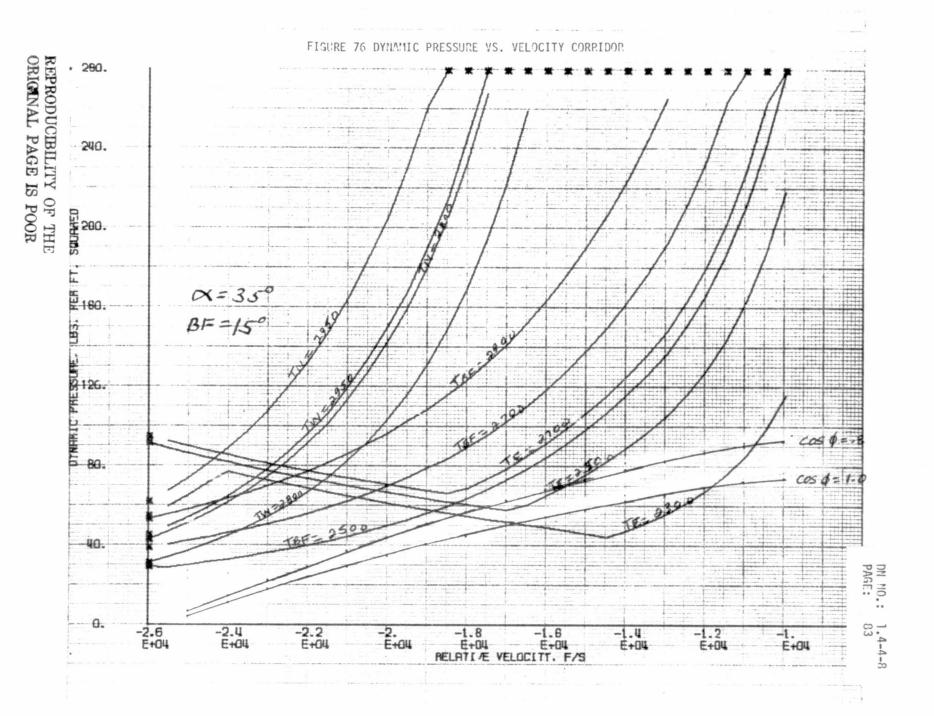


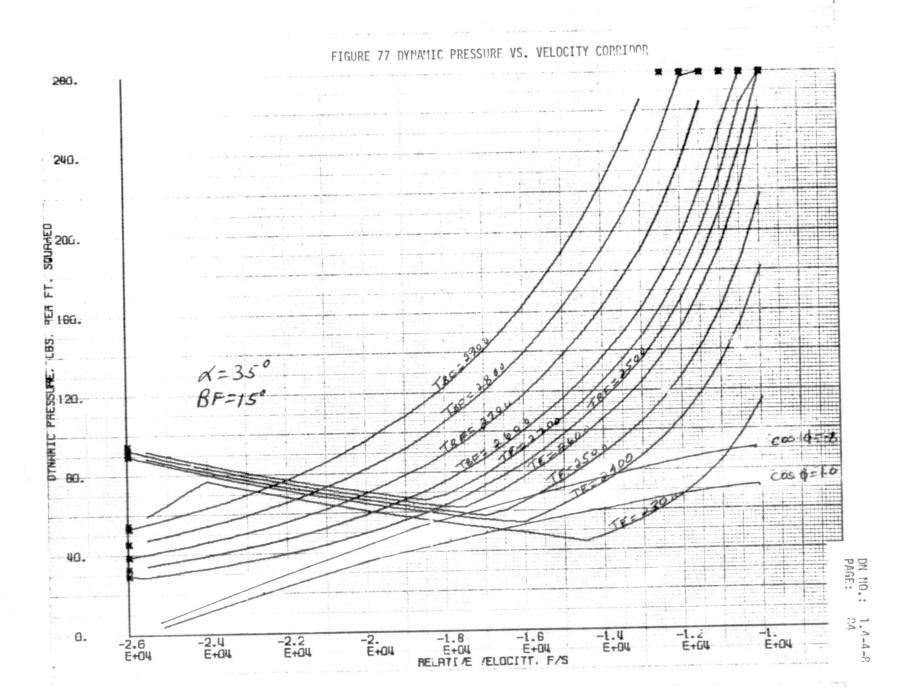


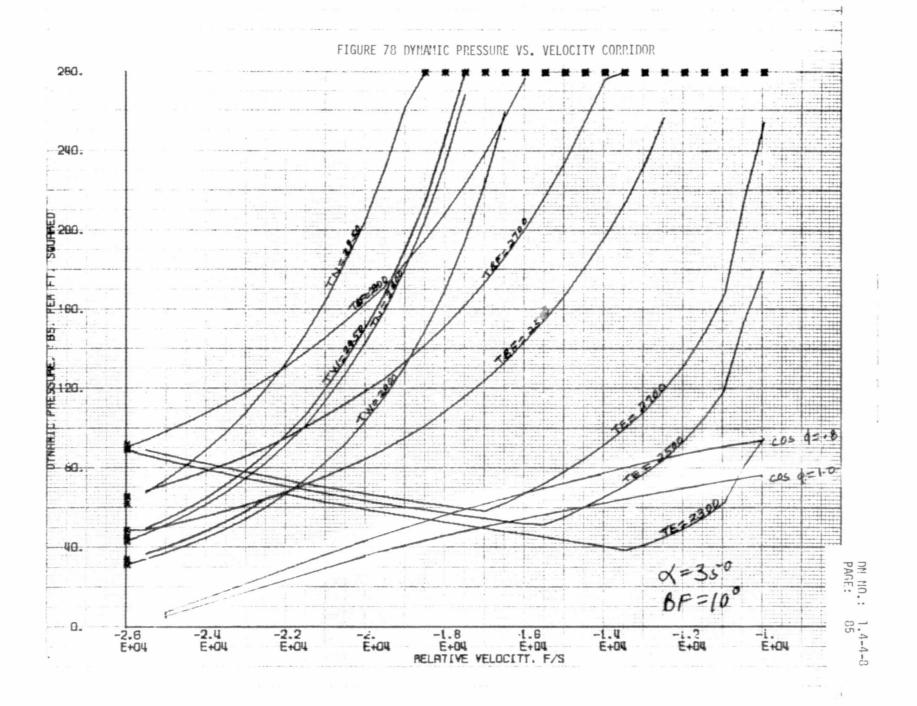


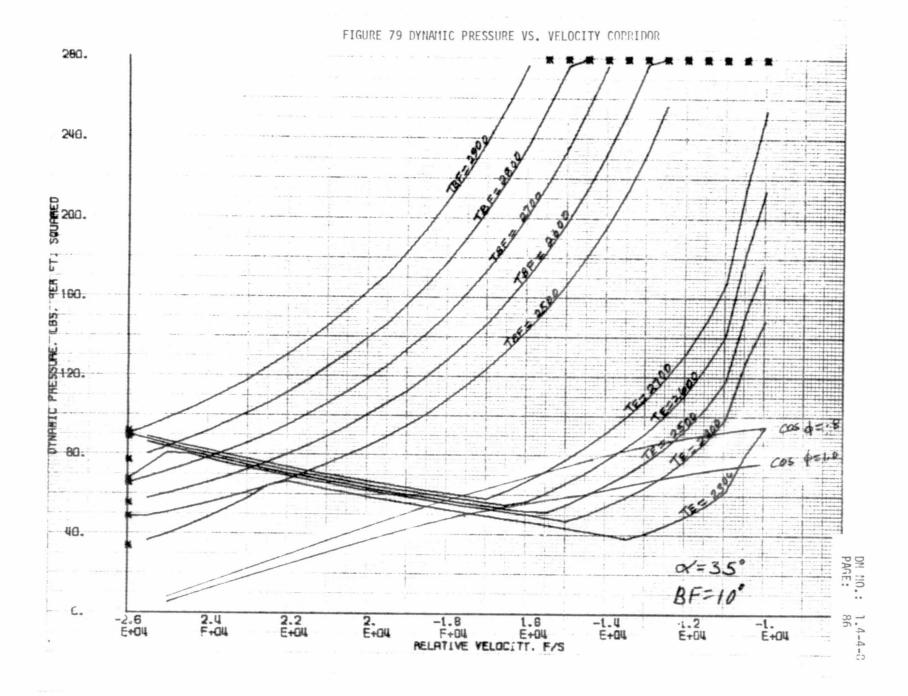


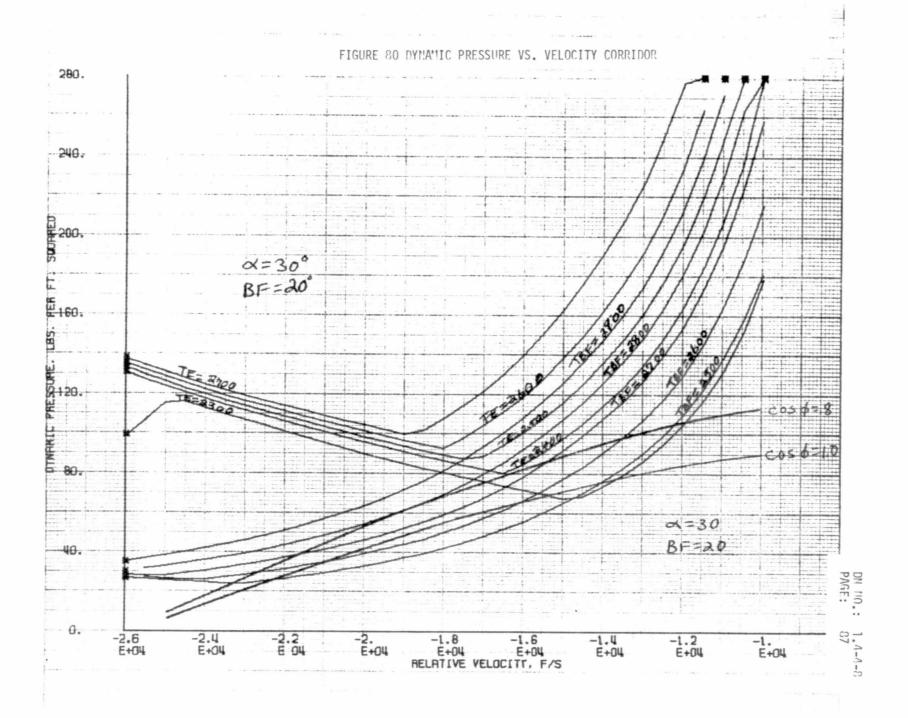


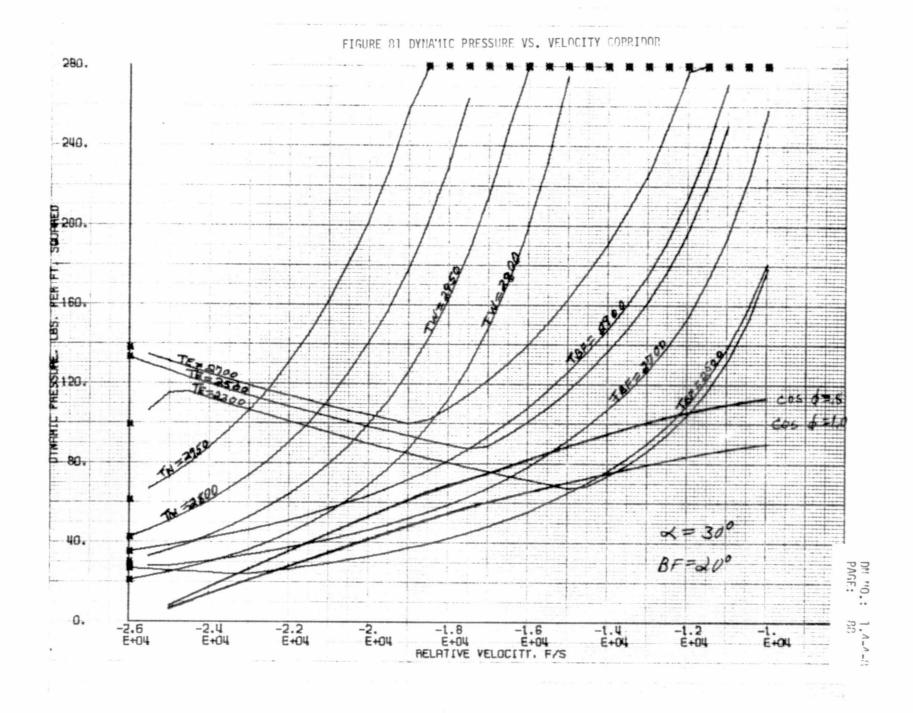


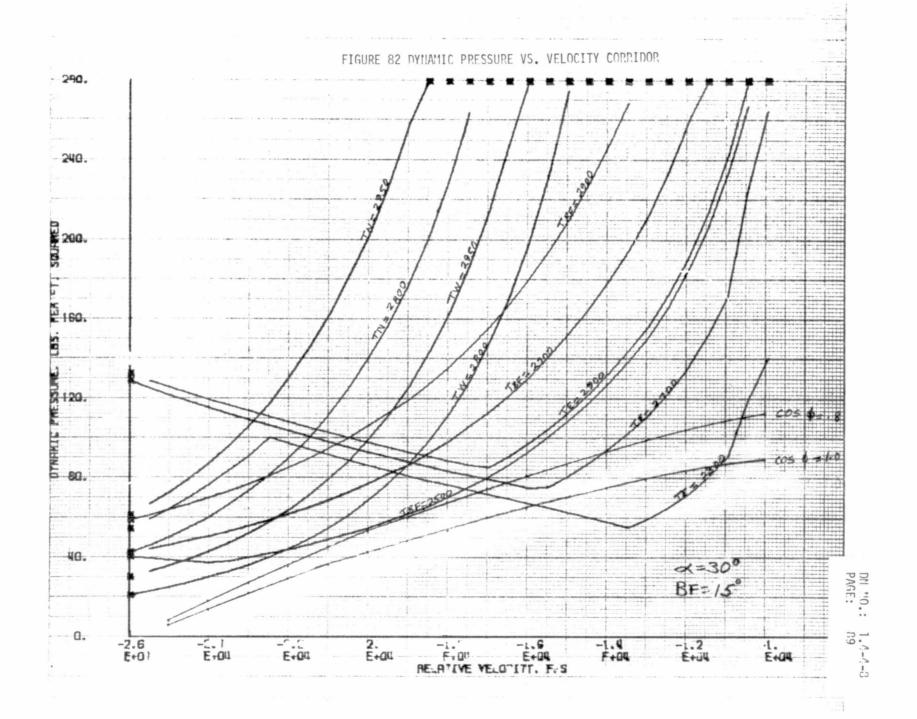


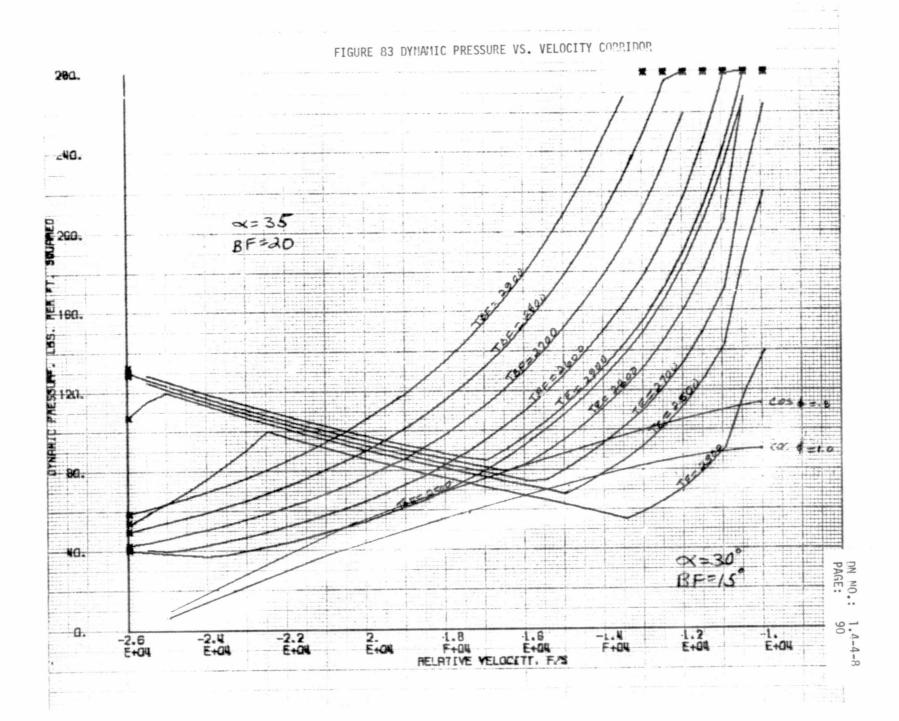


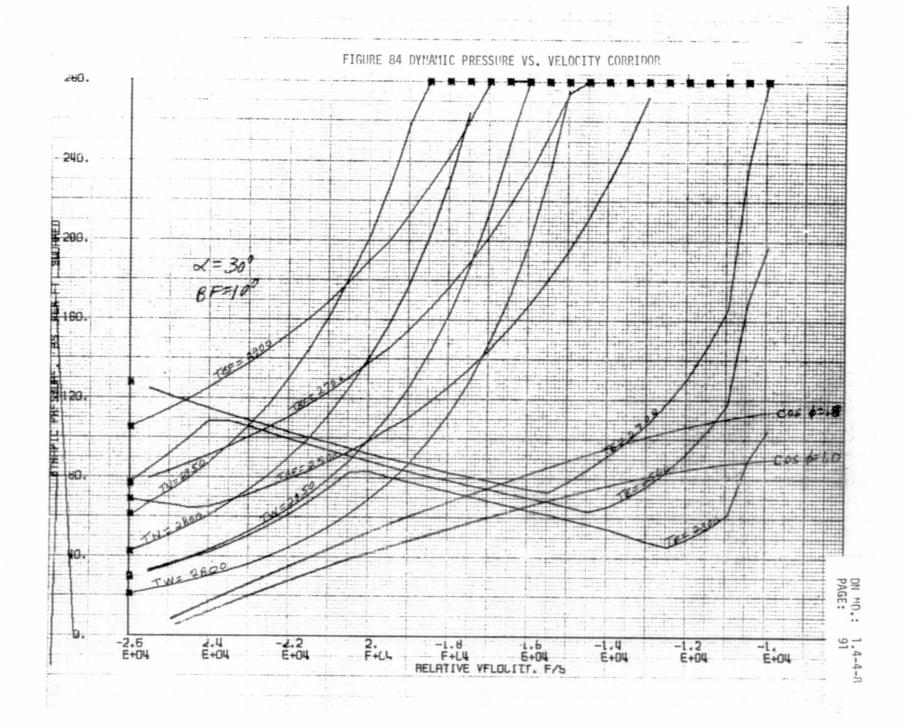


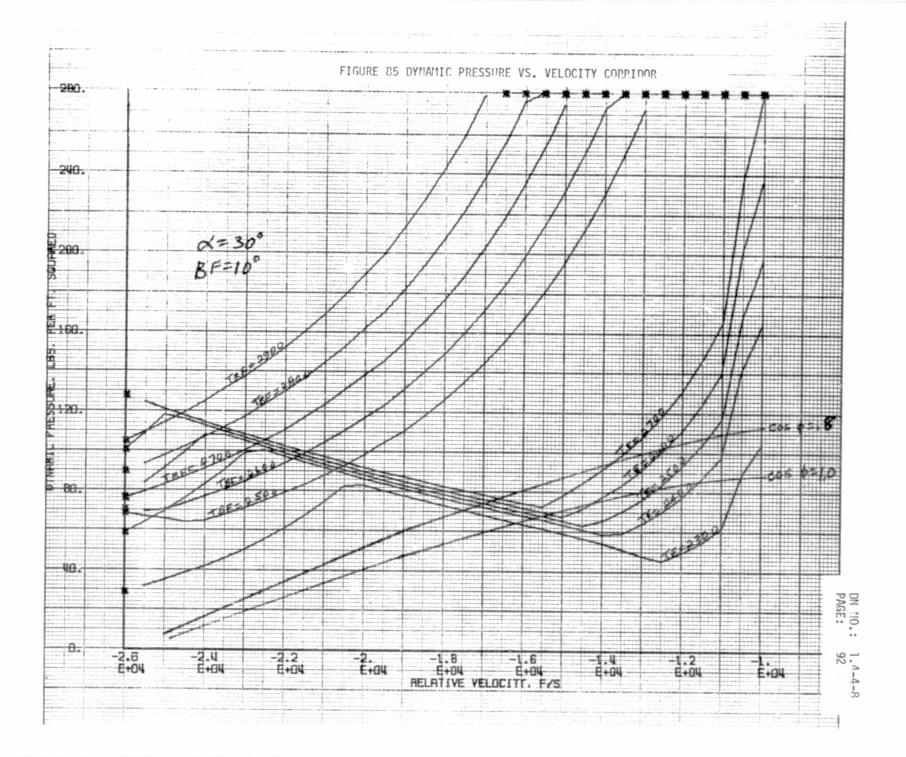


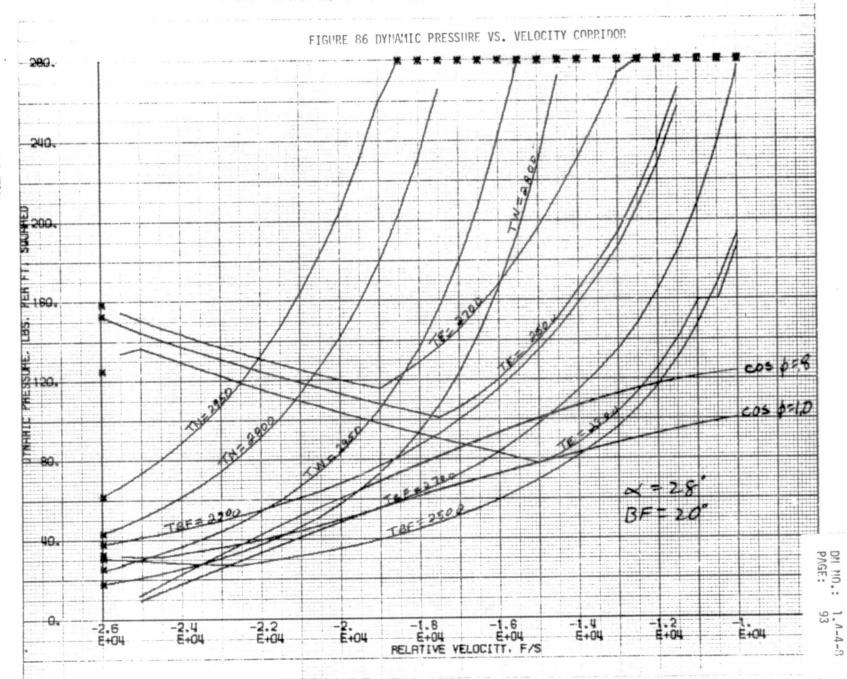


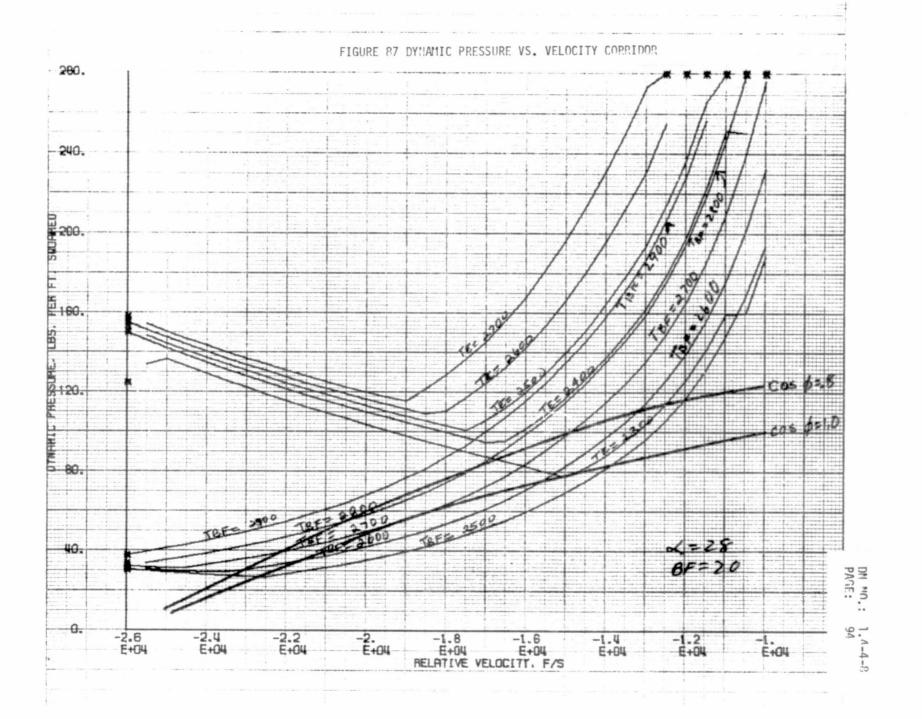


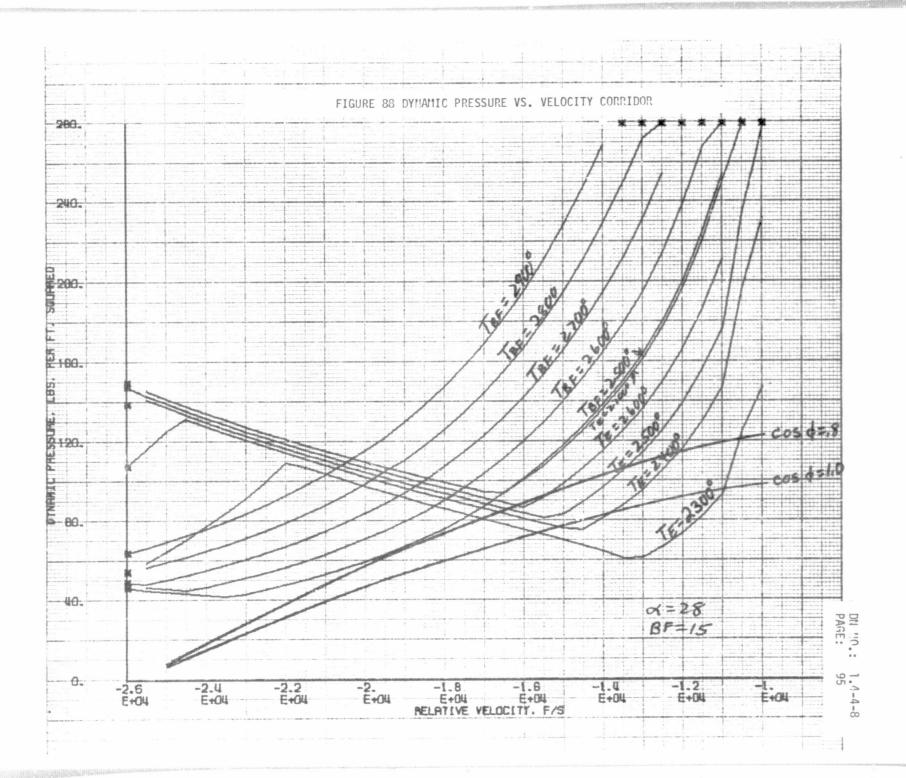


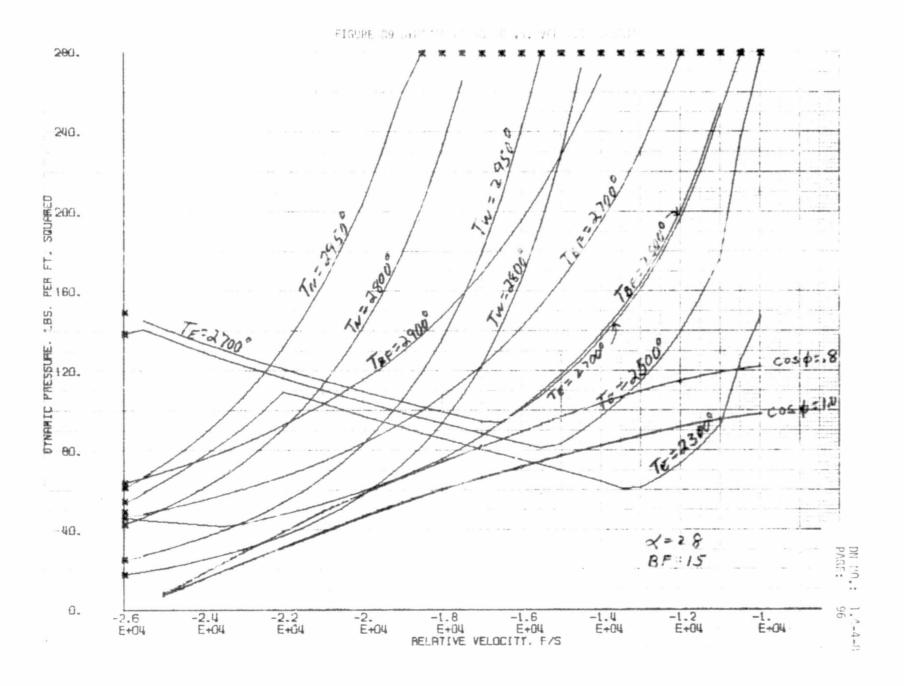


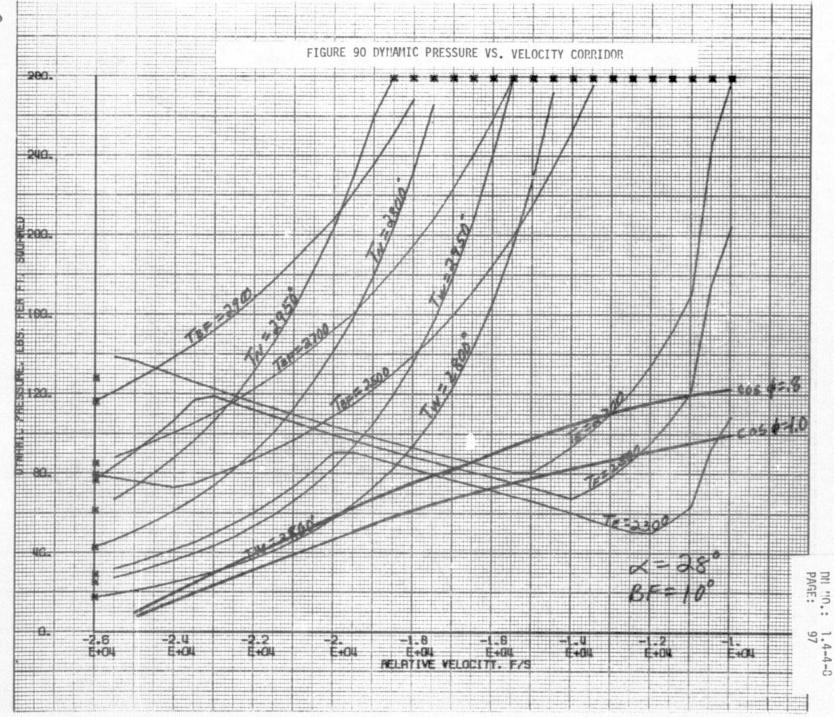


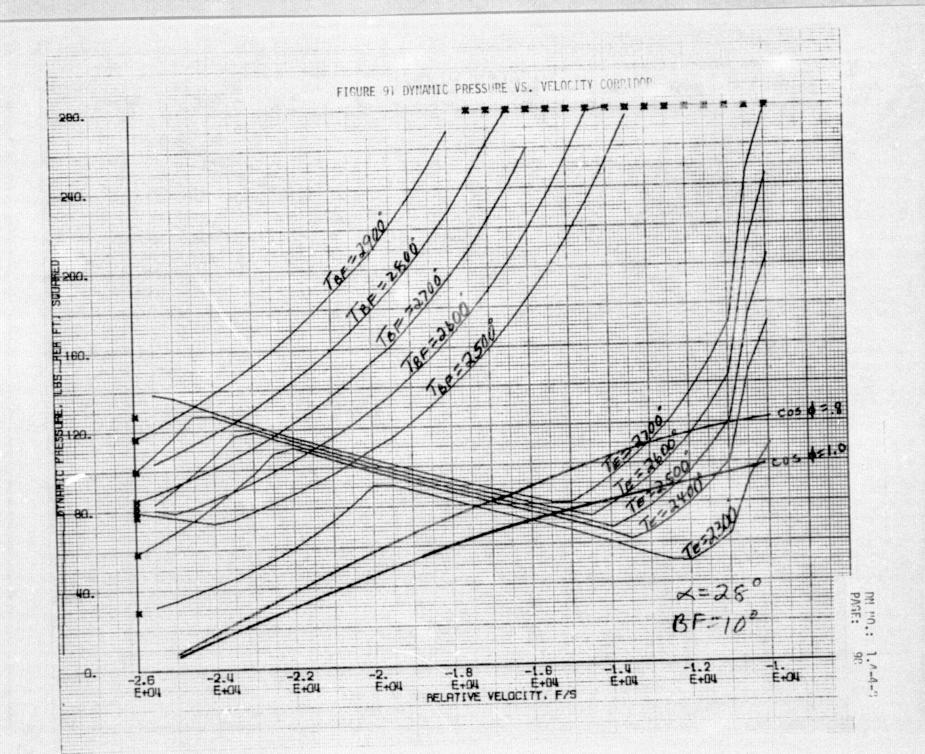


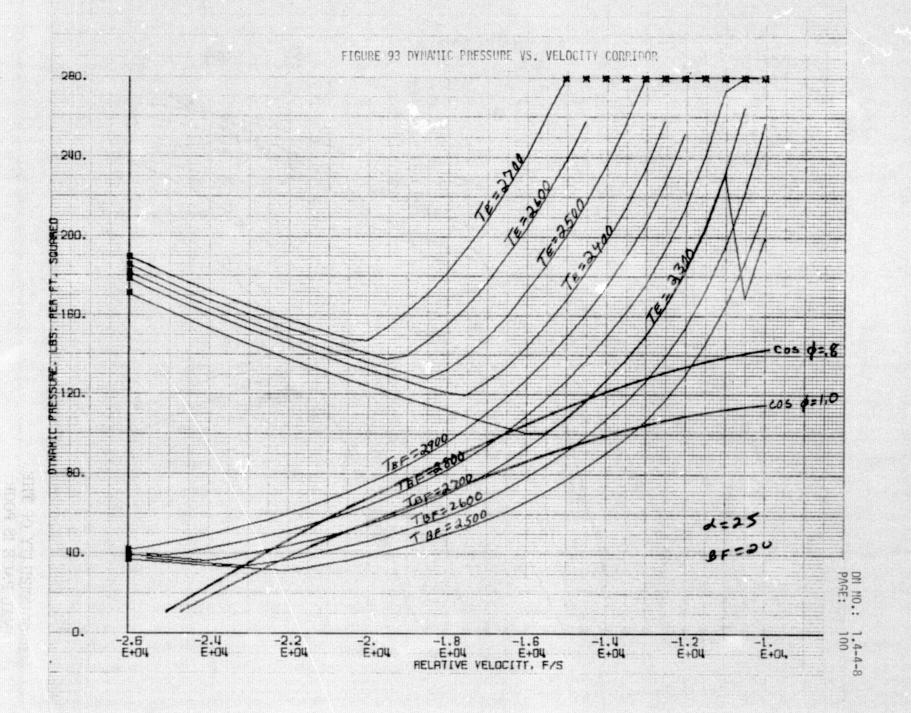


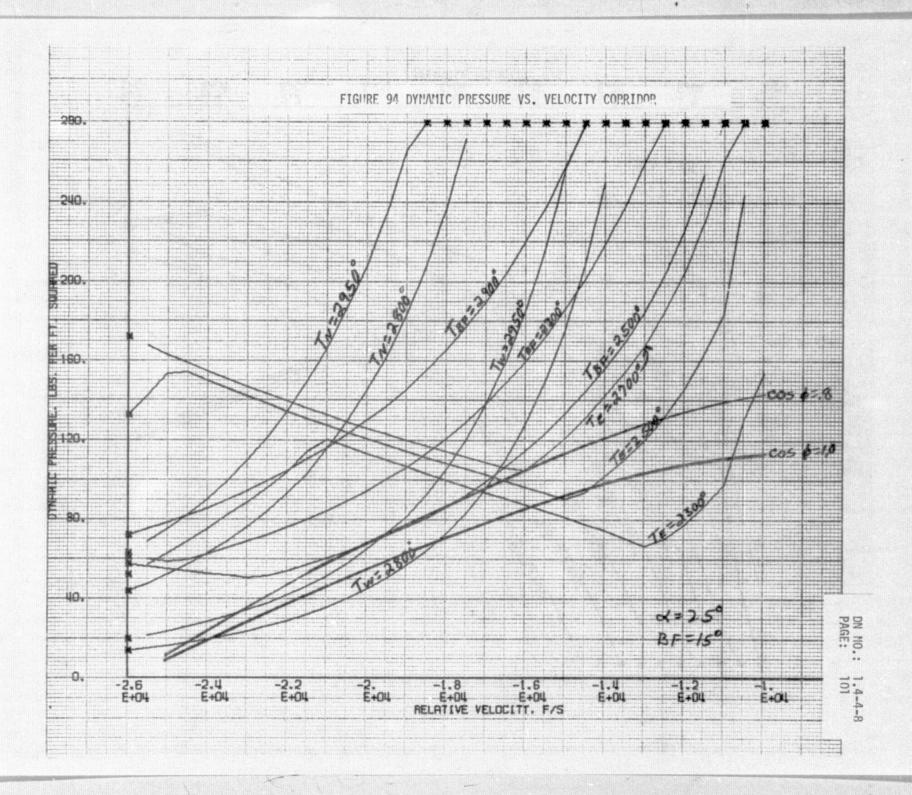


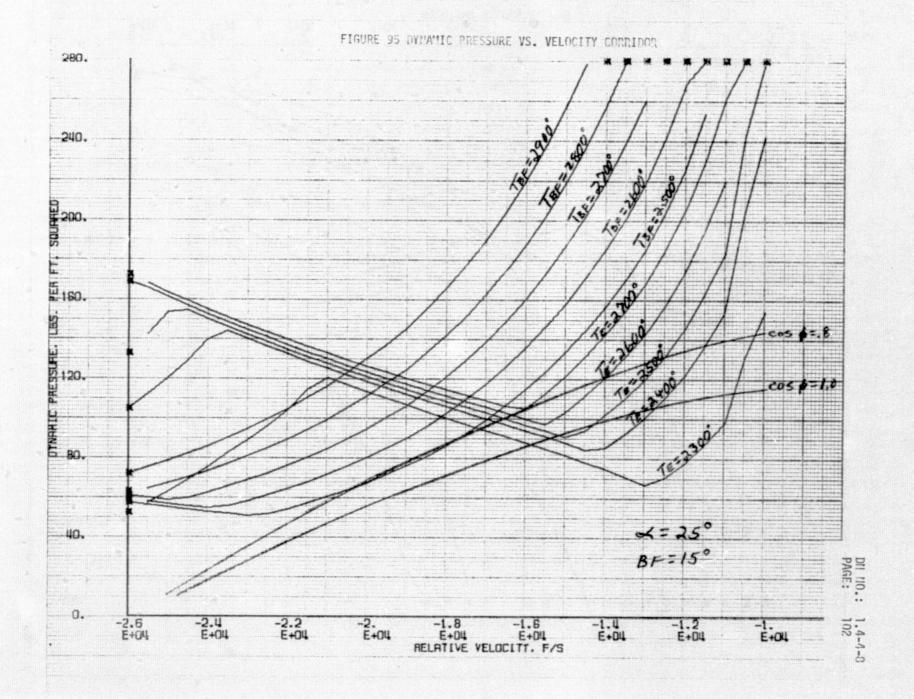


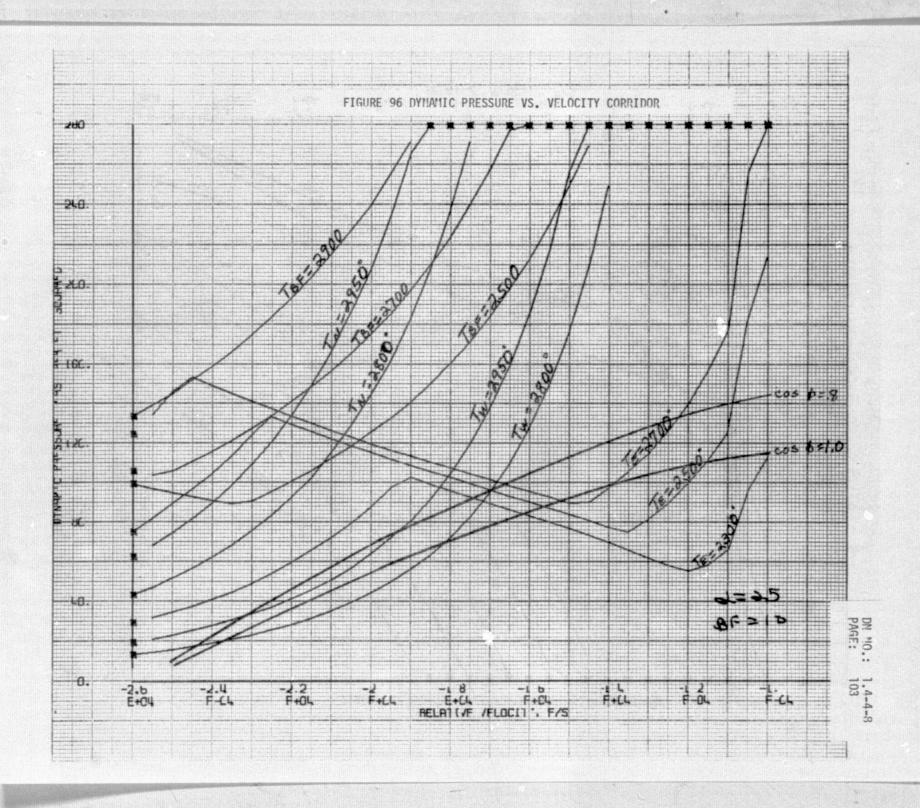


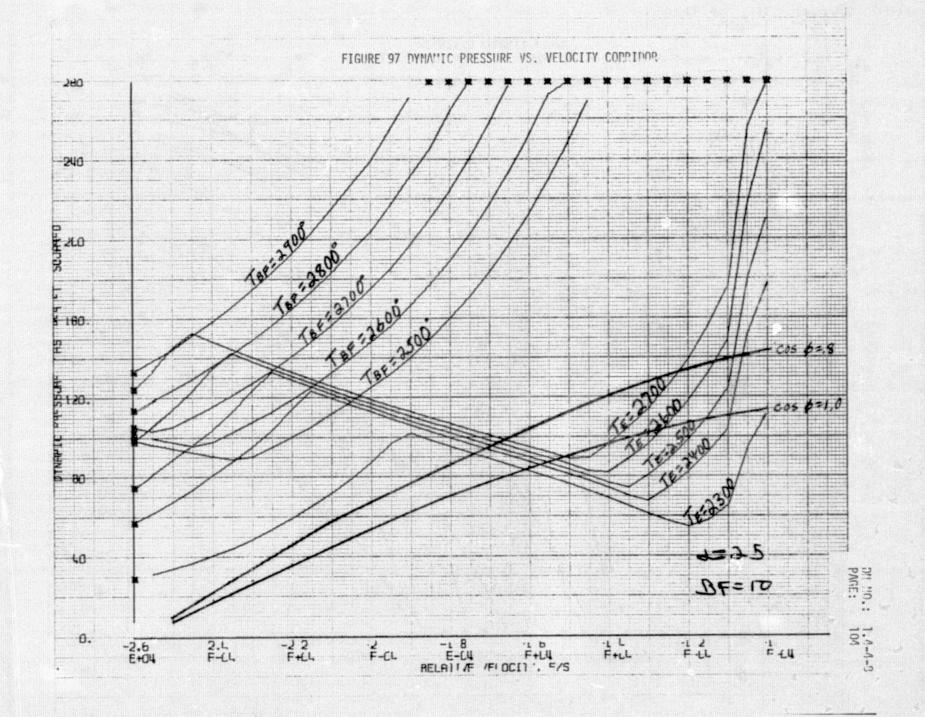


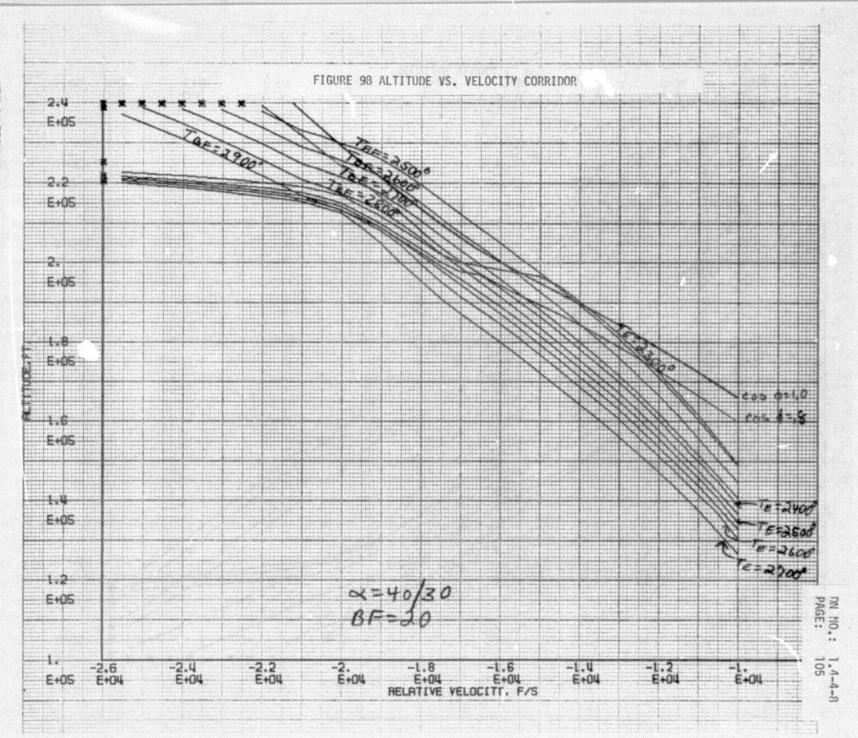


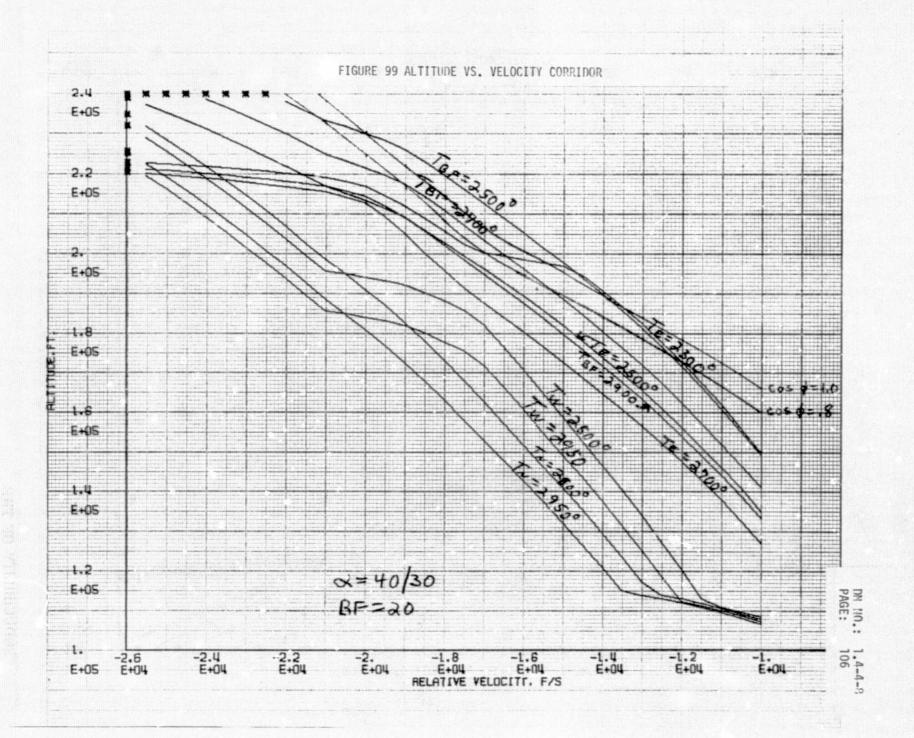


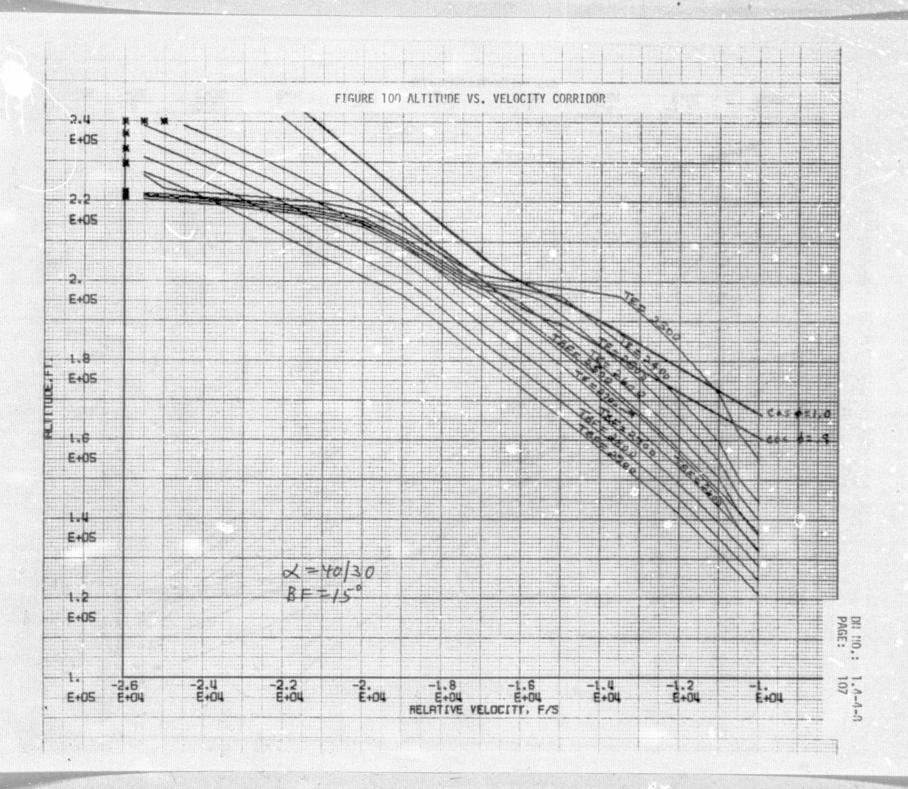


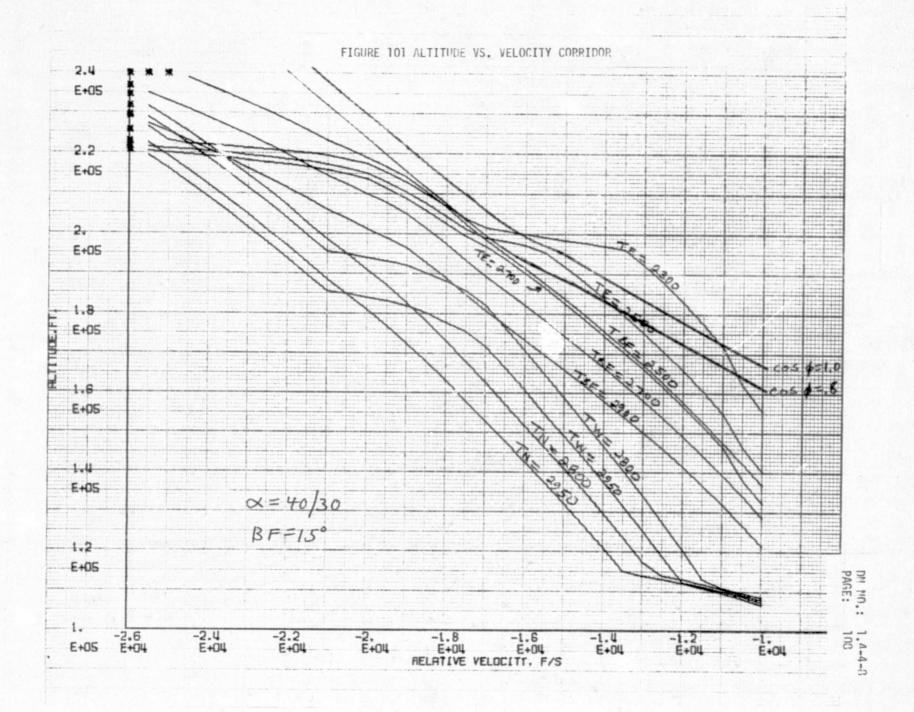


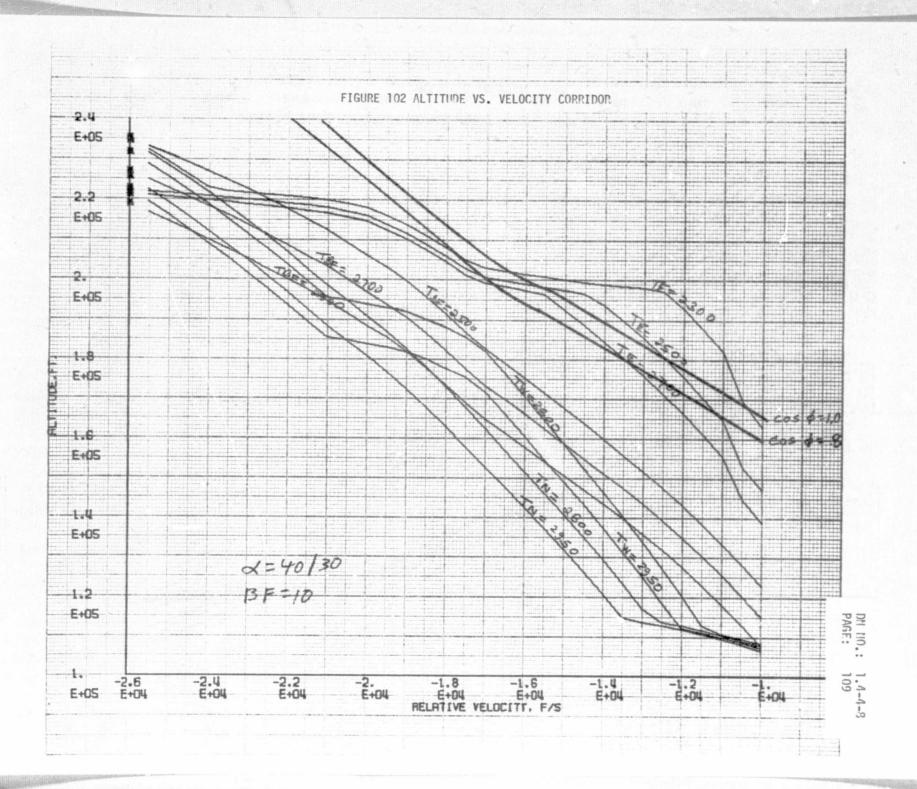


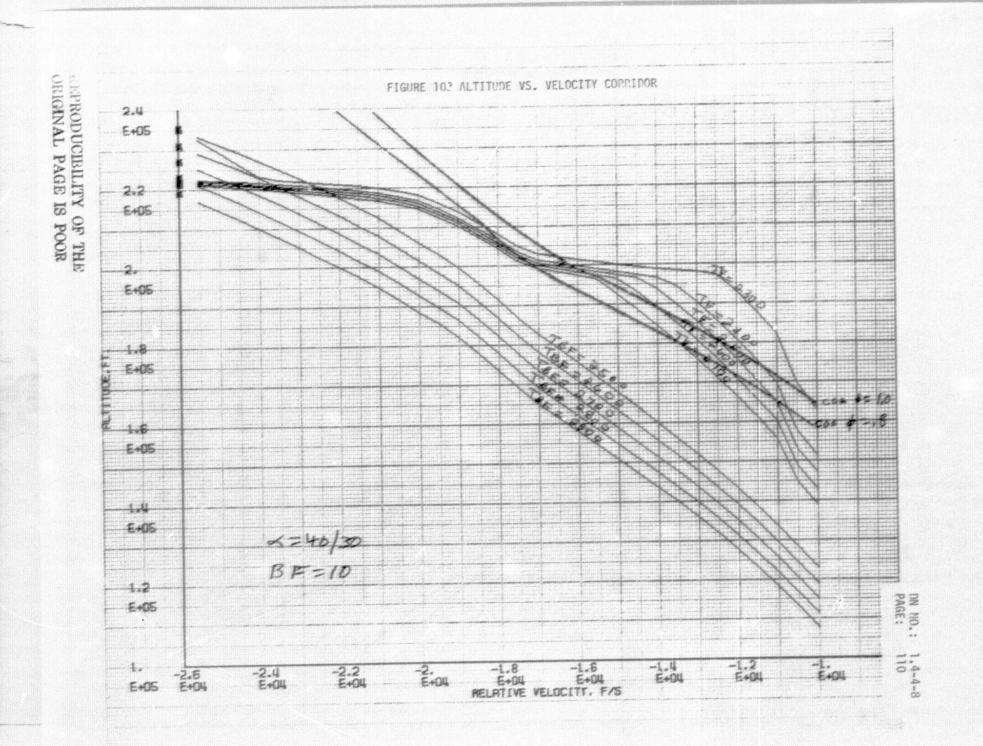


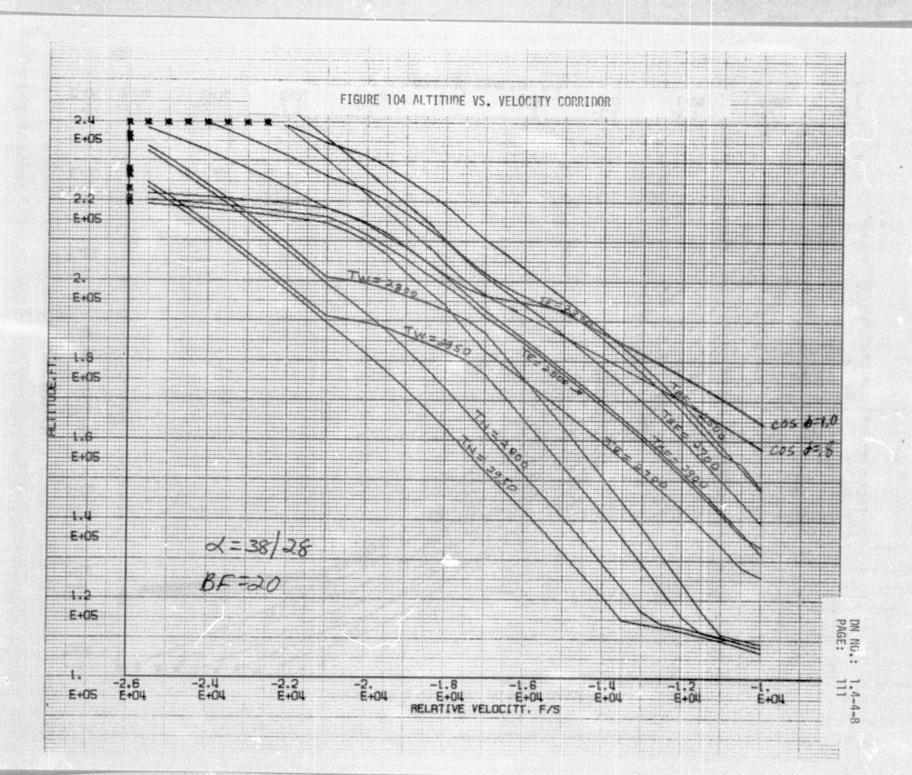


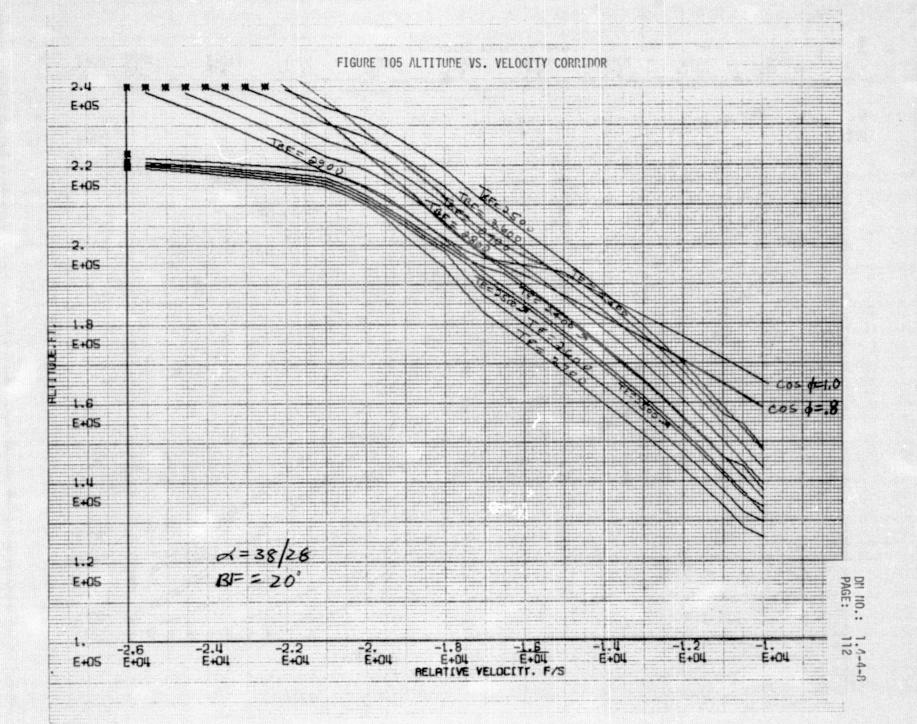


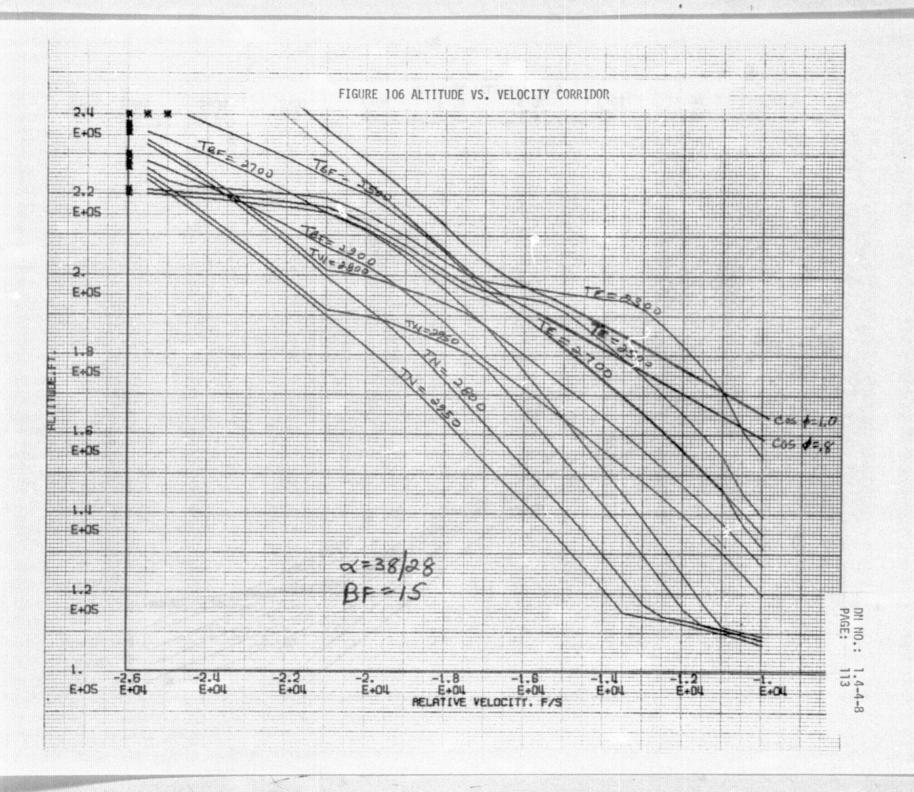


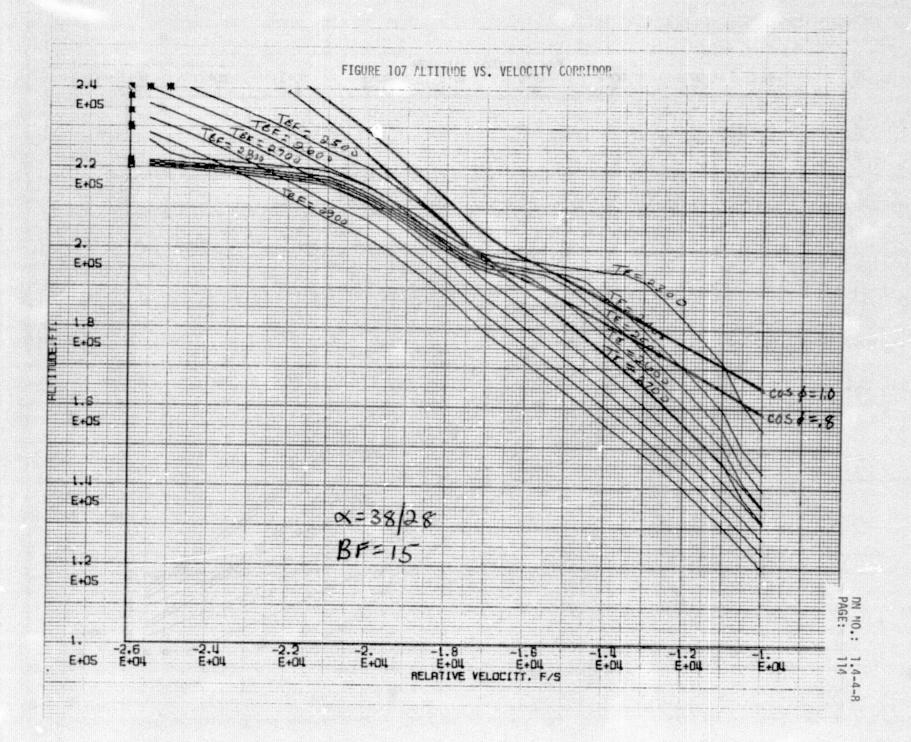


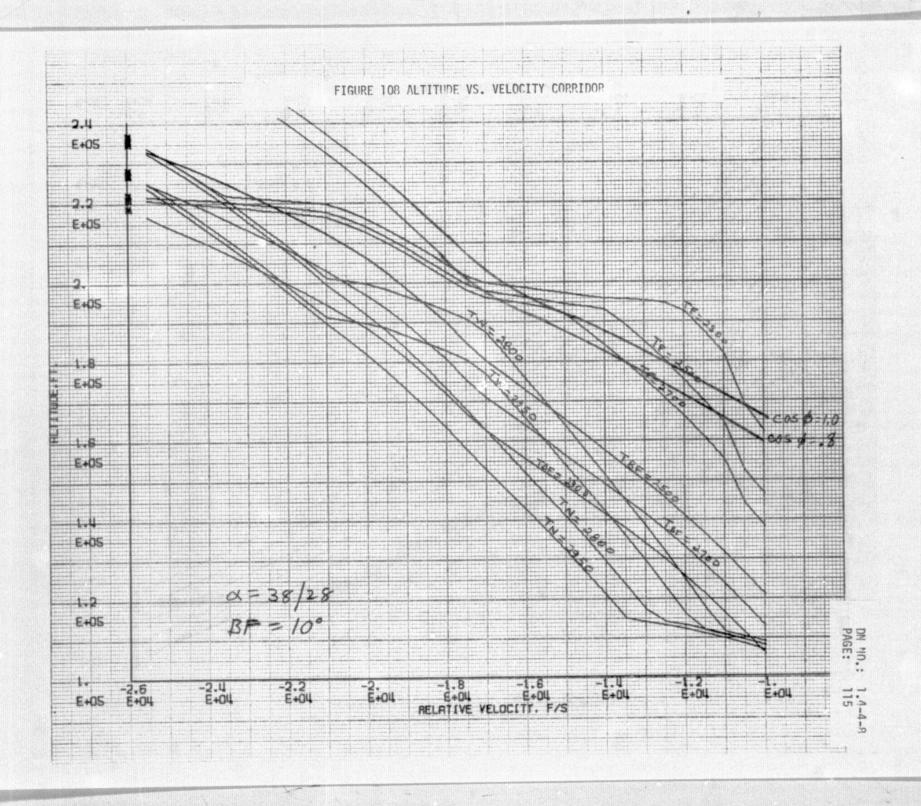


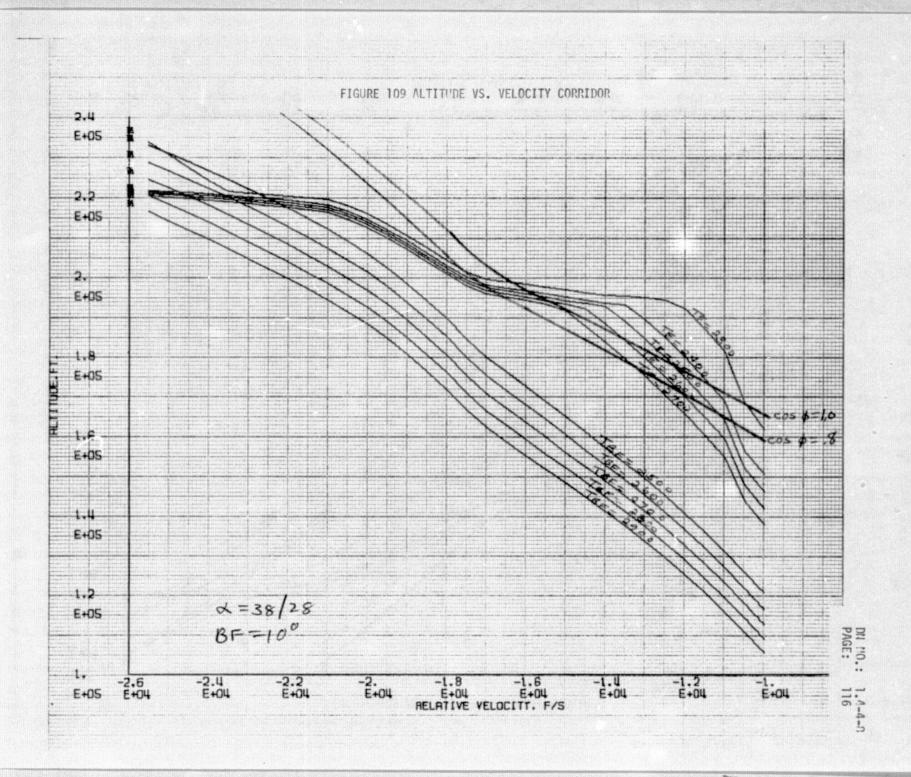


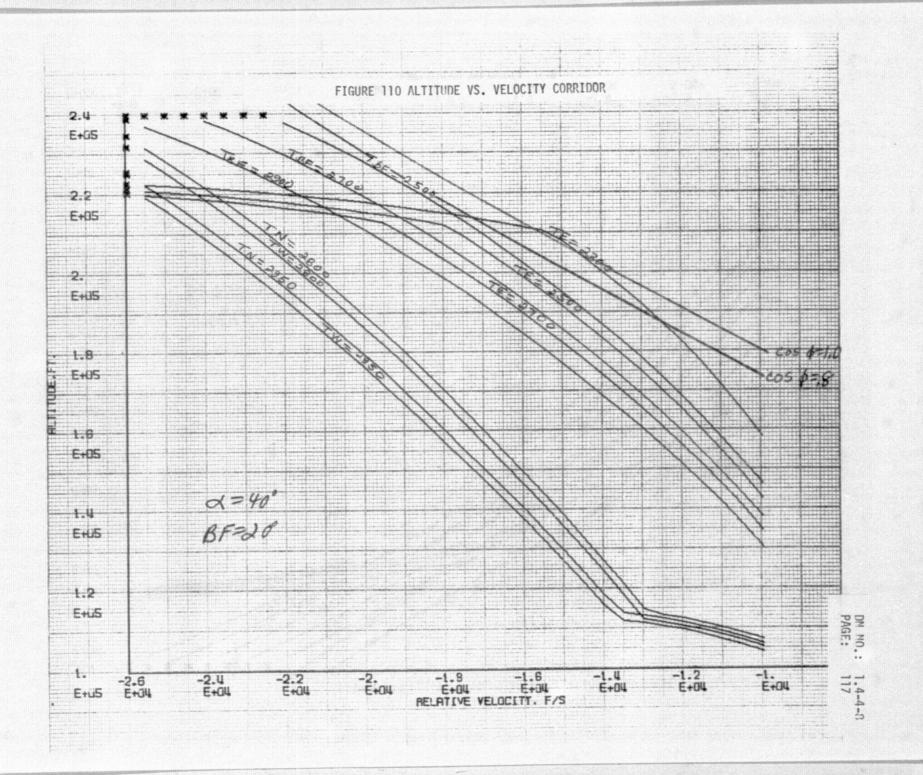


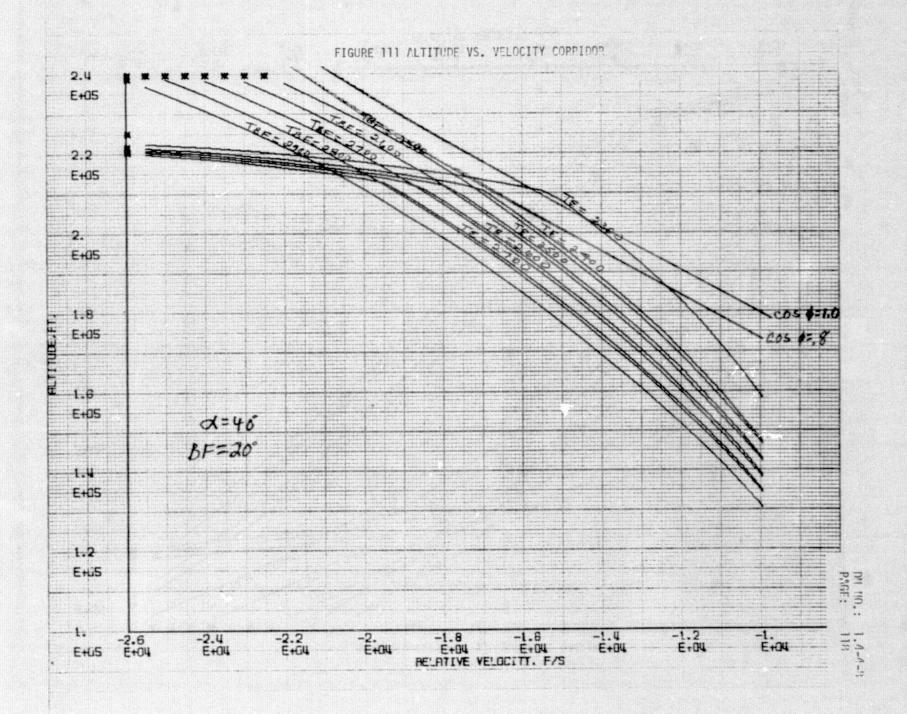


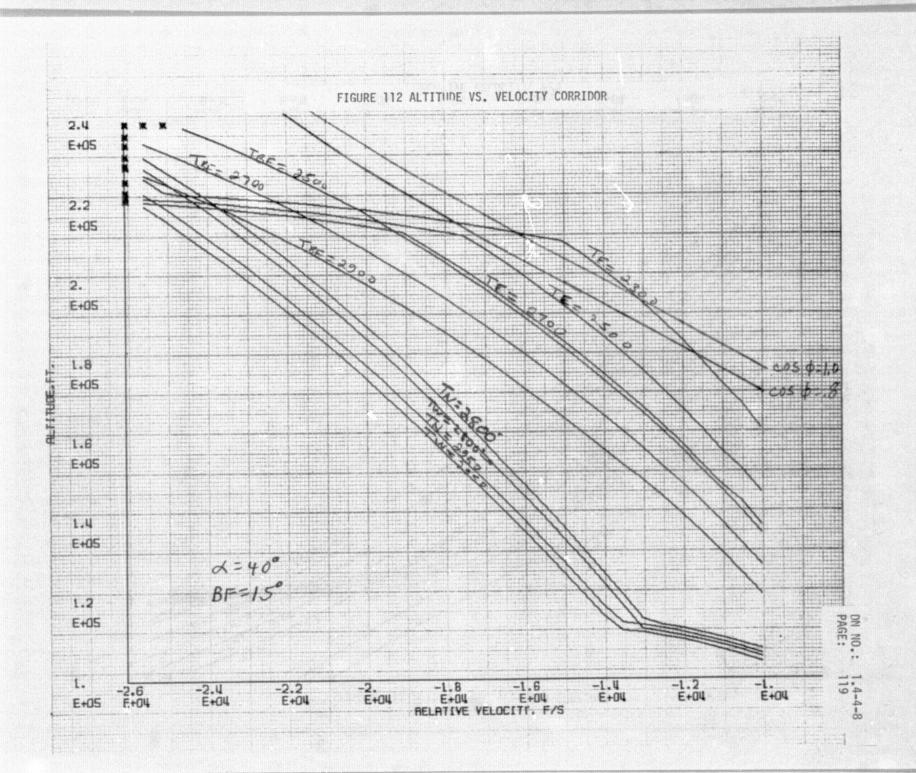


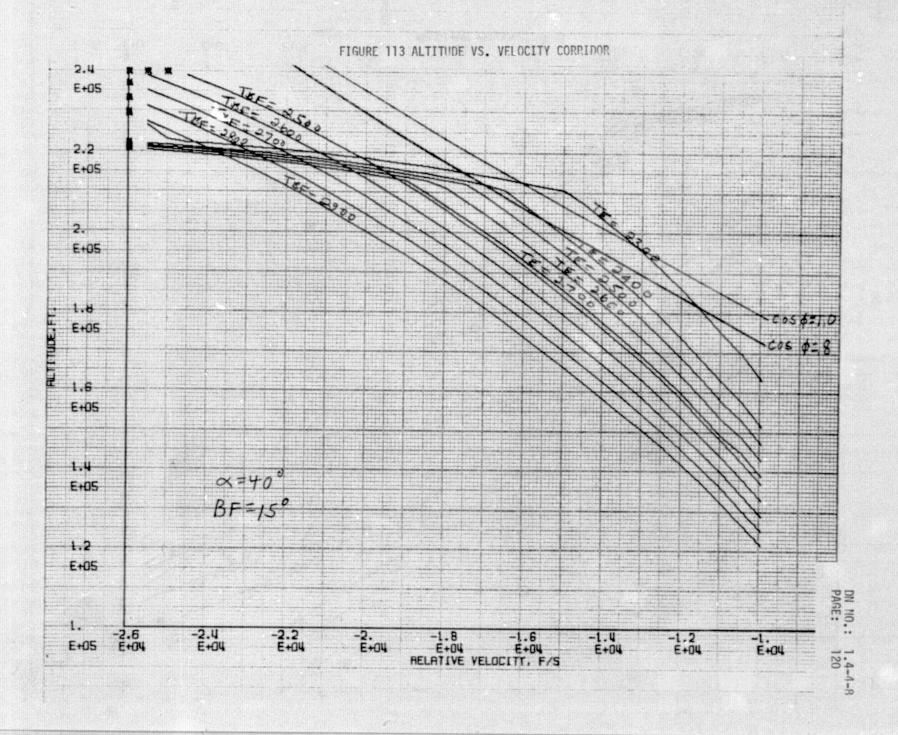


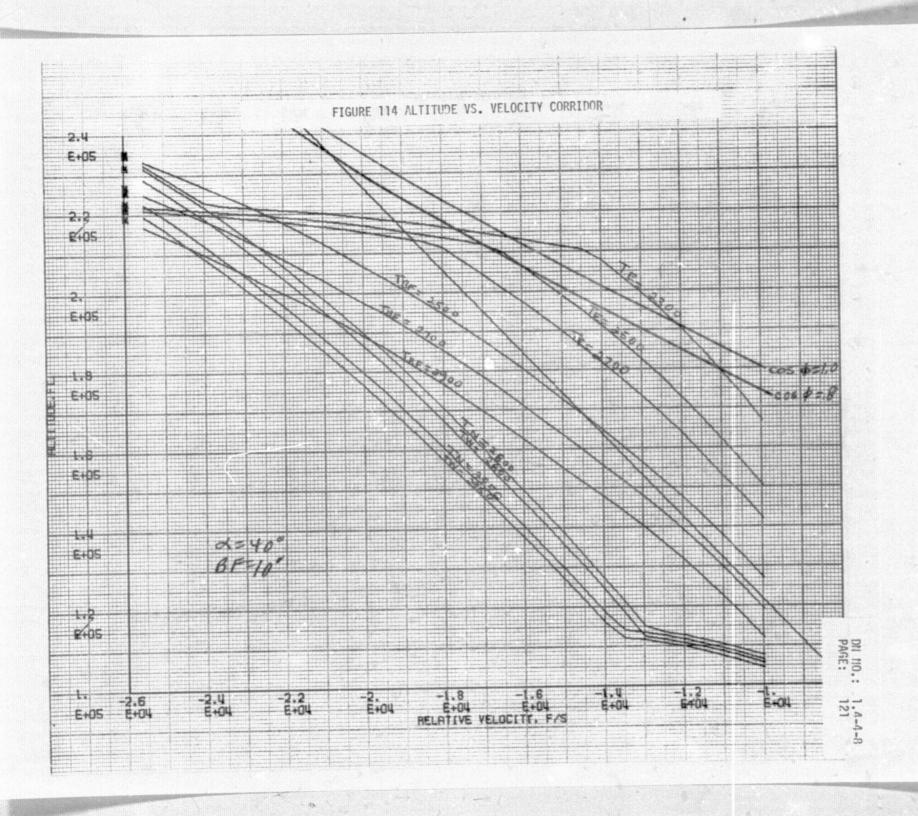


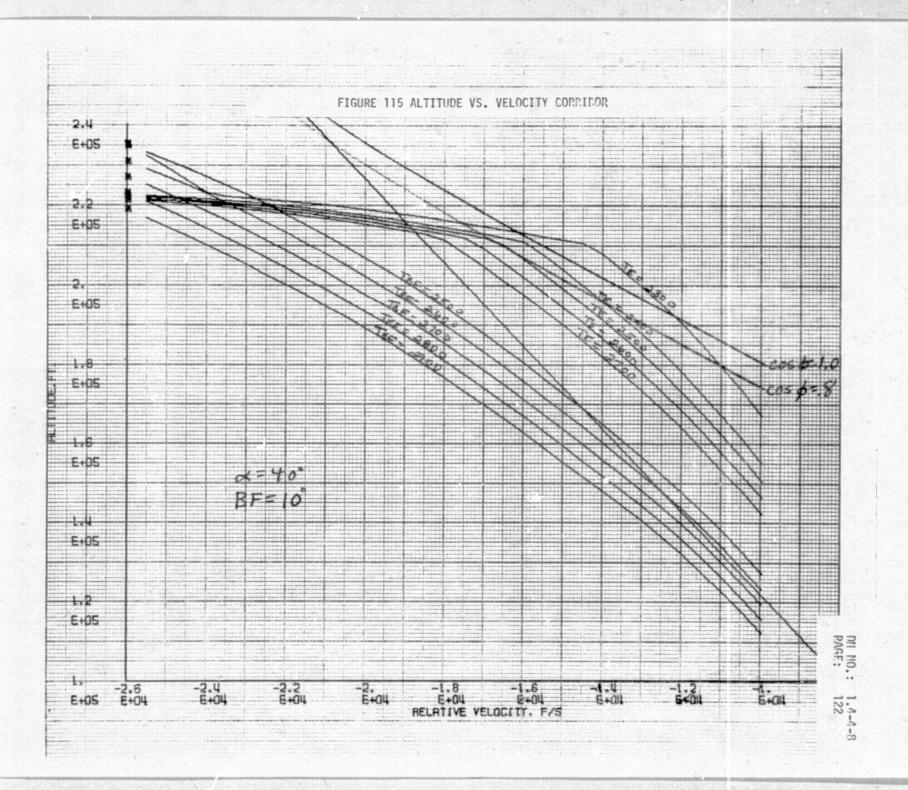


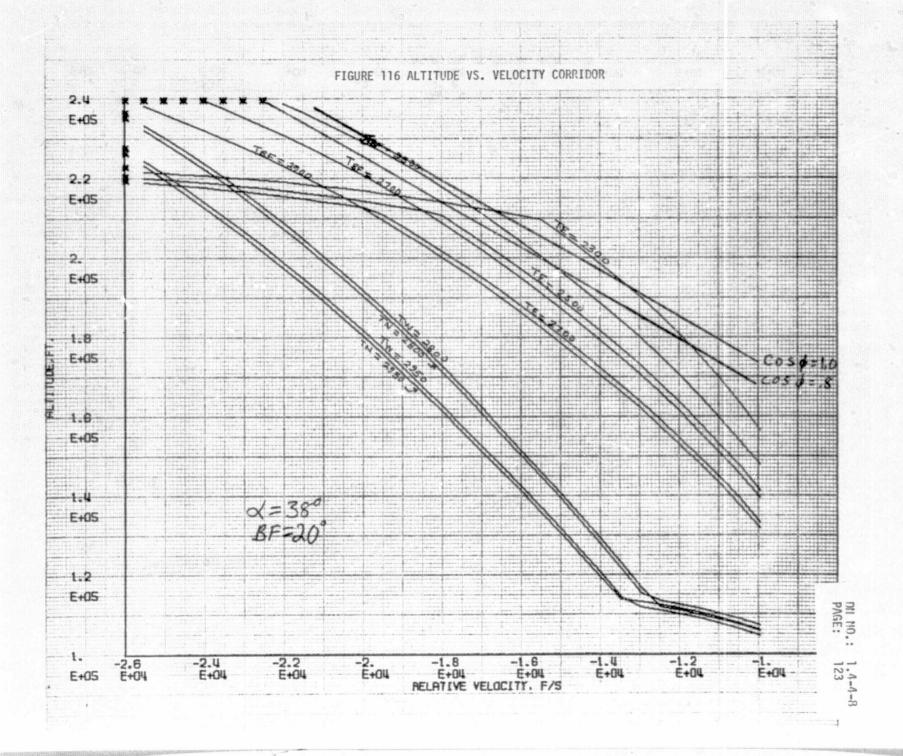


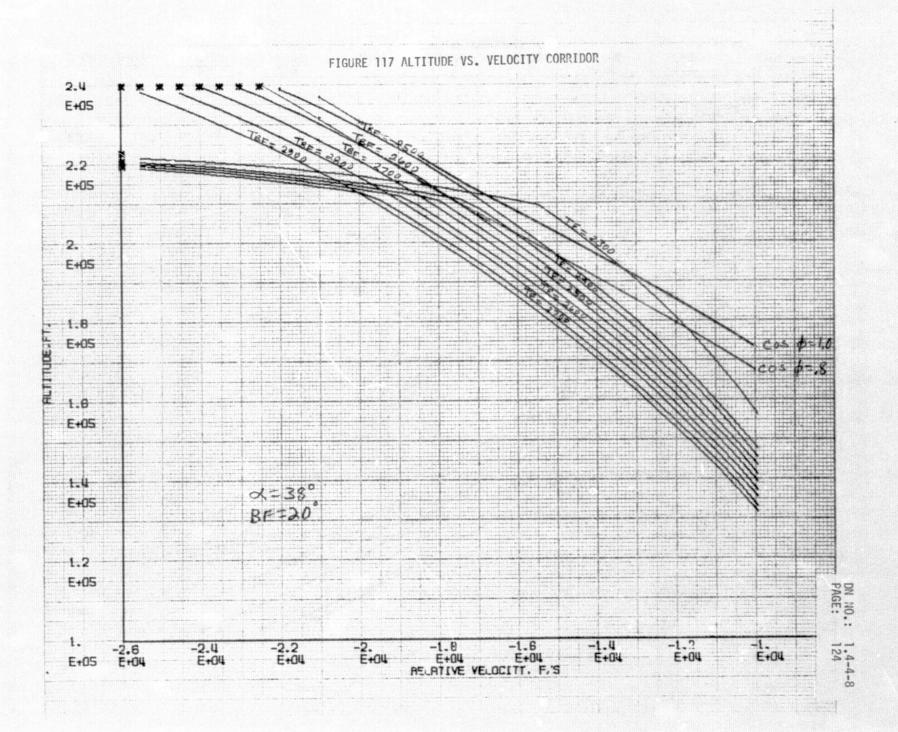












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